

SNAS461C - MAY 2010 - REVISED APRIL 2013

# LM98640QML Dual Channel, 14-Bit, 40 MSPS Analog Front End with LVDS Output

## **FEATURES**

- Total Ionizing Dose 100 krad(Si)
- Single Event Latch-Up Free up to 120 MeVcm<sup>2</sup>/mg
- SEFI free up to 120 MeV-cm<sup>2</sup>/mg
- Seialized LVDS Outputs •
- **LVDS Input Clock**
- CDS or S/H Processing for CCD or CIS sensors
- **Programmable Analog Gain for Each Channel**
- **Programmable Analog Offset Correction**
- **Programmable Input Clamp Voltage**
- Programmable Sampling Edge up to 1/64th pixel period

## **KEY SPECIFICATIONS**

- Input Level 2.85 Volts
- **ADC Resolution 14-Bit**
- ADC Sampling Rate 5MSPS to 40 MSPS •
- INL at 15MHz ±3.5 LSB
- CDS or S/H Gain 0dB or 6dB
- PGA Gain Steps 256 Steps
- PGA Gain Range -3dB to 18dB
- Coarse DAC Resolution ±8 Bits
- Coarse DAC Range ±250mV
- Fine DAC Resolution ±8 Bits
- Fine DAC Range ±5mV
- Noise Floor -79dB
- Crosstalk -80dB
- **Power Consumption** 
  - PGA 1-4x Gain 125 mW per channel (15MSPS) 140 mW per channel (25MSPS)
  - PGA 1-8x Gain 125 mW per channel (15MSPS) 178 mW per channel (40MSPS)
  - Operating Temp -55 to 125°C
  - Supply Voltages 3.3V Nominal (3.15V to 3.45V range) 1.8V Nominal (1.7V to 1.9V range)

## **APPLICATIONS**

- **Focal Plane Electronics**
- Imaging Attitude Control Systems
- **Assembly Line Vision Systems** •
- **Factory Automation Vision Systems**
- **High-speed Document Scanner** •
- **Multi- Function Peripherals**

## DESCRIPTION

The LM98640QML is a fully integrated, high performance 14-Bit, 5 MSPS to 40 MSPS signal solution for image processing processing applications. The LM98640QML is Radiation tolerant up to a total ionizing dose of 100krads allowing it to be used in space imaging applications. Configuration Registers are Single Event Functional Interrupt Free up to 120 MeV-cm<sup>2</sup>/mg. The Serial LVDS Output format performs well during ionizing doses, preventing data loss. The LM98640QML has an adaptive power scaling feature to optimize power consumption based on the operating frequency and amount of gain required. High-speed signal throughput is achieved with an innovative architecture utilizing Correlated Double Sampling (CDS), typically employed with CCD arrays, or Sample and Hold (S/H) inputs (for Contact Image Sensors and CMOS image sensors). The sampling edges are programmable to a resolution of 1/64th of a pixel period. Both the CDS and S/H have a programmable gain of either 0dB or 6dB. The signal paths utilize two ±8 bit offset correction DACs for coarse and fine offset correction, and 8 bit Programmable Gain Amplifiers (PGA) for each channel. The PGA and offset DAC are programmed independently allowing unique values of gain and offset for each input. The signals are then routed to two on chip 14-bit 40MHz high performance analog-to-digital converters (ADC). The fully differential processing channel provides exceptional noise immunity, having a very low noise floor of -79dB with a gain of 1x. The 14-bit ADCs have excellent dynamic performance making the LM98640QML transparent in the image reproduction chain.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet. All trademarks are the property of their respective owners.



SNAS461C - MAY 2010 - REVISED APRIL 2013

## LM98640QML Overall Chip Block Diagram



Figure 1. Chip Block Diagram



SNAS461C - MAY 2010 - REVISED APRIL 2013

## LM98640QML Pin Out Diagram



Figure 2. LM98640QML Pin Out Diagram CFP Package See Package Number NBB0068D

System Block Diagram



Figure 3. TYPICAL CCD SYSTEM

TEXAS INSTRUMENTS

SNAS461C-MAY 2010-REVISED APRIL 2013

www.ti.com

## **Typical Application Diagram**



Figure 4. Typical Sample/Hold Mode Application Diagram

## LM98640QML-SP

www.ti.com

#### SNAS461C - MAY 2010 - REVISED APRIL 2013

	Pin Descriptions								
Pin	Name	I/O <sup>(1)</sup>	Тур	Res	Description				
1	VCOM1	0	А		Common mode of ADC reference. Bypass with 0.1µF capacitor to VSS33.				
2	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
3	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
4	VSS33		Р		Analog supply return.				
5	VSS33		Р		Analog supply return.				
6	OS1-	I	А		Analog input signal.				
7	OS1+	I	А		Sample/Hold Mode Reference Level. Bypassed with a 0.1µF to ground in CDS mode.				
8	VSS33		Р		Analog supply return.				
9	VCLP	0	А		Programmable Clamp Voltage output. Normally bypassed with a $0.1\mu\text{F}$ capacitor to VSS33.				
10	VSS33		Р		Analog supply return.				
11	OS2+	I	А		Sample/Hold Mode Reference Level. Bypassed with a 0.1µF to ground in CDS mode.				
12	OS2-	I	А		Analog input signal.				
13	VSS33		Р		Analog supply return.				
14	VSS33		Р		Analog supply return.				
15	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
16	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
17	VCOM2	0	А		Common mode of ADC reference. Bypass with 0.1µF capacitor to ground.				
18	VREFB2	0	А		Bottom of ADC reference. Bypass with a 0.1µF capacitor to ground.				
19	VREFT2	0	А		Top of ADC reference. Bypass with a 0.1µF capacitor to ground.				
20	VSS33		Р		Analog supply return.				
21	VSS33		Р		Analog supply return.				
22	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
23	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.				
24	VSS33		Р		Analog supply return.				
25	SDO	0	D		Serial Interface Data Output. (Tri-State when SEN is high)				
26	SDI	I	D		Serial Interface Data Input. (Tri-State when SEN is high)				
27	SCLK	I	D	PD	Serial Interface shift register clock. (Tri-State when SEN is high)				
28	SEN	I	D	PU	Active-low chip enable for the Serial Interface.				
29	NC				No Connection. Can be connected to VSS18.				
30	CLPIN	I	D		Input clamp signal.				
31	VSS18		Р		Digital supply return.				
32	VDD18		Р		Digital power supply. Decouple with minimum 0.1µF capacitor to VSS18 plane.				
33	DTM1	0	D		Digital Timing Monitor. If not used, can be connected to VDD18 through a $10k\Omega$ resistor.				
34	DTM0	0	D		Digital Timing Monitor. If not used, can be connected to VDD18 through a $10k\Omega$ resistor.				
35	VDD18		Р		Digital power supply. Decouple with minimum 0.1µF capacitor to VSS18 plane.				
36	VSS18		Р		Digital supply return.				
37	TXFRM+	0	D		LVDS Frame+				
38	TXFRM-	0	D		LVDS Frame-				
39	TXOUT3+	0	D		LVDS Data Out3+				
40	TXOUT3-	0	D		LVDS Data Out3-				
41	TXOUT2+	0	D		LVDS Data Out2+				
42	TXOUT2-	0	D		LVDS Data Out2-				
43	TXOUT1+	0	D		LVDS Data Out1+				
44	TXOUT1-	0	D		LVDS Data Out1-				
45	TXOUT0+	0	D		LVDS Data Out0+				

(1) (I=Input), (O=Output), (IO=Bi-directional), (P=Power), (D=Digital), (A=Analog), (PU=Pull Up with an internal resistor), (PD=Pull Down with an internal resistor.).

ISTRUMENTS

ÈXAS

www.ti.com

## Pin Descriptions (continued)

Pin	Name	I/O <sup>(1)</sup>	Тур	Res	Description
46	TXOUT0-	0	D		LVDS Data Out0-
47	TXCLK+	0	D		LVDS Clock+
48	TXCLK-	0	D		LVDS Clock-
49	VSS18		Р		Digital supply return.
50	VDD18		Р		Digital power supply. Decouple with minimum 0.1µF capacitor to VSS18 plane.
51	ATB0	0	А		Analog Test Bus. If not used, can be connected to VSS18 through a $10k\Omega$ resistor.
52	ATB1	0	А		Analog Test Bus. If not used, can be connected to VSS18 through a $10k\Omega$ resistor.
53	VDD18		Р		Digital power supply. Decouple with minimum 0.1µF capacitor to VSS18 plane.
54	VDD18		Р		Digital power supply. Decouple with minimum 0.1µF capacitor to VSS18 plane.
55	VSS18		Р		Digital supply return.
56	VSS18		Р		Digital supply return.
57	INCLK-	I	D		Clock Input. Inverting input for LVDS clocks.
58	INCLK+	I	D		Clock Input. Non-Inverting input for LVDS clocks.
59	VSS33		Р		Analog supply return.
60	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.
61	VDD33		Р		Analog power supply. Decouple with minimum 0.1µF capacitor to VSS33 plane.
62	VSS33		Р		Analog supply return.
63	IBIAS0	I	А		Connect with external 10k $\Omega$ 1% resistor to IBIAS1 pin.
64	IBIAS1	I	А		Connect with external 10kΩ 1% resistor to IBIAS0 pin.
65	VREFBG	0	A		Band gap reference output. Bypass with a $0.1 \mu F$ capacitor to VSS33. Can be overdriven with external voltage source.
66	VSS33		Р		Analog supply return.
67	VREFT1	0	А		Top of ADC reference. Bypass with a 0.1µF capacitor to VSS33.
68	VREFB1	0	А		Bottom of ADC reference. Bypass with a 0.1µF capacitor to VSS33.
	Exp Pad		Р		Exposed pad must be soldered to ground plane to ensure rated performance.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

