

Enhanced RTC With NVRAM Control

Features

- ➤ Direct clock/calendar replacement for IBM[®] AT-compatible computers and other applications
- ➤ 114 bytes of general nonvolatile storage
- ➤ Enhanced features include:
 - System wake-up capability alarm interrupt output active in battery-backup mode
 - 2.7–3.6V operation (bq4285L);
 4.5–5.5V operation (bq4285E)
 - 32kHz output for power management
- Automatic backup and writeprotect control to external SRAM
- ➤ Functionally compatible with the DS1285
- ➤ Less than 0.5 µA load under battery operation

➤ 14 bytes for clock/calendar and

- ➤ BCD or binary format for clock and calendar data
- ➤ Calendar in day of the week, day of the month, months, and years, with automatic leap-year adjustment.
- ➤ Time of day in seconds, minutes, and hours
 - 12- or 24-hour format
 - Optional daylight saving adjustment
- ➤ Programmable square wave output
- ➤ Three individually maskable interrupt event flags:
 - Periodic rates from 122µs to 500ms
 - Time-of-day alarm once per second to once per day
 - End-of-clock update cycle
- ➤ 24-pin plastic DIP or SOIC

General Description

The CMOS bq4285E/L is a low-power microprocessor peripheral providing a time-of-day clock and 100-year calendar with alarm features and battery operation. Other features include three maskable interrupt sources, square wave output, and 114 bytes of general nonvolatile storage.

A 32.768kHz output is available for sustaining power-management activities. Wake-up capability is provided by an alarm interrupt, which is active in battery-backup mode.

The bq4285E/L write-protects the clock, calendar, and storage registers during power failure. A backup battery then maintains data and operates the clock and calendar.

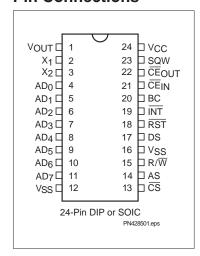
The bq4285E/L is a fully compatible real-time clock for IBM AT-compatible computers and other applications. The only external components are a 32.768kHz crystal and a backup battery.

The bq4285E/L integrates a battery-backup controller to make a

Pin Names

Pin Connections

control



28-Pin PLCC: No Longer Available

AD₀-AD₇ Multiplexed address/data input/output MOT Bus type select input CS Chip select input Address strobe input AS DS Data strobe input R/\overline{W} Read/write input ĪNT Interrupt request output RST Reset input SOW Square wave output BC 3V backup cell input X1-X2 Crystal inputs NC No connect \overline{CE}_{IN} RAM chip enable input **CEOUT** RAM chip enable output

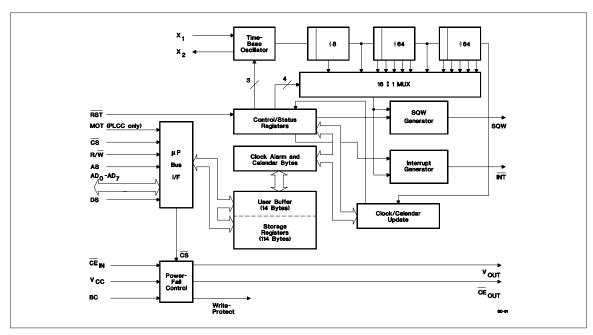
Supply output

+5V supply

 V_{OUT} V_{CC}

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Block Diagram



standard CMOS SRAM nonvolatile during power-fail conditions. During power-fail, the bq4285E/L automatically write-protects the external SRAM and provides a $V_{\rm CC}$ output sourced from the clock backup battery.

Pin Descriptions

AD₀-AD₇ Multiplexed address/data input/output

The bq4285E/L bus cycle consists of two phases: the address phase and the data-transfer phase. The address phase precedes the data-transfer phase. During the address phase, an address placed on AD_0-AD_7 is latched into the bq4285E/L on the falling edge of the AS signal. During the data-transfer phase of the bus cycle, the AD_0-AD_7 pins serve as a bidirectional data bus.

MOT

Connect to VSS for normal operation

The setting should not be changed during system operation. MOT is internally pulled low by a $20 \mathrm{K}\Omega$ resistor. For the DIP and SOIC packages, this pin is internally connected to Vss, enabling the bus timing for the Intel architecture.

$\overline{\mathbf{CS}}$ Chip select input

 $\overline{\text{CS}}$ should be driven low and held stable during the data-transfer phase of a bus cycle accessing the bq4285E/L.

Table 1. Bus Setup

Bus Type	MOT Level	DS Equivalent	R/W Equivalent	AS Equivalent
			_	
Intel	$V_{\rm SS}$	$\overline{\frac{\text{RD},}{\text{MEMR}}}$, or $\overline{\text{I/OR}}$	$\frac{\overline{WR},}{\overline{MEMW}}$, or $\overline{I/OW}$	ALE

\mathbf{AS} Address strobe input

AS serves to demultiplex the address/data bus. The falling edge of AS latches the address on AD₀-AD₇. This demultiplexing process is independent of the $\overline{\text{CS}}$ signal.

SQW

Square-wave output

SQW may output a programmable frequency square-wave signal during normal (V_{CC} valid) system operation. Any one of the 13 specific frequencies may be selected through register A. This pin is held low when the square-wave enable bit (SQWE) in register B is 0 (see the Control/Status Registers section).

Reset may be disabled by connecting RST to

Vcc. This allows the control bits to retain their states through power-down/power-up cycles.

A 32.768kHz output is enabled by setting the SQWE bit in register B to 1 and the 32KE bit in register C to 1 after setting OSC2-OSC0 in register A to 011 (binary).

\mathbf{DS} Data strobe input

With MOT = VSS, the DS input is provided a signal similar to \overline{RD} , \overline{MEMR} , or $\overline{I/OR}$ in an Intel-based system. The falling edge on DS is used to enable the outputs during a read cycle.

BC

3V backup cell input

BC should be connected to a 3V backup cell for RTC operation and storage register nonvolatility in the absence of power. When V_{CC} slews down past V_{BC} (3V typical), the integral control circuitry switches the power source to BC. When V_{CC} returns above V_{BC}, the power source is switched to V_{CC} .

Upon power-up, a voltage within the V_{BC} range must be present on the BC pin for the oscillator to start up.

R/\overline{W} Read/write input

With MOT = VSS, R/W is provided a signal similar to WR, MEMW, or I/OW in an Intelbased system. The rising edge on R/\overline{W} latches data into the bq4285E/L.

X1-X2

Crystal inputs

The X1-X2 inputs are provided for an external 32.768Khz quartz crystal, Daiwa DT-26 or equivalent, with 6pF load capacitance. A trimming capacitor may be necessary for extremely precise time-base generation.

\overline{INT} Interrupt request output

INT is an open-drain output. This allows INT to be valid in battery-backup mode for the alarm interrupt. To use this feature, INT must be connected to a power supply other than V_{CC}. INT is asserted low when any event flag is set and the corresponding event enable bit is also set. INT becomes high-impedance whenever register C is read (see the Control/Status Registers section).