SNAS461C - MAY 2010 - REVISED APRIL 2013

## Absolute Maximum Ratings<sup>(1)(2)</sup>

-		
Supply Voltage (VDD33)		4.2V
Supply Voltage (VDD18)		2.35V
Voltage on any VDD33 Input Pin (Not to exceed 4.2V)		-0.3V to (VDD33 + 0.3V)
Voltage on any VDD33 Output Pin (Not to exceed 4.2V)		-0.3V to (VDD33 + 0.3V)
Voltage on any VDD18 Input Pin (Not to exceed 2.35V)		-0.3V to (VDD18 + 0.3V)
Voltage on any VDD18 Output Pin (Not to exceed 2.35V)	-0.3V to (VDD18 + 0.3V)	
Input Current at any pin other than Sup	±25 mA	
Package Input Current (except Supply	Pins) <sup>(3)</sup>	±50 mA
Maximum Junction Temperature (TA)		150°C
Thermal Resistance <sup>(4)</sup>	(θ <sub>JA</sub> ) @ 225 LFPM	11.1°C/W
	(θ <sub>JA</sub> ) @ 0 LFPM	16.5°C/W
	(θ <sub>JC</sub> )	1.2°C/W
ESD Rating <sup>(5)</sup>	Human Body Model	2500V
	Machine Model	250V
Storage Temperature		-65°C to +150°C
Soldering process must comply with Te	xas Instruments' Reflow Temperature Profile specifi	cations. Refer to www.ti.com/packaging. <sup>(6)</sup>

All voltages are measured with respect to VSS = 0V, unless otherwise specified.

(1) An voltages are included with respect to vol 2 or , and so dates where because.
 (2) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not ensure specific performance limits. For ensured specifications and test conditions, see the Electrical Characteristics. The ensured specifications apply only for the test conditions listed. Some performance characteristics may degrade when the device is not operated under the listed test conditions. Operation of the device beyond the Operating Ratings is not recommended

- When the input voltage (V<sub>IN</sub>) at any pin exceeds the power supplies (V<sub>IN</sub> < VSS or V<sub>IN</sub> > VDD33), the current at that pin should be limited to 25 mA. The 50 mA maximum package input current rating limits the number of pins that can simultaneously safely exceed the power supplies with an input current of 25 mA to two.
- (4) The maximum power dissipation must be derated at elevated temperatures and is dictated by T<sub>JMAX</sub>, θ<sub>JA</sub> and the ambient temperature, T<sub>A</sub>. The maximum allowable power dissipation at any temperature is P<sub>D</sub> = (T<sub>JMAX</sub> T<sub>A</sub>)/θ<sub>JA</sub>. The values for maximum power dissipation listed above will be reached only when the device is operated in a severe fault condition (e.g. when input or output pins are driven beyond the power supply voltages, or the power supply polarity is reversed). Such conditions should always be avoided.

(5) Human body model is 100 pF capacitor discharged through a 1.5 kΩ resistor. Machine model is 220 pF discharged through 0Ω.

(6) When the input voltage (V<sub>IN</sub>) at any pin exceeds the power supplies (V<sub>IN</sub> < VSS or V<sub>IN</sub> > VDD33), the current at that pin should be limited to 25 mA. The 50 mA maximum package input current rating limits the number of pins that can simultaneously safely exceed the power supplies with an input current of 25 mA to two.

## **Operating Ratings**<sup>(1)(2)(3)</sup>

Operating Temperature Range	-55°C ≤ T <sub>A</sub> ≤ +125°C
VDD33	+3.15V to +3.45V
VDD18	+1.7V to +1.9V
VSS33 - VSS18	≤100mV

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not ensure specific performance limits. For ensured specifications and test conditions, see the Electrical Characteristics. The ensured specifications apply only for the test conditions listed. Some performance characteristics may degrade when the device is not operated under the listed test conditions. Operation of the device beyond the Operating Ratings is not recommended.
- (2) All voltages are measured with respect to VSS = 0V, unless otherwise specified.
- (3) When the input voltage (V<sub>IN</sub>) at any pin exceeds the power supplies (V<sub>IN</sub> < VSS or V<sub>IN</sub> > VDD33), the current at that pin should be limited to 25 mA. The 50 mA maximum package input current rating limits the number of pins that can simultaneously safely exceed the power supplies with an input current of 25 mA to two.



## **Quality Conformance Inspection**

MIL-STD-883, Method 5005 - Group A

Subgroup	Description	Temp (°C)
1	Static tests at	+25
2	Static tests at	+125
3	Static tests at	-55
4	Dynamic tests at	+25
5	Dynamic tests at	+125
6	Dynamic tests at	-55
7	Functional tests at	+25
8A	Functional tests at	+125
8B	Functional tests at	-55
9	Switching tests at	+25
10	Switching tests at	+125
11	Switching tests at	-55
12	Setting time at	+25
13	Setting time at	+125
14	Setting time at	-55

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup>

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
CMOS Digital I	nput DC Specifications (SCLK, SEN	N, SDI, CLPIN)						
V <sub>IH</sub>	Logical "1" Input Voltage				2.0		V	1, 2, 3
V <sub>IL</sub>	Logical "0" Input Voltage					0.8	V	1, 2, 3
		CLPIN		38		44	μA	
IIH	Logical "1" Input Current V <sub>IH</sub> = VDD33	SCLK, SDI		40		300	nA	1, 2, 3
		SEN		21		28	μA	
	Logical "0" Input Current	CLPIN		-85	-300		nA	1, 2, 3
I <sub>IL</sub>		SCLK, SDI		-50	-300		nA	
	VIL - V00	SEN		-60	-70		μΑ	
CMOS Digital C	Dutput DC Specifications (SDO)							
V <sub>OH</sub>	Logical "1" Output Voltage	I <sub>OUT</sub> = -0.5mA		1.93	1.8		V	1, 2, 3
V <sub>OL</sub>	Logical "0" Output Voltage	I <sub>OUT</sub> = 1.6mA		0.05		0.2	V	1, 2, 3
I <sub>OH</sub>	Output Leakage Current	$V_{OUT} = V_{DD}$		20		50	nA	1, 2, 3

(1) The analog inputs are protected as shown below. Input voltage magnitudes beyond the supply rails will not damage the device, provided the current is limited per Note 2 under the LM98640QML Electrical Characteristics. However, input errors will be generated If the input goes above VDD33 and below VSS.



(2) When the input voltage (V<sub>IN</sub>) at any pin exceeds the power supplies (V<sub>IN</sub> < VSS or V<sub>IN</sub> > VDD33), the current at that pin should be limited to 25 mA. The 50 mA maximum package input current rating limits the number of pins that can simultaneously safely exceed the power supplies with an input current of 25 mA to two.

(3) Typical figures are at T<sub>A</sub> = 25°C, and represent most likely parametric norms at the time of product characterization. The typical specifications are not ensured.



www.ti.com

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups	
I <sub>OL</sub>	Output Leakage Current	$V_{OUT} = V_{SS}$		-20	-50		nA	1, 2, 3	
LVDS Clock Re	eceiver DC Specifications (INCLK+	and INCLK- Pins)							
	Differential LVDS Clock	$R_L = 100\Omega$							
V <sub>IHL</sub>	High Threshold Voltage	V <sub>CM</sub> (LVDS Input Common Mode Voltage) = 1.25V		100		250	mV	1, 2, 3	
	Differential LVDS Clock	RL = 100Ω							
V <sub>ILL</sub>	Low Threshold Voltage	V <sub>CM</sub> (LVDS Input Common Mode Voltage) = 1.25V		-100	-250		mV	1, 2, 3	
LVDS Output D	OC Specifications								
V <sub>OD</sub>	Differential Output Voltage	LVDS Output Modes =		275	210	410	mV	1, 2, 3	
V <sub>OS</sub>	LVDS Output Offset Voltage	0000 x100 R <sub>L</sub> = 100Ω		1.19	1.05	1.3	V	1, 2, 3	
V <sub>OD</sub>	Differential Output Voltage	LVDS Output Modes =		325	250	460	mV	1, 2, 3	
V <sub>OS</sub>	LVDS Output Offset Voltage	0000 x101 R <sub>L</sub> = 100Ω		1.19	1.05	1.3	V	1, 2, 3	
V <sub>OD</sub>	Differential Output Voltage	LVDS Output Modes =		377	300	535	mV	1, 2, 3	
V <sub>OS</sub>	LVDS Output Offset Voltage	0000 x110 R <sub>L</sub> = 100Ω		1.1	.95	1.2	V	1, 2, 3	
V <sub>OD</sub>	Differential Output Voltage	LVDS Output Modes =		425	350	590	mV	1, 2, 3	
V <sub>OS</sub>	LVDS Output Offset Voltage	0000 x111 R <sub>L</sub> = 100Ω		1.1	0.95	1.2	V	1, 2, 3	
I <sub>OH</sub>	LVDS Output Leakage Current			4.25		5	μA	1, 2, 3	
I <sub>OL</sub>	LVDS Output Leakage Current			-4.29	-5		μA	1, 2, 3	
I <sub>OS</sub>	Output Short Circuit Current	$V_{OUT} = 0V, R_L = 100\Omega$		40		50	mA	1, 2, 3	
I <sub>IHL</sub>	Diffferential LVDS Clock Input Current	V <sub>IH</sub> = VDD33		23		36	μA	1, 2, 3	
IILL	Diffferential LVDS Clock Input Current	V <sub>IL</sub> = VSS		-34	-49		μA	1, 2, 3	

STRUMENTS

EXAS

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
Power Supply	Specifications	1						
	VDD33 Analog Supply Current	Powerdown Control Reg = 0x00 (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Power optimized for	5MHz		51.5		58		
	PGA Gain = 1-4x	15MHz		61.3		69	~ ^	1 0 0
		25MHz		69.6		79	mA	1, 2, 3
		40MHz		87.6		98		
	VDD33 Analog Supply Current	Powerdown Control Reg = 0x00 (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Power optimized for	5MHz		51.5		58		
	PGA Gain = 1-8x	15MHz		61.3		68	m۸	1 2 2
		25MHz		72.9		82	IIIA	1, 2, 3
		40MHz		91.3		103		
IA	VDD33 Analog Supply Current Single Channel	Powerdown Control Reg = 0x15 (CH1 PD) or = 0x2A (CH2 PD) (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Power optimized for	5MHz		29.5		35		
		15MHz		36.1		42		4 0 0
		25MHz		42		47	mA	1, 2, 3
		40MHz		53.7		60		
	VDD33 Analog Supply Current	Powerdown Control Reg = 0x15 (CH1 PD) or = 0x2A (CH2 PD) (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Power optimized for	5MHz		29.5		35		
	FGA Gain = 1-6X	15MHz		36.1		42	1.	
		25MHz		43.8		50	mA	1, 2, 3
		40MHz		55.6		64		
	VDD33 Analog Supply Current Powerdown	Powerdown Control Reg = 0x80		2.85		3.85	mA	1, 2, 3
	VDD18 Digital Supply Current	5MHz		36				
	LVDS Quad Lane Mode	15MHz		39			m۸	
	LVDS Output Mode Reg	25MHz		42			11174	
	- 000L	40MHz		45				
ID		5MHz		23.5		29		
	VDD18 Digital Supply Current	15MHz		25.5		31	mΔ	122
	v 22 to Digital Supply Suitent	25MHz		27.5		33		1, 2, 3
		40MHz		30.5		37		
	VDD18 Digital Supply Current Powerdown	Powerdown Control Reg = 0x80		1.2		3.0	mA	1, 2, 3



www.ti.com

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
	Average Power Dissipation	5MHz		212		244		
	Power optimized for	15MHz		250		284		
	PGA Gain = 1-4x Dual Channel	25MHz		280		320	mvv	1, 2, 3
2112	LVDS Dual Lane Mode	40MHz		345		390		
PWR	Average Power Dissipation	5MHz		212		244		
	Power optimized for	15MHz		250		284	- -	
	PGA Gain = 1-8x Dual Channel	25MHz		290		330	mW	1, 2, 3
	LVDS Dual Lane Mode	40MHz		356		407		
		200 mVpp, 200 KHz		-72.3				
	Dynamic Power Supply Rejection	200 mVpp, 500 KHz	-	-72			dB	
PSRR	Ratio	200 mVpp, 1 MHz	See <sup>(4)</sup>	-71				
	PGA Gain = 1x	200 mVpp, 1.5 MHz	-	-68				
		200 mVpp, 2 MHz	-	-66				
Internal Refere	nce Specifications		1				1	1
V <sub>REFBG</sub>	Reference Voltage		See <sup>(5)</sup>	1.218			V	
	Reference Tolerance (chip to chip)		See <sup>(6)</sup>	±2			%	
R <sub>REFBG</sub>	Reference Impedance		See <sup>(6)</sup>	20			kΩ	
	<b>T</b>	25°C to 125°C		80			°/mqq	
V <sub>REFTC</sub>	Temperature Coefficient	-55°C to 25°C		50			C	
Input Sampling	Circuit Specifications					ł		r
		CDS Gain=1x, PGA Gain=1x				2		
V <sub>IN</sub>	Input Voltage Level	CDS Gain=2x, PGA Gain=1x				1	Vp-p	1, 2, 3
		CDS Gain=1x, PGA Gain=0.7x		2.85				
V <sub>RESET</sub>	Reset Feed Through			500			mV	
		CDS Gain = 1x	See <sup>(6)</sup>	00.4				
	Sample and Hold Mode	$OS_X = VDD33 (OS_X = VSS)$		384			μΑ	
IIN_SH	Input Leakage Current	CDS Gain = 2x	See <sup>(6)</sup>	475				
		$OS_X = VDD33 (OS_X = VSS)$		-475			μΑ	
	Sample/Hold Mode		See <sup>(6)</sup>				_	
C <sub>SH</sub>	Equivalent Input Capacitance	CDS Gain = 1x		4			р⊢	
	(see Figure 22)	CDS Gain = 2x	See <sup>(6)</sup>	8			pF	
	CDS Mode		See <sup>(6)</sup>	200			~ ^	
IN_CDS	Input Leakage Current	$OS_X = VDD33 (OS_X = VSS)$		300		1	nA	
	CLPIN Switch Resistance		See <sup>(6)</sup>	40			_	
KCLPIN	(OS <sub>X</sub> to VCLP Node in Figure 19)			16			Ω	

(4) Dynamic Power Supply Rejection Ratio is performed by injecting a 200mVpp sine wave ac coupled to the analog supply pin. The LM98640's inputs are left floating in CDS mode and an FFT is captured. The spur ensured by the injected signal is recorded.

(5) This Parameter is ensured by design and/or characterization and is not tested.

(6) This Parameter is ensured by design and/or characterization and is not tested.

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L = 10pF$ , and  $f_{INCLK} = 40MHz$  unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
VCLP Reference	e Circuit Specification							
	VCLP DAC Resolution			5	5		Bits	1, 2, 3
	VCLP DAC Step Size			98	96	102	mV	1, 2, 3
		VCLP Control Register =		00.4	404			4 0 0
N/	VCLP DAC Voltage Min Output	0110 0000		224	194	298	mv	1, 2, 3
VVCLP		VCLP Control Register =		0.07	2.00	2.44		4 0 0
	VCLP DAC Voltage Max Output	0111 1101		3.07	2.99	3.11	V	1, 2, 3
	VCLP DAC Short Circuit Output	VCLP Control Register =		22			~	
ISC	Current	011x xxxx		33			mA	
Coarse Analog	Offset DAC Specifications							
	Resolution			±8			Bits	
	Offset Adjustment Range Referred	Minimum DAC Code = 0x000		-262	-264	-251		
	to AFE Input CDS Gain = 1x	Maximum DAC Code = 0x1FF		263	251	266	mV	1, 2, 3
	Offset Adjustment Range Referred	Minimum DAC Code = 0x000		-131	-132	-126	.,	
	to AFE Input CDS Gain = 2x	Maximum DAC Code = 0x1FF		131	126	133	mv	1, 2, 3
	Offset Adjustment Range	Minimum DAC Code = 0x000		-2146	-2162	-2058	LSB	1 2 2
	Referred to AFE Output M	Maximum DAC Code = 0x1FF		2154	2058	2176	LOD	1, 2, 3
	DAC Step Size CDS Gain = 1x	Input Referred		1			mV	
	DAC Step Size CDS Gain = 1x	Output Referred		8			LSB	
DNL	Differential Non-Linearity	CDS Gain = 1x or 2x 40MHz		±0.97	-1.1	1.1	LSB	1, 2, 3
INL	Integral Non-Linearity	CDS Gain = 1x or 2x 40MHz		±1.5	-2.8	2.80	LSB	1, 2, 3
Fine Analog Of	fset DAC Specifications							
	Resolution			±8			Bits	
	Offset Adjustment Range Referred	Minimum DAC Code = 0x000		-4.6	-5.9	-3.1		
	to AFE Input CDS Gain = 1x	Maximum DAC Code = 0x1FF		5.3	4.3	6.8	mV	1, 2, 3
	Offset Adjustment Range Referred	Minimum DAC Code = 0x000		-2.3	-2.9	-1.5		
	to AFE Input CDS Gain = 2x	Maximum DAC Code = 0x1FF		2.6	2.1	3.4	mV	1, 2, 3
	Offset Adjustment Range	Minimum DAC Code = 0x000	-	-38	-48	-25	ISB	1 2 3
	Referred to AFE Output	Maximum DAC Code = 0x1FF		43	35	56	LOD	1, 2, 3
	DAC Step Size CDS Gain = 1x	Input Referred		20			uV	
	DAC Step Size CDS Gain = 1x	Output Referred		0.16			LSB	
DNL	Differential Non-Linearity			±1			LSB	
INL	Integral Non-Linearity			±2.2			LSB	