\overline{CE}_{IN}

External RAM chip enable input, active low

CEIN should be driven low to enable the controlled external RAM. CEIN is internally pulled up with a $50\text{K}\Omega$ resistor.

$\overline{\text{RST}}$ Reset input

The bg4285E/L is reset when \overline{RST} is pulled low. When reset, INT becomes highimpedance, and the bq4285E/L is not accessible. Table 4 in the Control/Status Registers section lists the register bits that are cleared by a reset.

CEOUT

External RAM chip enable output, active low

When power is valid, $\overline{\text{CE}}_{\text{OUT}}$ reflects $\overline{\text{CE}}_{\text{IN}}$.

Supply output Vout

V_{OUT} provides the higher of V_{CC} or V_{BC}, switched internally, to supply external RAM.

$\mathbf{v}_{\mathbf{c}\mathbf{c}}$ Positive power supply

 $\mathbf{v_{ss}}$ Ground

3

Functional Description Address Map

The bq4285E/L provides 14 bytes of clock and control/status registers and 114 bytes of general nonvolatile storage. Figure 1 illustrates the address map for the bq4285L.

Update Period

The update period for the bq4285E/L is one second. The bq4285E/L updates the contents of the clock and calendar locations during the update cycle at the end of each

update period (see Figure 2). The alarm flag bit may also be set during the update cycle.

The bq4285E/L copies the local register updates into the user buffer accessed by the host processor. When a 1 is written to the update transfer inhibit bit (UTI) in register B, the user copy of the clock and calendar bytes remains unchanged, while the local copy of the same bytes continues to be updated every second.

The update-in-progress bit (UIP) in register A is set t_{BUC} time before the beginning of an update cycle (see Figure 2). This bit is cleared and the update-complete flag (UF) is set at the end of the update cycle.

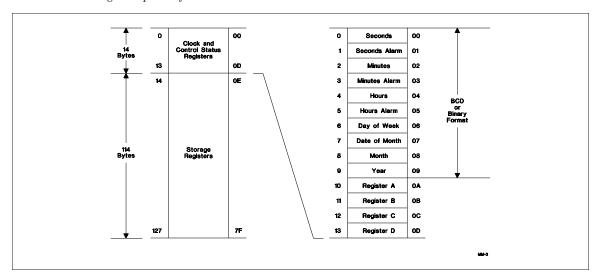


Figure 1. Address Map

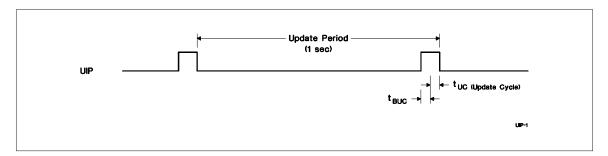


Figure 2. Update Period Timing and UIP

Programming the RTC

The time-of-day, alarm, and calendar bytes can be written in either the BCD or binary format (see Table 2).

These steps may be followed to program the time, alarm, and calendar:

- 1. Modify the contents of register B:
 - Write a 1 to the UTI bit to prevent transfers between RTC bytes and user buffer.
 - Write the appropriate value to the data format (DF) bit to select BCD or binary format for all time, alarm, and calendar bytes.
 - c. Write the appropriate value to the hour format (HF) bit.

- Write new values to all the time, alarm, and calendar locations.
- 3. Clear the UTI bit to allow update transfers.

On the next update cycle, the RTC updates all 10 bytes in the selected format.

Square-Wave Output

The bq4285E/L divides the 32.768kHz oscillator frequency to produce the 1 Hz update frequency for the clock and calendar. Thirteen taps from the frequency divider are fed to a 16:1 multiplexer circuit. The output of this mux is fed to the SQW output and periodic interrupt generation circuitry. The four least-significant bits of register A, RS0–RS3, select among the 13 taps (see Table 3). The square-wave output is enabled by writing a 1 to the square-wave enable bit (SQWE) in register B. A 32.768kHz output may be selected by setting OSC2–OSC0 in register A to 011 while SQWE = 1 and 32KE = 1.

Table 2. Time, Alarm, and Calendar Formats

			Range	
Address	RTC Bytes	Decimal	Binary	Binary-Coded Decimal
0	Seconds	0–59	00H-3BH	00H–59H
1	Seconds alarm	0–59	00H-3BH	00H–59H
2	Minutes	0–59	00H-3BH	00H–59H
3	Minutes alarm	0–59	00H-3BH	00H-59H
4	Hours, 12-hour format	1–12	01H–OCH AM; 81H–8CH PM	01H–12H AM; 81H–92H PM
	Hours, 24-hour format	0–23	00H-17H	00H-23H
5	Hours alarm, 12-hour format	1–12	01H–OCH AM; 81H–8CH PM	01H–12H AM; 81H–92H PM
	Hours alarm, 24-hour format	0–23	00H-17H	00H-23H
6	Day of week (1=Sunday)	1–7	01H-07H	01H-07H
7	Day of month	1–31	01H-1FH	01H-31H
8	Month	1–12	01H-0CH	01H-12H
9	Year	0–99	00H-63H	00H-99H

bq4285E/L

Interrupts

The bq4285E/L allows three individually selected interrupt events to generate an interrupt request. These three interrupt events are:

- \blacksquare The periodic interrupt, programmable to occur once every $122\,\mu s$ to 500 ms.
- The alarm interrupt, programmable to occur once per second to once per day, is active in battery-backup mode, providing a "wake-up" feature.
- The update-ended interrupt, which occurs at the end of each update cycle.

Each of the three interrupt events is enabled by an individual interrupt-enable bit in register B. When an event occurs, its event flag bit in register C is set. If the corresponding event enable bit is also set, then an interrupt request is generated. The interrupt request flag bit (INTF) of register C is set with every interrupt request. Reading register C clears all flag bits, including INTF, and makes INT high-impedance.

Two methods can be used to process bq4285E/L interrupt events:

- Enable interrupt events and use the interrupt request output to invoke an interrupt service routine.
- Do not enable the interrupts and use a polling routine to periodically check the status of the flag bits.

The individual interrupt sources are described in detail in the following sections.

Periodic Interrupt

The mux output used to drive the SQW output also drives the interrupt-generation circuitry. If the periodic interrupt event is enabled by writing a 1 to the periodic interrupt enable bit (PIE) in register C, an interrupt request is generated once every $122\mu s$ to 500ms. The period between interrupts is selected by the same bits in register A that select the square wave frequency (see Table 3). Setting OSC2–OSC0 in register A to 011 does not affect the periodic interrupt timing.