STRUMENTS

EXAS



www.ti.com

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
PGA Specificat	pecifications							
	Gain Resolution					8	Bits	1, 2, 3
	Monotonicity		See <sup>(7)</sup>					
	Maximum Gain	CDS Gain = 1x		8.3	7.92	8.78	V/V	1, 2, 3
	Maxinum Gain	CDS Gain = 1x		18.4	17.99	18.88	dB	1, 2, 3
	Minimum Gain	CDS Gain = 1x		0.64	0.62	0.66	V/V	1, 2, 3
		CDS Gain = 1x		-3.8	-4.15	-3.54	dB	1, 2, 3
	PGA Eurotion	Gain	(V/V) = (1	80/(277-PC	GA Code)	)		
	FGA Function	Gain (dB)	= 20LOG	10(180/(27	7-PGA C	ode))		
				99.0	95.2		%	1, 2
	Channel Matching	Minimum PGA Gain		99.0	94.0		%	3
	Channel Matching		99.0	95.2		%	1, 2	
		Maximum FGA Gain		99.0	94.0		%	3
ADC Specificat	ions							
V <sub>REFT</sub>	Top of Reference			2.0			V	
V <sub>REFB</sub>	Bottom of Reference			1.0			V	
$V_{REFT}$ - $V_{REFB}$	Differential Reference Voltage			1.0			V	
	Overrange Output Code			16383	16383		Code	1, 2, 3
	Underrange Output Code			0		0	Code	1, 2, 3
Full Channel P	erformance Specifications		-					
		5MHz		0.78	-1.03	1.53		
		5MHz CDS		1.0	-1.20	2.24		
DNL	Differential Non-Linearity	15MHz		0.78	-1.02	1.58	LSB	1, 2, 3
		25MHz		0.78	-1.01	1.36		
		40MHz		0.78	-1.03	1.45		
		5MHz		1.7	-5.38	4.38		
		5MHz CDS		1.7	-3.41	5.15	1	
INL	Integral Non-Linearity	15MHz		1.9	-3.45	3.49	LSB	1, 2, 3
		25MHz		2.4	-5.40	6.03		
		40MHz		6.0	-9.9	7.34		

(7) This Parameter is ensured by design and/or characterization and is not tested.



www.ti.com

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Units	Sub- groups
				-66.0		-64.6		1, 2
		SINIHZ		-65.0		-62.5	aв	3
				-66.0		-64.6		1, 2
	Noise Floor CDS Gain = 1x	15MHZ		-66.0		-64.5	aв	3
	PGA Gain = FE			-66.0		-64.6		1, 2
		ZOWIHZ		-65.0		-64.3	aв	3
				-66.0		-64.6		1, 2
		40MHZ		-66.5		-65.7	dB	3
				8.20		9.6		1, 2
		510172		9.15		11.9	LSB	3
				8.20		9.6	1.05	1, 2
Nutra	Noise Floor CDS Gain = 1x	15MHZ		8.20		9.4	LSB	3
Noise	PGA Gain = FE			8.20		9.45		1, 2
		25MHZ		9.15		10.0	LSB	3
		40MHz		8.20		9.45		1, 2
				7.70		8.5	LSB	3
	Noise Floor CDS Gain = 1x PGA Gain = 61	5MHz		-79		-78	dB	1, 2
		15MHz		-79		-78	dB	1, 2
		25MHz		-79		-78	dB	1, 2
		40MHz		-79		-78	dB	1, 2
		5MHz		1.8		2.05	LSB	1, 2
	Noise Floor CDS Gain = 1x	15MHz		1.8		2.05	LSB	1, 2
	PGA Gain = 61	25MHz		1.8		2.05	LSB	1, 2
		40MHz		1.8		2.05	LSB	1, 2
		5MHz		-79		-77	- dB	4.5.0
		15MHz		-86		-84		
	Channel to Channel Crosstalk	25MHz		-79		-77		4, 5, 6
		40MHz		-76		-74		
		5MHz		2.2		6.0		
	CDS Mode Bimodal Offset	15MHz		2.1		6.0	.,	1, 2, 3
	PGA Gain = 1x	25MHz		2.2		6.0	mv	
5145		40MHz		2.3		6.0		
BMD		5MHz		0.35		1		
	CDS Mode Bimodal Offset	15MHz		0.29		0.87	.,	
	CDS Gain = 1x PGA Gain = 1x	25MHz		0.33		0.89	mv	1, 2, 3
		40MHz		0.4		1.05		
		<b>CM U</b>		67.4	66.0		15	4, 5
		5MHz		64.2	63.0		αB	6
				68.0	66.6		15	4, 5
		15MHz		64.2	63.0		dB	6
SNR	Signal-to-Noise Ratio	0.51.11.1		68.5	66.7		15	4, 5
		25MHz		64.2	63.0		dB	6
		401.11		68.5	66.5		15	4, 5
		40MHz		64.0	62.0		aВ	6



www.ti.com

## LM98640QML Electrical Characteristics<sup>(1)(2)</sup> (continued)

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 40MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Тур <sup>(3)</sup>	Min	Max	Max Units	
				-71.4		-69.0		4, 5
		SMHZ		-69.9		-67.8	aв	6
				-75.1		-73.1	٩D	4, 5
TUD	Total Usersania Distantian	TOMHZ		-73.9		-71.8	aв	6
THD	Total Harmonic Distortion			-68.9		-66.8	٩D	4, 5
		201012		-68.2		-66.2	uБ	6
				-62.0		-60.0	٩D	4, 5
				-62.0		-60.0	aв	6
		EMU		71.5	69.4		٩D	4, 5
SFDR				70.4	68.4		uБ	6
				76.0	74.0		٩D	4, 5
	Spurious Free Dynamic Dange			76.0	74.0		dB	6
	Spunous-Free Dynamic Range			69.0	67.0		٩D	4, 5
				69.0	67.0		uв	6
				62.0	60.0		dD	4, 5
		4010112		62.0	60.0		uБ	6
				67.0	65.0		dD	4, 5
				64.5	62.0		uБ	6
				68.0	66.0		dD	4, 5
	Signal-to-Noise Plus Distortion	ТЭМПZ		64.5	62.5		uБ	6
SINAD	Ratio	Ratio 66.0 64.0			dD	4, 5		
		ZOWINZ		64.5	62.5		uБ	6
				61.0	59.0		dB	4, 5
		4010112		60.5	59.0		uв	6
		51147		10.8	10.5		Bite	4, 5
		JIVII IZ		10.4	10.0		Units dB dB dB dB dB dB dB dB dB dB dB dB dB	6
				11.0	10.7		Bito	4, 5
ENOB	Effective Number of Rite			10.4	10.1		DIIS	6
LINOB		25MHz		10.7	10.3		Bite	4, 5
				10.4	10.1		DIIS	6
				9.8	9.5		Bito	4, 5
		40IVI⊓Z		9.8 <b>9.5</b>			DIIS	6



#### SNAS461C - MAY 2010 - REVISED APRIL 2013

## **AC Timing Specifications**

The following specifications apply for VDD33 = 3.3V, VDD18 = 1.8V,  $C_L$  = 10pF, and  $f_{INCLK}$  = 15MHz unless otherwise specified.

	Parameter	Test Conditions	Notes	Typ <sup>(1)</sup>	Min	Max	Max Units		
Input Clock Tir	ning Specifications							r	
4	Input Clock Fraguency	INCLK = ADCCLK			F	40	MUT	9, 10,	
INCLK		(ADC Rate Clock)			5	40	IVITZ	11	
T <sub>dc</sub>	Input Clock Duty Cycle			50/50	40/60	60/40	%	9, 10, 11	
Full Channel L	atency Specifications	•							
t <sub>LAT</sub>	Pipeline Latency		See <sup>(2)</sup>			10	T <sub>ADC</sub>		
LVDS Output T	iming Specifications								
t <sub>DOD</sub>	Data Output Delay	f <sub>INCLK</sub> = 40MHz INCLK = ADCCLK		6.44		7.50		9, 10, 11	
t	Dual Lane Mode	(ADC Rate Clock)		0.60		1 01	00	9, 10,	
LDSO	Odd Data Setup	not tested in production.		0.09		1.91	115	11	
ta ea	Dual Lane Mode	Min/Max ensured by design, characterization and statistical		0.80	4.0	ne	9, 10,		
USE	Even Data Setup	analysis.		0.09		4.0	115	11	
toop	Quad Lane Mode			0.63		2.00	ns	9, 10,	
<sup>v</sup> QSR	Data to Rising Clock Setup			0.00		2.00	115	11	
tour	Quad Lane Mode	_		0.53		1 60	ns	9, 10,	
'QHF	Falling Clock to Data Hold			0.00		1.00	110	11	
Serial Interface	Timing Specifications	T			1	n		n.	
		$f_{SCLK} \le f_{INCLK}$				20	MHz	9, 10, 11	
f <sub>SCLK</sub>	Input Clock Frequency	INCLK = ADCCLK	_	1					
		(ADC Rate Clock)							
	SCLK Duty Cycle			50/50	40/60	60/40	ns	9, 10, 11	
t <sub>IH</sub>	Input Hold Time			1	2.5		ns	9, 10, 11	
t <sub>IS</sub>	Input Setup Time			1	2.5		ns	9, 10, 11	
t <sub>SENSC</sub>	SCLK Start Time After SEN Low			1	1.5		ns	9, 10, 11	
t <sub>SCSEN</sub>	SEN High after last SCLK Rising Edge			2	2.5		ns	9, 10, 11	
t <sub>SENW</sub>	SEN Pulse Width			6	8		ns	9, 10, 11	
t <sub>OD</sub>	Output Delay Time			10.54		11.6	ns	9, 10, 11	
t <sub>HZ</sub>	Data Output to High Z			1.2		1.23	T <sub>SCLK</sub>	9, 10, 11	

(1) Typical figures are at  $T_A = 25^{\circ}$ C, and represent most likely parametric norms at the time of product characterization. The typical specifications are not ensured.