Table 3. Square-Wave Frequency/Periodic Interrupt Rate

		Reg	gister A E	Bits			Square	e Wave	Periodic I	nterrupt
OSC2	OSC1	OSC0	RS3	RS2	RS1	RS0	Frequency	Units	Period	Units
0	1	0	0	0	0	0	None		None	
0	1	0	0	0	0	1	256	Hz	3.90625	ms
0	1	0	0	0	1	0	128	$_{ m Hz}$	7.8125	ms
0	1	0	0	0	1	1	8.192	kHz	122.070	μs
0	1	0	0	1	0	0	4.096	kHz	244.141	μs
0	1	0	0	1	0	1	2.048	kHz	488.281	μs
0	1	0	0	1	1	0	1.024	kHz	976.5625	μs
0	1	0	0	1	1	1	512	Hz	1.95315	ms
0	1	0	1	0	0	0	256	Hz	3.90625	ms
0	1	0	1	0	0	1	128	Hz	7.8125	ms
0	1	0	1	0	1	0	64	Hz	15.625	ms
0	1	0	1	0	1	1	32	Hz	31.25	ms
0	1	0	1	1	0	0	16	Hz	62.5	ms
0	1	0	1	1	0	1	8	Hz	125	ms
0	1	0	1	1	1	0	4	Hz	250	ms
0	1	0	1	1	1	1	2	Hz	500	ms
0	1	1	X	X	X	X	32.768	kHz	same as above defir by RS3–RS0	

Alarm Interrupt

The alarm interrupt request is valid in battery-backup mode, providing a "wake-up" capability. During each update cycle, the RTC compares the hours, minutes, and seconds bytes with the three corresponding alarm bytes. If a match of all bytes is found, the alarm interrupt event flag bit, AF in register C, is set to 1. If the alarm event is enabled, an interrupt request is generated.

An alarm byte may be removed from the comparison by setting it to a "don't care" state. An alarm byte is set to a "don't care" state by writing a 1 to each of its two most-significant bits. A "don't care" state may be used to select the frequency of alarm interrupt events as follows:

- If none of the three alarm bytes is "don't care," the frequency is once per day, when hours, minutes, and seconds match.
- If only the hour alarm byte is "don't care," the frequency is once per hour, when minutes and seconds match.
- If only the hour and minute alarm bytes are "don't care," the frequency is once per minute, when seconds match.
- If the hour, minute, and second alarm bytes are "don't care," the frequency is once per second.

Update Cycle Interrupt

The update cycle ended flag bit (UF) in register C is set to a 1 at the end of an update cycle. If the update interrupt enable bit (UIE) of register B is 1, and the update transfer inhibit bit (UTI) in register B is 0, then an interrupt request is generated at the end of each update cycle.

Accessing RTC bytes

Time and calendar bytes read during an update cycle may be in error. Three methods to access the time and calendar bytes without ambiguity are:

- Enable the update interrupt event to generate interrupt requests at the end of the update cycle. The interrupt handler has a maximum of 999ms to access the clock bytes before the next update cycle begins (see Figure 3).
- Poll the update-in-progress bit (UIP) in register A. If UIP = 0, the polling routine has a minimum of t_{BUC} time to access the clock bytes (see Figure 3).
- Use the periodic interrupt event to generate interrupt requests every tpi time, such that UIP = 1 always occurs between the periodic interrupts. The interrupt handler will have a minimum of tpi/2 + tbuc time to access the clock bytes (see Figure 3).

Oscillator Control

When power is first applied to the bq4285E/L and $V_{\rm CC}$ is above $V_{\rm PFD}$, the internal oscillator and frequency divider are turned on by writing a 010 pattern to bits 4 through 6 of register A. A pattern of 011 behaves as 010 but additionally transforms register C into a read/write register. This allows the 32.768kHz output on the square wave pin to be turned on. A pattern of 11X turns the oscillator on, but keeps the frequency divider disabled. Any other pattern to these bits keeps the oscillator off.

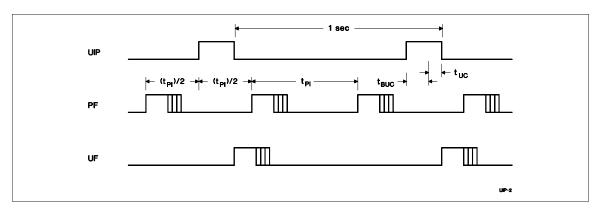


Figure 3. Update-Ended/Periodic Interrupt Relationship

Power-Down/Power-Up Cycle

The bq4285E/L power-up/power-down cycles are different. The bq4285L continuously monitors $V_{\rm CC}$ for out-of-tolerance. During a power failure, when $V_{\rm CC}$ falls below $V_{\rm PFD}$ (2.53V typical), the bq4285L write-protects the clock and storage registers. The power source is switched to BC when $V_{\rm CC}$ is less than $V_{\rm PFD}$ and BC is greater than $V_{\rm PFD}$, or when $V_{\rm CC}$ is less than $V_{\rm BC}$ and $V_{\rm BC}$ is less than $V_{\rm PFD}$. RTC operation and storage data are sustained by a valid backup energy source. When $V_{\rm CC}$ is above $V_{\rm PFD}$, the power source is $V_{\rm CC}$. Write-protection continues for $t_{\rm CSR}$ time after $V_{\rm CC}$ rises above $V_{\rm PFD}$.

The bq4285E continuously monitors V_{CC} for out-of-tolerance. During a power failure, when V_{CC} falls below V_{PFD} (4.17V typical), the bq4285E write-protects the clock and storage registers. When V_{CC} is below V_{BC} (3V typical), the power source is switched to BC. RTC operation and storage data are sustained by a valid backup energy source. When V_{CC} is above V_{BC} , the power source is V_{CC} . Write-protection continues for t_{CSR} time after V_{CC} rises above V_{PFD} .

An external CMOS static RAM is battery-backed using the V_{OUT} and chip enable output pins from the bq4285E/L. As the voltage input V_{CC} slows down during a power failure, the chip enable output, $\overline{CE}_{O\underline{UT}}$ is forced inactive independent of the chip enable input \overline{CE}_{IN}

This activity unconditionally write-protects the external SRAM as $V_{\rm CC}$ falls below $V_{\rm PFD}$. If a memory access is in process to the external SRAM during power-fail detection, that memory cycle continues to completion before the memory is write-protected. If the memory cycle is

not terminated within time twpT (30µs maximum), the chip enable output is unconditionally driven high, write-protecting the controlled SRAM.

As the supply continues to fall past V_{PFD} , an internal switching device forces V_{OUT} to the external backup energy source. CE_{OUT} is held high by the V_{OUT} energy source.

During power-up, V_{OUT} is switched back to the main supply as V_{CC} rises above the backup cell input voltage sourcing V_{OUT} . If $V_{PFD} < V_{BC}$ on the $\underline{bq4285L}$, the switch to the main supply occurs at V_{PFD} . \overline{CE}_{OUT} is held inactive for time t_{CER} (200ms maximum) after the power supply has reached V_{PFD} , independent of the \overline{CE}_{IN} input, to allow for processor stabilization.