(2) This Parameter is ensured by design and/or characterization and is not tested.



#### www.ti.com

	Parameter	Test Conditions	Min	Max	Units			
		Powerdown Control Reg = 0x00 (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	VDD33 Analog Supply Current Dual Channel Power optimized for	5MHz						
	PGA Gain = 1-4x	15MHz	VHz +2					
		25MHz		±Z	IIIA			
		40MHz	Test ConditionsMinMaxUnitPowerdown Control Reg = 0x00 Power Trimming section for PGA and C Power Trimming register settings) $\pm 2$ mA15MHz 25MHz $\pm 2$ mA25MHz 40MHz $\pm 2$ mAPowerdown Control Reg = 0x00 Power Trimming section for PGA and C Power Trimming register settings) $\pm 2$ mA25MHz 2 $5MHz$ 15MHz 2 $\pm 2$ mA0C Power Trimming section for PGA and 					
		Powerdown Control Reg = 0x00 (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Channel Power optimized for	5MHz						
	PGA Gain = 1-8x	15MHz		+0	2 mA			
		25MHz	25MHz					
IA		40MHz						
	VDD33 Analog Supply Current Single	Powerdown Control Reg = 0x15 (CH1 PD) or = 0x2A (CH2 PD) (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Channel Power optimized for	5MHz						
	PGA Gain = 1-4x	15MHz		±2				
		25MHz			mA			
		40MHz						
		Powerdown Control Reg = 0x15 (CH1 PD) or = 0x2A (CH2 PD) (see Power Trimming section for PGA and ADC Power Trimming register settings)						
	Channel Power optimized for	5MHz						
	PGA Gain = 1-8x	15MHz						
		25MHz		±2	mA			
		40MHz						
	VDD33 Analog Supply Current Powerdown	Powerdown Control Reg = 0x80		±1	mA			
	VDD18 Digital Supply Current	5MHz						
		15MHz			4			
П		25MHz		±1	mA			
		40MHz						
	VDD18 Digital Supply Current Powerdown	Powerdown Control Reg = 0x80		±1	mA			

## Operating Life Test Delta Parameters T<sub>A</sub> at 25°C<sup>(1)(2)</sup>

(1) The analog inputs are protected as shown below. Input voltage magnitudes beyond the supply rails will not damage the device, provided the current is limited per Note 2 under the LM98640QML Electrical Characteristics. However, input errors will be generated If the input goes above VDD33 and below VSS.



(2) These parameters are worse case drift. Deltas are performed at room temperature Post OP Life. All other parameters no Deltas are required.

Texas Instruments

SNAS461C - MAY 2010 - REVISED APRIL 2013

www.ti.com



Copyright © 2010–2013, Texas Instruments Incorporated







### System Overview

#### Introduction

The LM98640QML is a 14-bit, 5MSPS to 40MSPS, dual channel, complete Analog Front End (AFE) for digital imaging applications. The system block diagram of the LM98640QML, shown in Figure 4 highlights the main features of the device. Each input has its own Input Bias and Clamping Network and Correlated Double Sample (CDS) amplifier (which can also be configure to operate in Sample/Hold Mode). Two +/-8Bit Offset DACs apply independent coarse and fine offset correction for each channel. A -3 to 18dB Programmable Gain Amplifier (PGA) applies independent gain correction for each channel. The signals are digitized using two independent on chip high performance 14-bit, 40MHz analog-to-digital converters. The data is finally output using a unique Serial LVDS output format that prevents data loss during any ionizing doses.

## Input Sampling Modes

The LM98640QML provides two input sampling modes, Sample & Hold mode and Correlated Double Sample (CDS) mode. The following sections describe these two input sampling modes.

#### Sample & Hold Mode

In Sample/Hold mode, a Video Level signal and a Reference Level signal need to be presented to the LM98640QML. The Reference Level signal must be connected to the  $OS_X$ + pin, and the Video Level signal connected to the  $OS_X$ - pin. The output code will then be  $OS_X$ + minus  $OS_X$ -, or the difference between the Reference Level and Video Level. A minimum code represents zero deviation between the Reference and Video Levels and a maximum code represents a 2V deviation between the Reference and Video Levels with CDS and PGA gains of 1x.

The Reference Level signal can be either an external signal from the image sensor, or the VCLP pin can be externally connected to the  $OS_X$ + pin. In order to fully utilize the range of the input circuitry it is desirable to cause the Black Level signal voltage to be as close to the Reference Level voltage as possible, resulting in a near zero scale output for Black Level pixels. The LM98640QML provides several methods for ensuring the Black Level signal and Reference Level are matched, these are described in the Input Bias and Clamping section.

To place the LM98640QML in Sample & Hold Mode from power up, first write the baseline configuration to the registers as shown in Table 5. This configuration has Sample & Hold mode enabled by default. Next, the SAMPLE pulse must be properly positioned over the input signal using the CLAMP/SAMPLE Adjust.

## Sample & Hold Mode CLAMP/SAMPLE Adjust

For accurate sampling of the input signals the LM98640QML allows for full adjustment of the internal SAMPLE pulse to align it to the proper positions over the input signal. In Sample & Hold mode the SAMPLE pulse should be placed over the pixel output period of the image sensor. Only the Sample Start and Sample End Registers (0x22,0x23) need to be configured, the Clamp Start and Clamp End Registers (0x20,0x21) are not valid in Sample & Hold Mode. Internally the input clock is divided into 64 edges per clock period, the Sample Start and Sample End Registers correspond to the internal edge number the SAMPLE pulse will start and end. To adjust the SAMPLE pulse, first send the CLAMP and SAMPLE signals to the DTM pins by writing **10** to bits[4:3] of the Clock Monitor Register (0x09). This will allow the user to observe the SAMPLE pulse on pin DTM1 along with the image sensor output using an oscilloscope. Then, using the Sample Start and End Registers, adjust the SAMPLE pulse to align it over the Video Level portion of the image sensor output. To allow for settling and to reduce noise, the SAMPLE pulse should be made as wide as possible and fill the entire Video Level portion of the input signal.

Figure 17 shows some examples of an input waveform and where the SAMPLE pulse should be placed. Ideally the image sensor output would line up directly with the input clock at the AFE inputs, but due to trace delays in the system the image sensor output is delayed relative to the input clock. In the delayed image sensor waveform the Sample Start value is higher than the Sample End value. In this situation the SAMPLE pulse will start in one clock period and wraps around to the next. This allows the LM98640QML to adjust for the delay in the image sensor waveform. Notice that edge zero of the internal clock does not line up with the rising edge of the input clock. This is due to internal delays of the clock signals. The amount of delay can be calculated from operating frequency using the following formula:  $t_{DCLK} = 6.0ns + 3/64 * T_{INCLK}$ 



SNAS461C - MAY 2010 - REVISED APRIL 2013



Figure 17. S/H Mode CLAMP/SAMPLE Adjust

#### CDS Mode

In CDS mode, both the Reference Level and Video Level are presented to the LM98640QML on the  $OS_X$ - pin. The  $OS_X$ + pin should be bypassed to ground with a 0.1uF capacitor. The CLAMP pulse is then used to sample the Reference Level and the SAMPLE pulse is used to sample the Video Level. The output code will then be the Reference Level minus the Video Level, or the difference between the Reference Level and Video Level. A minimum code represents zero deviation between the Reference and Video Levels and a maximum code represents a 2V deviation between the Reference and Video Levels with CDS and PGA gains of 1x.

To place the LM98640QML in CDS Mode from power up, first write the baseline configuration to the registers as shown in Table 5. Then ensure S/H mode is disabled by clearing bit[7] of the Sample & Hold Register (0x06), then enable CDS mode by setting bit[0] of the Main Configuration Register (0x00). Next the CLAMP and SAMPLE pulses need to be positioned correctly over the reference and video levels respectively using the CLAMP/SAMPLE Adjust.

#### CDS Mode Bimodal Offset

In CDS mode, the input sampling amplifier has two physical paths through which a particular pixel will be sampled. These two sampling paths are a requirement in the Correlated Double Sampling architecture. The sampling of the one pixel will travel the first path (arbritrarily called an even pixel), and the sampling of the next pixel will travel the second path (called an odd pixel). The sampling will continue in an even/odd/even/odd fashion for all pixels processed in a particular channel. Due to slight variances in the sampling paths (most commonly a difference in switched capacitor matching), the processing of identical pixels through the two different paths may result in a small offset in ADC output data between the two paths. To correct this, a simple digital offset can be applied in post processing to either the even pixel data or the odd pixel data. To simplify this action, the LM98640QML will indicate (with the TXFRM signal) whether the pixel traveled the even path or the odd path. For all "Odd" pixels, the TXFRM signal is high for three TXCLK periods. For "Even" pixels, the TXFRM signal is high for three is only one sampling path, therefore there is no need to indicate an even or odd pixel. As a result, the TXFRM signal is the same for every pixel in Sample and Hold mode (i.e. high for three TXCLK periods).

Copyright © 2010–2013, Texas Instruments Incorporated



www.ti.com

#### CDS Mode CLAMP/SAMPLE Adjust

In CDS mode, the LM98640QML utilizes two input networks, alternating between them every pixel, to increase throughput speeds. Because of this, there are two sets of CLAMP and SAMPLE pulses in the Table 8, one for even pixels and one for odd. Sample Start and Sample End Registers (0x22,0x23) along with the Clamp Start and Clamp End Registers (0x20,0x21) control both the even and odd CLAMP and SAMPLE pulses. To adjust the CLAMP and SAMPLE pulses, first send the CLAMP<sub>ODD</sub> and SAMPLE<sub>ODD</sub> signals to the DTM pins by writing **10** to bits[4:3] of the Clock Monitor Register (0x09). This will allow the user to observe the CLAMP<sub>ODD</sub> and SAMPLE<sub>ODD</sub> pulses on pins DTM0 and DTM1 along with the image sensor output using an oscilloscope. The CLAMP and SAMPLE pulses will only be shown for every other pixel because of the even odd architecture, but the positions of the even CLAMP and SAMPLE pulses will be identical to that of the odd CLAMP and SAMPLE. Then, using the Clamp Start/End and Sample Start/End registers, adjust the positions of the CLAMP and SAMPLE pulses to align them over the Reference and Video Levels of the input signal. To allow for settling and to reduce noise, the CLAMP and SAMPLE pulses should be made as wide as possible and placed near the far edge of their respective input levels.

The following figure shows some examples of input CCD waveforms and placement of the CLAMP and SAMPLE positions for each. Ideally the CCD output would line up directly with the input clock at the AFE inputs, but due to trace delays in the system the CCD output is delayed relative to the input clock. In the Delayed CCD waveform the Sample Start/End Register values are lower than the Clamp Start/End Register Values. In this situation the sample pulse is not generated until the next clock period, which allows it to be correctly placed in the Video Level of the input signal. Notice that edge zero of the internal clock does not line up with the rising edge of the input clock. This is due to internal delays of the clock signals. The amount of delay can be calculated from operating frequency using the following formula:  $t_{DCLK} = 6.0ns + 3/64 * T_{INCLK}$ 







## Input Bias and Clamping

The inputs to the LM98640QML are typically AC coupled and can be sampled in either Sample and Hold Mode (S/H Mode) or Correlated Double Sampling Mode (CDS Mode). The circuit of Figure 19 shows the input structure of the LM98640QML. The DC bias point for the LM98640QML side of the AC coupling capacitor can to be set using an external DC bias resistor network, by using the CLPIN configuration, or by using the BITCLP configuration. A typical CCD waveform is shown in Figure 20. Also shown in Figure 20 is an internal signal "CLAMP" which can be used to "gate" the CLPIN signal so that it only occurs during the "pedestal" portion of the CCD pixel waveform.



Figure 19. Input Structure Diagram

TEXAS INSTRUMENTS

www.ti.com

SNAS461C - MAY 2010 - REVISED APRIL 2013



Figure 20. Typical CCD Waveform and LM98640QML Input Clamp Signal (CLPIN)

#### Sample and Hold Mode Biasing

Proper DC biasing of the CCD waveform in Sample and Hold mode is critical for realizing optimal operating conditions. In Sample/Hold Mode, the DC bias point of the input pin is typically set by actuating the input clamp switch (see Figure 19) during optical black pixels which connects the input pins to the VCLP pin DC voltage. The signal controlling this switch is CLPIN. CLPIN is an external signal connected on the CLPIN pin.

Actuating the input clamp will force the average value of the CCD waveform to be centered around the VCLP DC voltage. During Optical Black Pixels, the CCD output has roughly three components. The first component of the pixel is a "Reset Noise" peak followed by the Reset (or Pedestal) Level voltage, then finally the Black Level voltage signal. Taking the average of these signal components will result in a final "clamped" DC bias point that is close to the Black Level signal voltage.

To provide a more precise DC bias point (i.e. a voltage closer to the Black Level voltage), the CLPIN pulse can be "gated" by the internally generated CLAMP clock. This resulting  $CLPIN_{GATED}$  signal is the logical "AND" of the CLAMP and CLPIN signals as shown in Figure 20. By using the  $CLPIN_{GATED}$  signal, the higher Reset Noise peak will not be included in the clamping period and only the Pedestal Level components of the CCD waveform will be centered around VCLP.



SNAS461C - MAY 2010-REVISED APRIL 2013





In Sample and Hold Mode, the impedance of the analog input pins is dominated by the switched capacitance of the CDS/Sample and Hold amplifier. The amplifier switched capacitance, shown as  $C_S$  in Figure 21, and internal parasitic capacitances can be estimated by a single capacitor switched between the analog input and the VCLP reference pin for Sample and Hold mode. During each pixel cycle, the modeled capacitor,  $C_{SH}$ , is charged to the  $OS_X$ + minus  $OS_X$ - voltage then discharged. The average input current at the  $OS_X$ - pin can be calculated knowing the input signal amplitude and the frequency of the pixel.



Figure 22. Equivalent Input Switched Capacitance S/H Mode

#### **CDS Mode Biasing**

Correlated Double Sampling mode does not require as precise a DC bias point as does Sample and Hold mode. This is due mainly to the nature of CDS itself, that is, the Video Signal voltage is referenced to the Reset Level voltage instead of the static DC VCLP voltage. The common mode voltage of these two points on the CCD waveform have little bearing on the resulting differential result. However, the DC bias point does need to be established to ensure the CCD waveform's common mode voltage is within rated operating ranges.





Figure 23. CDS Mode Simplified Input Diagram

The CDS mode biasing can be performed in the same way as described in the Sample and Hold Mode Biasing section, or, an external resistor divider can be placed across the  $OS_{X^-}$  input to provide the DC bias voltage. In CDS Mode the  $OS_X^+$  pins should each be decoupled with  $0.1\mu$ F capacitors to ground.



Figure 24. CDS Mode Input Bias Current

Unlike in Sample and Hold Mode, the input bias current in CDS Mode is relatively small. Due to the architecture of CDS switching, the average charge loss or gain on the input node is ideally zero over the duration of a pixel. This results in a much lower input bias current, whose main source is parasitic impedances and leakage currents. As a result of the lower input bias current in CDS Mode, maintaining the DC Bias point the input node over the length of a line will require a much smaller AC input coupling capacitor.

## VCLP DAC

The VCLP pin can be used to provide the reference level for incoming signals in Sample and Hold Mode. The pin is driven by the VCLP DAC, the VCLP DAC has five bits and has an approximate range of 2.9V. The VCLP DAC is controlled by the VCLP Control Register (0x04), and programmable through the serial interface.

## Programmable Gain

The LM98640QML provides two independent gain stages. The first stage is in the input CDS/SH circuit. The second is in the form of a Programmable Gain Amplifier (PGA).



#### **CDS/SH Stage Gain**

www.ti.com

The CDS/SH gain is programmable to either 0dB or 6dB gain. The load presented to the user in 6dB mode is roughly twice the switched load of 0dB mode. The CDS/SH gain settings affect both channels. The CDS/SH gain bit is located in bit 2 of the Main Configuration register, and programmable through the serial interface.

#### **PGA Gain Plots**

The PGA has an 8-bit resolution with a gain range of -3dB to 18dB. Figure 25 below shows a plot for the gain. Each channel has a independent PGA controlled by registers CH1 PGA and CH2 PGA, and programmable through the serial interface.



Figure 25. PGA Gain vs. PGA Gain Code

### **Programmable Analog Offset Correction**

The LM98640QML provides two analog DACs per channel to provide flexibility in offset control. Each channel has a Coarse DAC and Fine DAC which have +/-8bit resolutions (8bit + Sign). The two DACs can be used independently or as Coarse/Fine configuration. The Coarse DAC provides a sufficient range with moderate step sizes, while the Fine DAC is for designs which need a finely tuned offset. The correction voltage is applied to the "Video" level for both Sample & Hold and CDS input modes. Because of the DACs location in the signal path, the correction range lowers as CDS gain increases, and the output referred correction steps and ranges increase with PGA gain. Table 1 provides the range and step size of each DAC.

	CDS/SH Gain	Range <sup>(1)</sup>	Step Size <sup>(1)</sup>	Output ADC Codes				
Coarse DAC	1x	+/- 250mV	1mV	+/- 2048				
	2x	+/- 125mV	500µV	+/- 2048				
Fine DAC	1x	+/- 5mV	20µV	+/- 41				
	2x	+/- 2.5mV	10µV	+/- 41				

Table 1.	Analog	Offset	DAC	<b>Specifications</b>
----------	--------	--------	-----	-----------------------

(1) Referred to Input

To use the Offset Correction DACs, the Coarse DAC and Fine DAC must be enabled using bits[6:5] of the Main Configuration Register (0x00). Then the desired correction value should be entered into the CDAC or FDAC register of the appropriate channel. The Offset Correction DACs use a signed binary format which is summarized in Table 2.