During power-valid operation, the $\overline{\text{CE}}_{\text{IN}}$ input is passed through to the $\overline{\text{CE}}_{\text{OUT}}$ output with a propagation delay of less than 10ns.

Figure 4 shows the hardware hookup for the external RAM.

A primary backup energy source input is provided on the bq4285E/L. The BC input accepts a 3V primary battery, typically some type of lithium chemistry. To prevent battery drain when there is no valid data to retain, Vout and CEout are internally isolated from BC by the initial connection of a battery. Following the first application of Vcc above VPFD, this isolation is broken, and the backup cell provides power to Vout and $\overline{\rm CE}_{\rm OUT}$ for the external SRAM.

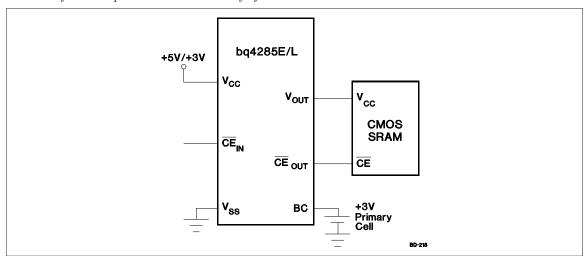


Figure 4. External RAM Hookup to the bq4285E/L RTC

Control/Status Registers

The four control/status registers of the bq4285E/L are accessible regardless of the status of the update cycle (see Table 4).

Register A

	Register A Bits										
7	6	5	4	3	2	1	0				
UIP	OS2	OS1	OS0	RS3	RS2	RS1	RS0				

Register A programs:

- The frequency of the square-wave and the periodic event rate.
- lacksquare Oscillator operation.

Register A provides:

Status of the update cycle.

RS0-RS3 - Frequency Select

7	6	5	4	3	2	1	0
-	-	-	-	RS3	RS2	RS1	RS0

These bits select one of the 13 frequencies for the SQW output and the periodic interrupt rate, as shown in Table 3.

OS0-OS2 - Oscillator Control

7	6	5	4	3	2	1	0
-	OS2	OS1	OS0	-	_	_	_

These three bits control the state of the oscillator and divider stages. A pattern of 010 enables RTC operation by turning on the oscillator and enabling the frequency di-

vider. A pattern of 011 behaves as 010 but additionally transforms register C into a read/write register. This allows the 32.768kHz output on the square wave pin to be turned on. A pattern of 11X turns the oscillator on, but keeps the frequency divider disabled. When 010 is written, the RTC begins its first update after 500ms.

UIP - Update Cycle Status

7	6	5	4	3	2	1	0
UIP	-	-	-	-	-	-	-

This read-only bit is set prior to the update cycle. When UIP equals 1, an RTC update cycle may be in progress. UIP is cleared at the end of each update cycle. This bit is also cleared when the update transfer inhibit (UTI) bit in register B is 1.

Register B

Register B Bits										
7	6	5	4	3	2	1	0			
UTI	PIE	AIE	UIE	SQWE	DF	HF	DSE			

Register B enables:

- Update cycle transfer operation
- Square-wave output
- Interrupt events
- Daylight saving adjustment

Register B selects:

■ Clock and calendar data formats

All bits of register B are read/write.

Table 4. Control/Status Registers

	1.00				Bit Name and State on Reset														
Reg.	Loc. (Hex)	Read	Write	7 (M	SB)	6	6		5	4	ļ	3		2	2	1		0 (LS	SB)
A	0A	Yes	Yes^1	UIP	na	OS2	na	OS1	na	OS0	na	RS3	na	RS2	na	RS1	na	RS0	na
В	0B	Yes	Yes	UTI	na	PIE	0	AIE	0	UIE	0	SQWE	0	DF	na	HF	na	DSE	na
C	0C	Yes	No^2	INTF	0	PF	0	AF	0	UF	0	-	0	32KE	na	-	0	-	0
D	0D	Yes	No	VRT	na	-	0	-	0	-	0	-	0	-	0	-	0	-	0

Notes:

na = not affected.

- 1. Except bit 7.
- 2. Read/write only when OSC2-OSC0 in register A is 011 (binary).

bq4285E/L

DSE - Daylight Saving Enable

7	6	5	4	3	2	1	0
-	-	-	-	-	-	-	DSE

This bit enables daylight-saving time adjustments when written to 1:

- On the last Sunday in October, the first time the bq4285E/L increments past 1:59:59 AM, the time falls back to 1:00:00 AM.
- On the first Sunday in April, the time springs forward from 2:00:00 AM to 3:00:00 AM.

7	6	5	4	3	2	1	0
-	-	-	-	-	-	HF	-

HF - Hour Format

This bit selects the time-of-day and alarm hour format:

1 = 24-hour format

0 = 12-hour format

7	6	5	4	3	2	1	0
-	-	-	-	-	DF	-	-

DF - Data Format

This bit selects the numeric format in which the time, alarm, and calendar bytes are represented:

1 = Binary

0 = BCD

7	6	5	4	3	2	1	0
-	-	-	-	SQWE	-	-	-

SQWE - Square-Wave Enable

This bit enables the square-wave output:

1 = Enabled

0 = Disabled and held low

UIE - Update Cycle Interrupt Enable

7	6	5	4	3	2	1	0
-	-	-	UIE	-	-	_	-

This bit enables an interrupt request due to an update ended interrupt event:

1 = Enabled

0 = Disabled

The UIE bit is automatically cleared when the UTI bit equals 1.

AIE - Alarm Interrupt Enable

7	6	5	4	3	2	1	0
-	-	AIE	-	-	-	-	-

This bit enables an interrupt request due to an alarm interrupt event:

1 = Enabled

0 = Disabled

PIE - Periodic Interrupt Enable

7	6	5	4	3	2	1	0
_	PIE	_	_	-	_	-	_

This bit enables an interrupt request due to a periodic interrupt event:

1 = Enabled

0 = Disabled

UTI - Update Transfer Inhibit

7	6	5	4	3	2	1	0
UTI	-	-	-	-	-	-	-

This bit inhibits the transfer of RTC bytes to the user buffer:

1 = Inhibits transfer and clears UIE

0 = Allows transfer

Register C

			Registe	er C Bits	\$		
7	6	5	4	3	2	1	0
INTF	PF	AF	UF	0	32KE	0	0

Register C is the read-only event status register.

Bits 0-3 - Unused Bits

7	6	5	4	3	2	1	0
-	-	-	-	0	-	0	0

These bits are always set to 0.

32KE-32KHz Enable Output

7	6	5	4	3	2	1	0
-	-	-	_	-	32KE	_	_

This bit may be set to a 1 only when the OSC2–OSC0 bits in register A are set to 011. Setting OSC2–OSC0 to anything other than 011 clears this bit. If SQWE in register B and 32KE are set, a $32.768 \mathrm{KHz}$ waveform is output on the square wave pin.

UF - Update-Event Flag

7	6	5	4	3	2	1	0
-	1	-	UF	-	-	-	-

This bit is set to a 1 at the end of the update cycle. Reading register C clears this bit.

AF - Alarm Event Flag

	7	6	5	4	3	2	1	0
ĺ	-	-	AF	-	-	-	-	-

This bit is set to a 1 when an alarm event occurs. Reading register C clears this bit.

PF - Periodic Event Flag

7	6	5	4	3	2	1	0
-	$_{\mathrm{PF}}$	-	-	-	-	_	-

This bit is set to a 1 every t_{PI} time, where t_{PI} is the time period selected by the settings of RS0–RS3 in register A. Reading register C clears this bit.

INTF - Interrupt Request Flag

7	6	5	4	3	2	1	0
INTF	-	-	-	-	-	-	-

This flag is set to a 1 when any of the following is true:

AIE = 1 and AF = 1

PIE = 1 and PF = 1

UIE = 1 and UF = 1

Reading register C clears this bit.

Register D

Register D Bits							
7	6	5	4	3	2	1	0
VRT	0	0	0	0	0	0	0

Register D is the read-only data integrity status register.

Bits 0-6 - Unused Bits

7	6	5	4	3	2	1	0
-	0	0	0	0	0	0	0

These bits are always set to 0.

VRT - Valid RAM and Time

7	6	5	4	3	2	1	0
_ •	0	- 0	-	0			-
VRT	_	_	_	_	_	_	_

1 = Valid backup energy source

0 = Backup energy source is depleted

When the backup energy source is depleted (VRT = 0), data integrity of the RTC and storage registers is not guaranteed.

Absolute Maximum Ratings—bq4285E

Symbol	Parameter	Value	Unit	Conditions
$V_{\rm CC}$	DC voltage applied on $V_{\rm CC}$ relative to $V_{\rm SS}$	-0.3 to 7.0	V	
V_{T}	DC voltage applied on any pin excluding V_{CC} relative to $V_{\rm SS}$	-0.3 to 7.0	V	$V_T \le V_{CC} + 0.3$
m.		0 to +70	$^{\circ}\mathrm{C}$	Commercial
T_{OPR}	Operating temperature	-40 to +85	$^{\circ}\mathrm{C}$	Industrial "N"
T_{STG}	Storage temperature	-55 to +125	$^{\circ}\mathrm{C}$	
T _{BIAS}	Temperature under bias	-40 to +85	$^{\circ}\mathrm{C}$	
TSOLDER	Soldering temperature	260	$^{\circ}\mathrm{C}$	For 10 seconds

Note:

Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

Absolute Maximum Ratings—bq4285L

Symbol Parameter		Value	Unit	Conditions
$V_{\rm CC}$	DC voltage applied on $V_{\rm CC}$ relative to $V_{\rm SS}$	-0.3 to 6.0	V	
V_{T}	DC voltage applied on any pin excluding $V_{\rm CC}$ relative to $V_{\rm SS}$		V	$V_T \le V_{CC} + 0.3$
T_{OPR}	Operating temperature	0 to +70	°C	Commercial
T _{STG}	Storage temperature	-55 to +125	°C	
$T_{ m BIAS}$	Temperature under bias	-40 to +85	$^{\circ}\mathrm{C}$	
TSOLDER	Soldering temperature	260	°C	For 10 seconds

Note:

Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

Recommended DC Operating Conditions—bq4285E (TA = TOPR)

Symbol	Parameter	Minimum	Typical	Maximum	Unit
$V_{\rm CC}$	Supply voltage	4.5	5.0	5.5	V
V_{IL}	Input low voltage	-0.3	-	0.8	v
V_{IH}	Input high voltage	2.2	-	$V_{\rm CC}$ + 0.3	v
V_{BC}	Backup cell voltage	2.5	-	4.0	V

Notes:

Typical values indicate operation at T_A = 25°C.

Potentials are relative to $V_{\rm SS}$.

Recommended DC Operating Conditions—bq4285L (TA = TOPR)

Symbol	Parameter	Minimum	Typical	Maximum	Unit
$V_{\rm CC}$	Supply voltage	2.7	3.15	3.6	V
$V_{ m IL}$	Input low voltage	-0.3	-	0.6	V
V_{IH}	Input high voltage	2.2	-	$V_{\rm CC}$ + 0.3	V
V_{BC}	Backup cell voltage	2.4	-	4.0	V

Notes:

Typical values indicate operation at T_A = 25°C.

Potentials are relative to V_{SS}.

Crystal Specifications—bq4285E/L (DT-26 or Equivalent)

Symbol	Parameter	Minimum	Typical	Maximum	Unit
$f_{\rm O}$	Oscillation frequency	-	32.768	-	kHz
$\mathrm{C_L}$	Load capacitance	-	6	-	pF
T_{P}	Temperature turnover point	20	25	30	°C
k	Parabolic curvature constant	-	-	-0.042	ppm/°C
Q	Quality factor	40,000	70,000	-	
R_1	Series resistance	-	-	45	ΚΩ
C_0	Shunt capacitance	-	1.1	1.8	pF
C ₀ /C ₁	Capacitance ratio	-	430	600	
$\mathrm{D_{L}}$	Drive level	-	-	1	μW
$\Delta f/f_{\mathrm{O}}$	Aging (first year at 25°C)	-	1	-	ppm

DC Electrical Characteristics—bq4285E (TA = T_{OPR} , V_{CC} = 5V \pm 10%)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions/Notes
I_{LI}	Input leakage current	-	-	± 1	μΑ	$V_{\rm IN}$ = $V_{\rm SS}$ to $V_{\rm CC}$
$I_{ m LO}$	Output leakage current	-	-	± 1	μΑ	$ \begin{vmatrix} AD_0 - AD_7, \overline{INT}, \text{and SQW} \\ \text{in high impedance,} \\ V_{OUT} = V_{SS} \text{ to } V_{CC} \\ \end{vmatrix} $
V _{OH}	Output high voltage	2.4	-	-	V	I _{OH} = -2.0 mA
V_{OL}	Output low voltage	-	-	0.4	V	$I_{\rm OL}$ = 4.0 mA
$I_{\rm CC}$	Operating supply current	-	7	15	mA	$\begin{aligned} &\text{Min. cycle, duty = 100\%,} \\ &\text{I}_{\text{OH}} = 0\text{mA, I}_{\text{OL}} = 0\text{mA} \end{aligned}$
V_{SO}	Supply switch-over voltage	-	V_{BC}	-	V	
I _{CCB}	Battery operation current	-	0.3	0.5	μА	V_{BC} = 3V, T_A = 25°C, no load on V_{OUT} or \overline{CE}_{OUT}
I _{CCSB}	Standby supply current	-	300	-	μА	$\label{eq:VIN} \begin{split} \frac{V_{IN} = V_{CC} \text{ or } V_{SS}, \\ \overline{CS} \ge V_{CC} - 0.2, \\ \text{no load on } V_{OUT} \end{split}$
$ m V_{PFD}$	Power-fail-detect voltage	4.0	4.17	4.35	V	
V _{OUT1}	V _{OUT} voltage	V _{CC} - 0.3V	-	-	V	$I_{\rm OUT} = 100 { m mA}, V_{\rm CC} > V_{ m BC}$
V _{OUT2}	V _{OUT} voltage	V _{BC} - 0.3V				$I_{OUT} = 100 \mu A, V_{CC} < V_{BC}$
$I_{\overline{CE}}$	Chip enable input current	-	-	100	μΑ	Internal 50K pull-up

Note: Typical values indicate operation at T_A = 25°C, V_{CC} = 5V or V_{BC} = 3V.