0

-20

-41

SNAS461C - MAY 2010 - REVISED APRIL 2013

www.ti.com

Table 2. Analog Onset Correction DAC Format								
CDAC / FDAC Input Value	CDAC Correction (Codes)	FDAC Correction (Code						
1 1111 1111	+2048	+41						
1 0111 1111	+1024	+20						

 Table 2. Analog Offset Correction DAC Format

0

-1024

-2048

## Analog to Digital Converter

0 1111 1111

0 0111 1111

0 0000 0000

The LM98640QML has a 14bit Analog to Digital Converts (ADC) for each channel. Each ADC has maximum and minimum conversion rate of 40 MSPS and 5 MSPS per channel respectively. The DNL performance is +/-0.5LSB and +/-2LSB for INL for a 14bit out. The noise floor is -79dB at 2V with a programmable gain of 0dB. If an out of range pixel is presented to the ADC, the ADC will return to full compliance within two cycles of the pixel clock.

## LVDS Output

### LVDS Output Voltage

The LM98640QML output data is presented in LVDS format. Table 3 shows the available LVDS differential output voltage (VOD) settings and its associated offset voltage (VOS).

VOD	VOS
250mV	1.2V
300mV	1.2V
350mV	1.1V
400mV	1.1V

Table 3. LVDS Differential Output Voltage Setting
---

## LVDS Output Modes

The LM98640QML has a unique serial LVDS output format to protect data transfer during ionizing doses. The format provides a buffer on either side of the data word, this is accomplished by clocking a 14bit word using a 16bit clock rate. In the event of an ionizing dose that affects the DLL the output clock period could fluctuate; with no buffer for the data word this fluctuation could cause the loss of one or more of the data word bits, but because the LM98640QML provides the buffer the fluctuation does not cause any data loss. The data can also be sent out in two modes: Dual or Quad Lane. The following sections describe these two modes.

## TXFRM Output

The LM98640QML output includes a frame signal (TXFRM) that should be used to locate the beginning and end of a particular pixel's serial data word. The rising edge of TXFRM is coincident with the pixel's leading bit transition (TXOUT MSB). This TXFRM rising edge can be detected by the capturing FPGA or ASIC to mark the start of the serial data word.

In CDS mode, the input sampling amplifier has two physical paths through which a particular pixel will be sampled. These two sampling paths are a requirement in the Correlated Double Sampling architecture. The sampling of the one pixel will travel the first path (arbritrarily called an even pixel), and the sampling of the next pixel will travel the second path (called an odd pixel). The sampling will continue in an even/odd/even/odd fashion for all pixels processed in a particular channel. Due to slight variances in the sampling paths (most commonly a difference in switched capacitor matching), the processing of identical pixels through the two different paths may result in a small offset in ADC output data between the two paths. To correct this, a simple digital offset can be applied in post processing to either the even pixel data or the odd pixel data. To simplify this action, the LM98640QML will indicate (with the TXFRM signal) whether the pixel traveled the even path or the odd path. For all "Odd" pixels, the TXFRM signal is high for three TXCLK periods. For "Even" pixels, the TXFRM signal is high for three is only one sampling path, therefore there is no need to indicate an even or odd pixel. As a result, the TXFRM signal is the same for every pixel in Sample and Hold mode (i.e. high for three TXCLK periods).



#### **Output Mode 1 - Dual Lane**

In Dual Lane mode each input channel has its own data output presented at 16X the pixel clock rate. A frame signal (TXFRM) is output at the pixel clock rate with the rising edge occurring coincident with the transition of the MSB of the data. In Sample/Hold Modes of operation, the falling edge is coincident with the transition of bit 7 of the data. In CDS Mode, the falling edge of TXFRM toggles between the ransition of bit 9 and bit 7 of the data. A differential clock is also output with transitions aligned with the center of the data eye. Data rates for Dual Lane mode range from 80Mbps, with a 5MHz clock, up to 640Mbps, with a 40MHz clock.



Figure 26. Dual Lane LVDS Output Timing Diagram

#### Output Mode 2 - Quad Lane

In Quad Lane mode each input channel is split into two data lanes which are presented at 8X the pixel rate. The MSBs (bits 13 through 7) will be presented to one channel while the LSBs (bits 6 through 0) will be presented to the other. A frame signal is run at the pixel clock rate with the rising edge coincident with the transition of the MSB of the data and the falling edge coincident with the transition of bits 10 and 3 of the data lanes for an odd output value, and coincident with the transition of bits 11 and 4 for a even output value. A differential clock is also output with rising edge transitions aligned within each data eye. Data rates for Quad Lane mode range from 40Mbps, with a 5MHz clock, up to 320Mbps, with a 40MHz clock.

**INSTRUMENTS** 

Texas





#### LVDS Test Modes

The LVDS test modes present programmable data patterns to the input of the LVDS serializer block. The type of pattern is selectable through the Test Pattern Control register. Once the LVDS test mode is enabled the patterns are output indefinitely. Table 4 below shows the available test pattern modes.

Test Pattern Control[6:4]	Test Mode
000	Fixed Code
001	Horizontal Gradient
010	Vertical Gradient
011	Lattice Pattern
100	Strip Pattern
101	LVDS Test Pattern (Synchronous)
110	LVDS Test Pattern (Asynchronous)
111	Reserved

Each pattern consists of a Start Period and Valid Pixel region. During the Start Period the output is the minimum code (0x0000). The Valid Pixel region contains the selected Test Pattern Mode output. The length (in pixels) of the Start period is set using the Test Pattern Start register, and the width of the Valid Pixel region is set using the Test Pattern Width register.

To start the test pattern generation, enable Test Mode using bit[1] of the Test and Scan Register (0x3D). Then load all parameters for the desired test pattern into the registers, and set Pattern Enable bit of the Test Pattern Control Register (0x34). Changing pattern parameters after the Pattern Enable bit is set may result in undesired output. The pattern will start at the next leading edge of CLPIN.

#### Test Mode 0 - Fixed Pattern

This test mode provides an LVDS output with a fixed value output during the valid pixel region. The fixed value is set via the Test Pattern Value registers. The Test Pattern Value register is split into two registers the upper 6 bits of the test code in first register, and the lower 8 bits of the test code in the second.



#### Test Mode 1 - Horizontal Gradient

This mode provides LVDS data that progresses horizontally from dark to light output values. This mode is highly variable, allowing control over the starting value of the gradient, the width of the gradient, and the increment rate of the gradient. The starting value can be set in the Test Pattern Value register, the width (in number of pixels) of each gradient step is set via Test Pattern Pitch register, and increment rate (in LSBs) is set via the Test Pattern Step register. When the LVDS Horizontal Gradient test pattern is selected, the ramp begins immediately and counts to the maximum value, and then repeats throughout the entire Valid Pixel region.

#### Test Mode 2 - Vertical Gradient

This mode is similar to the Horizontal Gradient, only the gradient is in the vertical direction. See the Horizontal Gradient mode description for details.

#### Test Mode 3 - Lattice Pattern

This mode provides LVDS data that creates a lattice grid. The lattice is made of dark lines on a light background. The line output value is set by Test Pattern Step register, and background value is set by Test Pattern Value register. The number of pixels & lines in the lattice is set via Test Pattern Pitch register.

### Test Mode 4 - Stripe Pattern

This mode provides LVDS data that creates a vertical stripe pattern. The stripe pattern is made of dark and light lines. The output value of the dark portion is set via Test Pattern Step register, and the light portion is set via Test Pattern Value register. The stripe width in pixels is set via Test Pattern Pitch register.

### Test Mode 5 - LVDS Test Pattern (Synchronous)

This mode provides an LVDS output with a fixed value repeated continuously. The pattern starts at the leading edge of CLPIN. The fixed value is set via the Test Pattern Value registers. The Test Pattern Value register is split into two registers the upper 8 bits of the test code in first register, and the lower 8 bits of the test code in the second. This is useful for system debugging of the LVDS link and receiver circuitry.

#### Test Mode 6 - LVDS Test Pattern (Asynchronous)

This mode provides an LVDS output with a fixed value repeated continuously. The pattern starts asynchronously without CLPIN. The fixed value is set via the Test Pattern Value registers. The Test Pattern Value register is split into two registers the upper 8 bits of the test code in first register, and the lower 8 bits of the test code in the second. This is useful for system debugging of the LVDS link and receiver circuitry.

#### Pseudo Random Number Mode

This mode provides LVDS data produced from the following polynomial:

$$P(x) = X^{14} + X^{13} + X^{11} + X^9 + 1$$

To start the Pseudo Random Number mode, set the Test Mode bit of the Test and Scan Register. Then load the seed value in the Test Pattern Value register, and set the Pseudo Random Enable bit of the Test Pattern Control register. The pattern will start outputting after the next leading edge of CLPIN.

## **Clock Receiver**

A differential clock receiver is used to generate all clock signals on the LM98640QML. The clock input should be externally terminated with 100 Ohms between the input clock pins. The clock may be DC or AC coupled to the AFE.

## **Power Trimming**

The LM98640QML provides an adaptive power scaling feature that allows the user to optimize power consumption based on the maximum operating frequency and the maximum amount of gain required. The power scaling mode is selectable through the PGA Power Trimming and ADC Power Trimming registers (0x02,0x03). The settings in these registers are common for both channels PGA and ADC. Using these registers the user can control the current of the two stages of the PGA, and the current for the two levels of the ADC. The following table provides a set of baseline configurations for various operating frequencies and gain ranges.