DC Electrical Characteristics—bq4285L ($T_A = T_{OPR}$, $V_{CC} = 3.13V \pm 0.45\%$)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions/Notes
I_{LI}	Input leakage current	-	-	± 1	μΑ	$V_{\rm IN}$ = $V_{\rm SS}$ to $V_{\rm CC}$
${ m I_{LO}}$	Output leakage current	-	-	± 1	μА	$ \begin{vmatrix} AD_0 - AD_7, \overline{INT}, \text{and SQW} \\ \text{in high impedance,} \\ V_{OUT} = V_{SS} \text{ to } V_{CC} \\ \end{vmatrix} $
V _{OH}	Output high voltage	2.2	-	-	V	I_{OH} = -2.0 mA
V_{OL}	Output low voltage	-	-	0.4	V	$I_{OL} = 4.0 \text{ mA}$
I_{CC}	Operating supply current	-	5	9	mA	$\begin{aligned} &\text{Min. cycle, duty = 100\%,} \\ &\text{I}_{\text{OH}} = 0\text{mA, I}_{\text{OL}} = 0\text{mA} \end{aligned}$
77	Contract to the contract of th	-	V_{PFD}	-	V	$V_{\rm BC} > V_{\rm PFD}$
$ m V_{SO}$	Supply switch-over voltage	-	V_{BC}	-	V	$V_{\rm BC} < V_{\rm PFD}$
I _{CCB}	Battery operation current	-	0.3	0.5	μА	V_{BC} = 3V, T_A = 25°C, no load on V_{OUT} or \overline{CE}_{OUT}
I_{CCSB}	Standby supply current	-	100	-	μΑ	$\label{eq:Vin} \begin{split} & \frac{V_{IN}}{CS} = V_{CC} \text{ or } V_{SS}, \\ & \frac{CS}{CS} \geq V_{CC} - 0.2, \\ & \text{no load on } V_{OUT} \end{split}$
$ m V_{PFD}$	Power-fail-detect voltage	2.4	2.53	2.65	V	
V _{OUT1}	V _{OUT} voltage	V _{CC} - 0.3V	-	-	V	$I_{\rm OUT} = 80 {\rm mA}, V_{\rm CC} > V_{\rm BC}$
V _{OUT2}	$V_{ m OUT}$ voltage	V _{BC} - 0.3V				$I_{OUT} = 100 \mu A, V_{CC} < V_{BC}$
I _{CE}	Chip enable input current	-	-	120	μΑ	Internal 30K pull-up

Note: Typical values indicate operation at T_A = 25°C, V_{CC} = 3V.

Capacitance—bq4285E/L ($T_A = 25$ °C, F = 1MHz, $V_{CC} = 5.0$ V)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions
C _{I/O}	Input/output capacitance	-	-	7	pF	$V_{OUT} = 0V$
C_{IN}	Input capacitance	-	-	5	pF	$V_{\rm IN} = 0V$

Note: This parameter is sampled and not 100% tested. It does not include the X1 or X2 pin.

AC Test Conditions—bq4285E

Parameter	Test Conditions
Input pulse levels	0 to 3.0 V
Input rise and fall times	5 ns
Input and output timing reference levels	1.5 V (unless otherwise specified)
Output load (including scope and jig)	See Figures 5 and 6

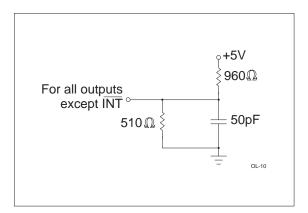


Figure 5. Output Load A—bq4285E

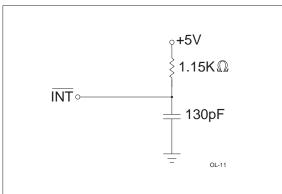
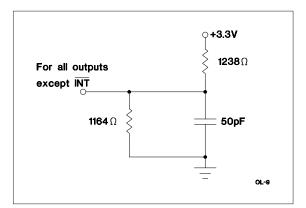


Figure 6. Output Load B—bq4285E

AC Test Conditions—bq4285L

Parameter	Test Conditions		
Input pulse levels	0 to 2.3 V		
Input rise and fall times	5 ns		
Input and output timing reference levels	1.2 V (unless otherwise specified)		
Output load (including scope and jig)	See Figures 7 and 8		



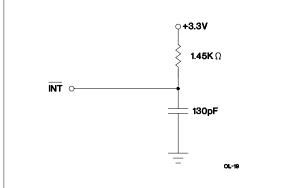


Figure 7. Output Load A—bq4285L

Figure 8. Output Load B—bq4285L

bq4285E/L

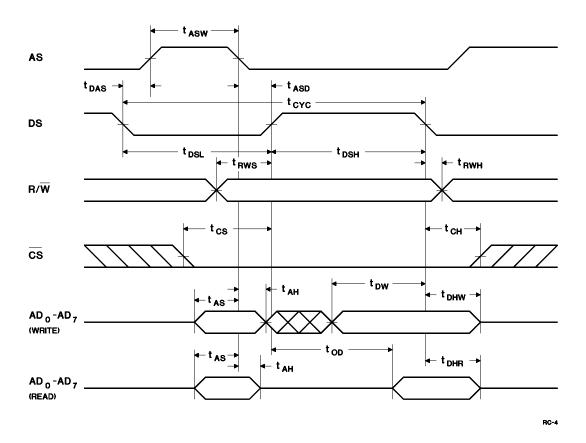
Read/Write Timing—bq4285E (TA = TOPR, VCC = 5V \pm 10%)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
$t_{\rm CYC}$	Cycle time	160	-	-	ns	
$t_{ m DSL}$	DS low or $\overline{RD}/\overline{WR}$ high time	80	-	-	ns	
$t_{ m DSH}$	DS high or $\overline{RD}/\overline{WR}$ low time	55	-	-	ns	
t_{RWH}	R/W hold time	0	-	-	ns	
$t_{ m RWS}$	R/W setup time	10	-	-	ns	
t_{CS}	Chip select setup time	5	-	-	ns	
t_{CH}	Chip select hold time	0	-	-	ns	
$t_{ m DHR}$	Read data hold time	0	-	25	ns	
$t_{ m DHW}$	Write data hold time	0	-	-	ns	
t_{AS}	Address setup time	20	-	-	ns	
$t_{ m AH}$	Address hold time	5	-	-	ns	
$t_{ m DAS}$	Delay time, DS to AS rise	10	-	-	ns	
tasw	Pulse width, AS high	30	-	-	ns	
$t_{ m ASD}$	Delay time, AS to DS rise (RD/WR fall)	35	-	-	ns	
t_{OD}	Output data delay time from DS rise (RD fall)	-	-	50	ns	
t_{DW}	Write data setup time	30	-	-	ns	
$t_{ m BUC}$	Delay time before update	-	244	-	μs	
$t_{ m PI}$	Periodic interrupt time interval	-	-	-	-	See Table 3
t_{UC}	Time of update cycle	-	1	-	μs	

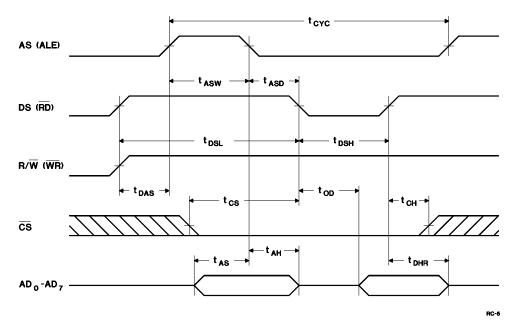
$\textbf{Read/Write Timing--bq4285L} \; (\texttt{TA} = \texttt{TOPR}, \texttt{VCC} = 3.15\texttt{V} \pm 0.45\%)$

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
$t_{\rm CYC}$	Cycle time	270	-	-	ns	
$t_{ m DSL}$	DS low or $\overline{RD}/\overline{WR}$ high time	135	-	-	ns	
$t_{ m DSH}$	DS high or $\overline{RD}/\overline{WR}$ low time	90	-	-	ns	
t_{RWH}	R/W hold time	0	-	-	ns	
$t_{ m RWS}$	R/W setup time	15	-	-	ns	
t_{CS}	Chip select setup time	8	-	-	ns	
t_{CH}	Chip select hold time	0	-	-	ns	
${ m t_{DHR}}$	Read data hold time	0	-	40	ns	
${ m t_{DHW}}$	Write data hold time	0	-	-	ns	
t_{AS}	Address setup time	30	-	-	ns	
t_{AH}	Address hold time	15	-	-	ns	
t_{DAS}	Delay time, DS to AS rise	15	-	-	ns	
tasw	Pulse width, AS high	50	-	-	ns	
$t_{ m ASD}$	Delay time, AS to DS rise (RD/WR fall)	55	-	-	ns	
t_{OD}	Output data delay time from DS rise $(\overline{RD} \text{ fall})$	-	-	100	ns	
t_{DW}	Write data setup time	50	-	-	ns	
$t_{ m BUC}$	Delay time before update	-	244	-	μs	
$t_{ m PI}$	Periodic interrupt time interval	-	-	-	-	See Table 3
tuc	Time of update cycle	-	1	-	μs	

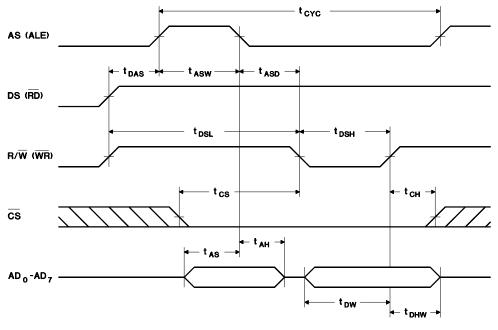
Motorola Bus Read/Write Timing—bq4285E/L (PLCC Package Only) Note: Package OBSOLETE



Intel Bus Read Timing—bq4285E/L



Intel Bus Write Timing—bq4285E/L



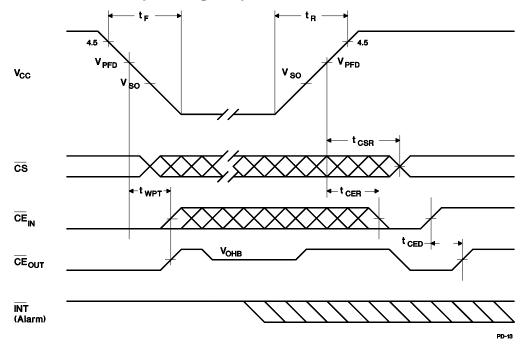
WC-6

Power-Down/Power-Up Timing—bq4285E (TA = TOPR)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions
t_{F}	V _{CC} slew from 4.5V to 0V	300	-	-	μs	
t_{R}	V _{CC} slew from 0V to 4.5V	100	-	-	μs	
tcsr	$\overline{\overline{\mathrm{CS}}}$ at V _{IH} after power-up	20	-	200	ms	
twpt	Write-protect time for external RAM	10	16	30	μs	Delay after $V_{\rm CC}$ slows down past $V_{\rm PFD}$ before SRAM is write-protected.
tcer	Chip enable recovery time	tcsr	-	t_{CSR}	ms	Time during which external SRAM is write-protected after V _{CC} passes V _{PFD} on power-up.
tced	Chip enable propagation delay to external SRAM	-	7	10	ns	

 $\label{lem:caution: Caution: Negative undershoots below the absolute maximum rating of -0.3V in battery-backup mode may affect data integrity.$

Power-Down/Power-Up Timing—bq4285E

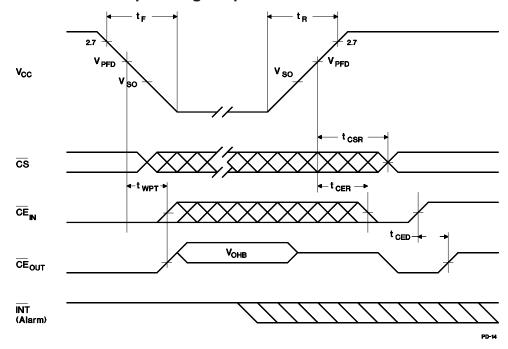


Power-Down/Power-Up Timing—bq4285L (TA = TOPR)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions
$t_{ m F}$	V _{CC} slew from 2.7V to 0V	300	-	-	μs	
$t_{ m R}$	V _{CC} slew from 0V to 2.7V	100	-	-	μs	
$t_{\rm CSR}$	$\overline{\mathrm{CS}}$ at V_{IH} after power-up	20	-	200	ms	$ \begin{array}{c} $
_	Write-protect time for ex-	-	0	-		$V_{\rm BC} > V_{ m PFD}$
twpT	ternal RAM	10	16	30	μs	$V_{\mathrm{BC}} < V_{\mathrm{PFD}}$
tcer	Chip enable recovery time	tcsr	-	$ m t_{CSR}$	ms	Time during which external SRAM is write-protected after V_{CC} passes V_{PFD} on power-up.
tced	Chip enable propagation delay to external SRAM	-	9	15	ns	

 $\label{lem:caution: Caution: Negative undershoots below the absolute maximum rating of -0.3V in battery-backup mode may affect data integrity.$

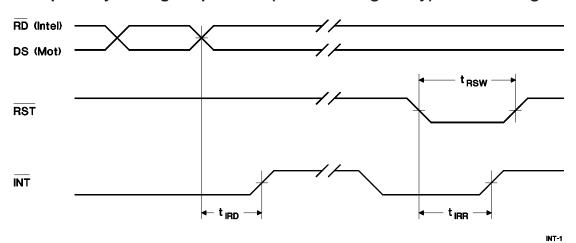
Power-Down/Power-Up Timing—bq4285L



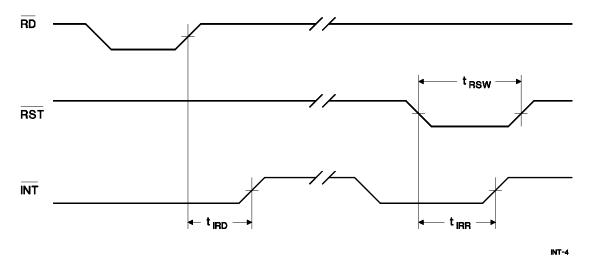
Interrupt Delay Timing—bq4285E/L (TA = TOPR)

Symbol	Parameter	Minimum	Typical	Maximum	Unit
t_{RSW}	Reset pulse width	5	-	-	μs
$t_{\rm IRR}$	$\overline{\text{INT}}$ release from $\overline{\text{RST}}$	-	-	2	μs
$t_{ m IRD}$	$\overline{\text{INT}}$ release from DS $(\overline{\text{RD}})$	-	-	2	μs

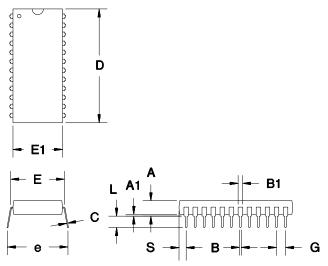
Interrupt Delay Timing—bq4285E/L (PLCC Package Only) Note: Package OBSOLETE



Interrupt Delay Timing—bq4285E/L



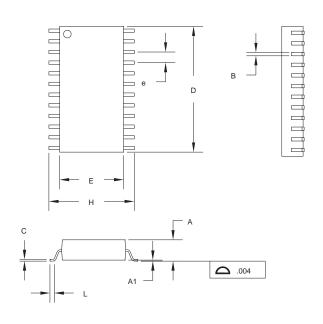
P: 24-Pin DIP (0.600")



24-Pin P (0.600" DIP)

	Inc	hes	Millimeters				
Dimension	Min.	Max.	Min.	Max.			
A	0.160	0.190	4.06	4.83			
A1	0.015	0.040	0.38	1.02			
В	0.015	0.022	0.38	0.56			
B1	0.045	0.065	1.14	1.65			
С	0.008	0.013	0.20	0.33			
D	1.240	1.280	31.50	32.51			
Е	0.600	0.625	15.24	15.88			
E1	0.530	0.570	13.46	14.48			
e	0.600	0.670	15.24	17.02			
G	0.090	0.110	2.29	2.79			
L	0.115	0.150	2.92	3.81			
S	0.070	0.090	1.78	2.29			

S: 24-Pin SOIC (0.300")



24-Pin S (0.300" SOIC)

	Inc	hes	Millimeters					
Dimension	Min. Max.		Min.	Max.				
A	0.095	0.105	2.41	2.67				
A1	0.004	0.012	0.10	0.30				
В	0.013	0.020	0.33	0.51				
C	0.008	0.013	0.20	0.33				
D	0.600	0.615	15.24	15.62				
E	0.290	0.305	7.37	7.75				
e	0.045	0.055	1.14	1.40				
Н	0.395	0.415	10.03	10.54				
L	0.020	0.040	0.51	1.02				

bq4285E/bq4285L

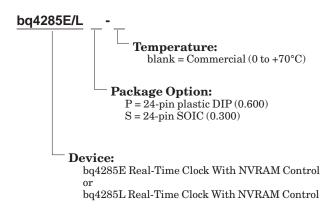
Data Sheet Revision History

Change No.	Page No.	Description	Nature of Change
1	1, 25	Package option change	Last time buy for PLCC
2	1, 2, 3, 14, 15, 20, 24, 26, 27	Package option removal	PLCC Last Time Buy Complete

Note:

Change 1 = Jan. 1999 B changes from May 1994. Change 2 = May 2004 (SLUS006A) changes from Jan. 1999 B

Ordering Information



*Contact factory for availability.





ti.com 9-Oct-2007

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing		ckage Qty	Eco Plan ⁽²⁾	Lead/Ball Finish	MSL Peak Temp ⁽³⁾
BQ4285EP	ACTIVE	PDIP	N	24	15	Pb-Free (RoHS)	A42 SN	N / A for Pkg Type
BQ4285LP	OBSOLETE	PDIP	N	24		TBD	Call TI	Call TI
BQ4285LS	OBSOLETE	SOIC	DW	24		TBD	Call TI	Call TI
BQ4285LSTR	OBSOLETE	SOIC	DW	24		TBD	Call TI	Call TI

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

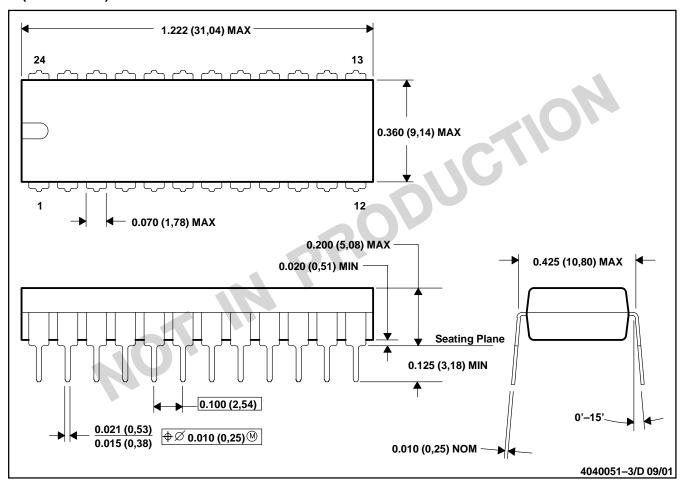
(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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N (R-PDIP-T24)

PLASTIC DUAL-IN-LINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-010

N (R-PDIP-T**)

PLASTIC DUAL-IN-LINE PACKAGE

24 PIN SHOWN



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-011
- D. Falls within JEDEC MS-015 (32 pin only)



DW (R-PDSO-G24)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters). Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013 variation AD.



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