Operating Frequency	1-4x Max PGA Gain	1-8x Max PGA Gain
5 - 15 MSPS	PGA Power Trimming = 0x00 ADC Power Trimming = 0x00	PGA Power Trimming = 0x01 ADC Power Trimming = 0x00
15 - 25 MSPS	PGA Power Trimming = 0x01 ADC Power Trimming = 0x00	PGA Power Trimming = 0x09 ADC Power Trimming = 0x00
25 - 40 MSPS	PGA Power Trimming = 0x01 ADC Power Trimming = 0x08	PGA Power Trimming = 0x09 ADC Power Trimming = 0x08

These configurations should be treated as baseline values and can be tuned to your specific application.

## Powerdown Modes

The LM98640QML provides several ways to save power when the device is not in normal usage mode. Using the Powerdown Control Register (0x01) the part can be placed into Powerdown Mode, or Single Channel Mode. In Powerdown Mode (Powerdown Control, bit[7]) the following blocks are placed in a Powerdown mode: VCLP, Channel 1 & 2 Reference Buffers, Channel 1 & 2 PGA OpAmps, and Channel 1 & 2 Amplifiers. Powerdown Mode will override all other Powerdown Control Register bits. To place the part in Single Channel Mode each block of the unused channel can be powered down using their respective control bits (Powerdown Control, bits[5:0]). If an external reference clamp is used the VCLP block can be powered down during any Power mode. For applications operating at a low enough frequency additional power can be saved by powering down one channel reference buffer, then externally tie both channel's reference pins together.

## **Serial Interface**

A serial interface is used to write and read the configuration registers. The interface is a four wire interface using SCLK, SEN, SDI, and SDO connections. The serial interface clock (SCLK) must be less than the main input clock (INCLK) for INCLK speeds of less than 20MHz, for INCLK speeds greater than 20MHz SCLK must remain below 20MHz. The main input clock (INCLK) to the LM98640QML must be active during all Serial Interface commands. The Serial Interface pins are high impedance while SEN is high, this allows multiple slave devices to be used with a single master device.

After power-up, the configuration registers must be written with the baseline values, using the serial interface, to place the part in a valid state.

## Writing to the Serial Registers

To write to the serial registers using the four wire interface, the timing diagram shown in Figure 28 must be met. First, SEN is toggled low. At the rising edge of the first clock, the master should assume control of the SDI pin and begin issuing the write command. The write command is built of a "write" bit (0), device address bit (0), six bit register address, and eight bit register value to be written. SDI is clocked into the LM98640QML at the rising edge of SCLK. The LM98640QML assumes control of the SDO pin during the first eight clocks of the cycle. During this period, data is clocked out of the device at the rising edge of SCLK. The eight bit value clocked out is the contents of the previously addressed register, regardless if the previous command was a read or a write. When SEN toggles high, the register is written to, and the LM98640QML now functions with this new data.

## **Reading the Serial Registers**

To read to the serial registers using the four wire interface, the timing diagram shown in Figure 29 must be met. Reading the registers takes two cycles. To start the first cycle, SEN is toggled low. At the rising edge of the first clock, the master should assume control of the SDI pin and begin issuing the read command. The read command is built of a "read" bit (1), device address bit (0), six bit register address, and eight "don't care" bits. SDI is clocked into the LM98640QML at the rising edge of SCLK. SEN is toggled high for a delay of at least  $t_{SENW}$  (see Figure 30). The second cycle begins when SEN is toggled low. The LM98640QML assumes control of the SDO pin during the first eight clocks of the cycle. During this period, data is clocked out of the device at the rising edge of SCLK. The eight bit value clocked out is the contents of the previously addressed register. The next command can be sent on the SDI pin simultaneously during this second cycle. When SEN toggles high, the register is not written to, but its contents are staged to be outputted at the beginning of the next command. Texas

**INSTRUMENTS** 







## Serial Interface Timing Details





## Supply/Grounding, Layout and Thermal Recommendations

## **Power Planes**

Power for the LM98640QML should be provided through a broad plane which is located on one layer adjacent to the ground plane(s). Placing the power and ground planes on adjacent layers will provide low impedance decoupling of the AFE supplies, especially at higher frequencies. The output of a linear regulator should feed into the power plane through a low impedance multi-via connection. The power plane should be split into individual power peninsulas near the AFE. Each peninsula should feed a particular power bus on the AFE, with decoupling for that power bus connecting the peninsula to the ground plane near each power/ground pin pair. Using this technique can be difficult on many printed circuit CAD tools. To work around this, zero ohm resistors can be used to connect the power source net to the individual nets for the different AFE power buses. As a final step, the zero ohm resistors can be removed and the plane and peninsulas can be connected manually after all other error checking is completed.

## **Bypass Capacitors**

The general recommendation is to have one 100nF capacitor for each power/ground pin pair. The capacitors should be surface mount multi-layer ceramic chip capacitors.

## Ground Plane

Grounding should be done using continuous full ground planes to minimize the impedance for all ground return paths, and provide the shortest possible image/return path for all signal traces.

## Thermal Management

The exposed pad on bottom of the package is attached to the back of the die to act as a heat sink. Connecting this pad to the PCB ground planes with a low thermal resistance path is the best way to remove heat from the AFE. This pad should also be connected to the ground planes through low impedance path for electrical purposes.

## **Radiation Environments**

Careful consideration should be given to environmental conditions when using a product in a radiation environment.

## Total Ionizing Dose

Testing and qualification of this product is done on a wafer level according to MIL-STD-883, Test Method 1019. Wafer level TID data is available with lot shipments.

## Single Event Latch-Up and Functional Interrupt

One time single event latch-up (SEL) and single event functional interrupt (SEFI) testing was preformed according to EIA/JEDEC Standard, EIA/JEDEC57. SEL testing was conducted with the junction temperature at 125°C. The linear energy transfer threshold (LETth) shown in the Key Specifications table on the front page is the maximum LET tested. A test report is available upon request.

## Single Event Effects

A report on single event upset (SEU) is available upon request.



## LM98640QML-SP

SNAS461C - MAY 2010 - REVISED APRIL 2013

www.ti.com

## Table 5. Configuration Registers

	Registers need to be written with baseline values after power-up to place part in a valid state.									
Address	Register Title	Baseline				Register/Bit	Description			
(Binary)	(Mnemonic)	(Binary)	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Analog C	onfiguration									
00 0000	Main Configuration	0000 0100	Not Used	Coarse DAC Enable	Fine DAC Enable	Reserved	CLPIN Gating Enable	CDS Gain Enable	Reserved	CDS Enable
00 0001	Powerdown Control	0000 0000	Master Powerdown	VCLP Powerdown	Ch2 Ref Buf Powerdown	Ch1 Ref Buf Powerdown	Ch2 PGA Powerdown	Ch1 PGA Powerdown	Ch2 ADC Powerdown	Ch1 ADC Powerdown
00 0010	PGA Power Trimming	0010 0100	Rese	erved	PGA Stage	e 2 Bias Currer	nt Trimming	PGA Stage	e 1 Bias Currer	nt Trimming
00 0011	ADC Power Trimming	0101 1011	Rese	erved	ADC	Current Trimm	ning 2	ADC	Current Trimm	ning 1
00 0100	VCLP Control	0111 0100	Not Used	Buffer Enable	VCLP Enable		VC	CLP Voltage Le	vel	
00 0101	LVDS Output Modes	0000 1110	Clear	Reserved	Reserved	Reserved	Quad Lane Enable	LVDS Enable	LVDS	Control
00 0110	Sample & Hold	1000 0001	S/H Enable		Not	Used		Ref Buf P	ower Level	Reserved
00 0111	Status	0000 0000				Not Used				False Lock
00 1000	Reserved	0000 0000				Rese	erved			
00 1001	Clock Monitor	0000 0000		Not Used		Enable	Select		Not Used	
00 1010	Reserved	0000 0000				Not	Used			
00 1011	Reserved	0000 0000				Not	Used			
00 1100	Reserved	0000 0000				Not	Used			
00 1101	Reserved	0000 0000				Not	Used			
00 1110	Reserved	0000 0000				Not	Used			
00 1111	Reserved	0000 0000	00 Not Used							
Gain & O	ffset DAC Configura	tion								
01 0000	CDAC1	0000 0000				Not Used				Offset bit 8
01 0001	CDAC1	1111 1111				Offset Val	ue bits 7:0			
01 0010	FDAC1	0000 0000				Not Used				Offset bit 8
01 0011	FDAC1	1111 1111				Offset Val	ue bits 7:0			
01 0100	Reserved	0000 0000				Not	Used			
01 0101	PGA1	0110 0001				PGA Ga	iin Value			
01 0110	Reserved	0000 0000				Not	Used			
01 0111	Reserved	0000 0000				Not	Used			1
01 1000	CDAC2	0000 0000				Not Used				Offset Bit 8
01 1001	CDAC2	1111 1111				Offset Val	ue bits 7:0			1
01 1010	FDAC2	0000 0000				Not Used				Offset Bit 8
01 1011	FDAC2	1111 1111				Offset Val	ue bits 7:0			
01 1100	PGA2	0110 0001				PGA Ga	in Value			
01 1101	Reserved	0000 0000				Not	Used			
01 1110	Reserved	0000 0000				Not	Used			
01 1111	Reserved	0000 0000				Not	Used			
Timing C	onfiguration	[			1					
10 0000	Clamp Start	0000 1000	Not	Used			Clamp S	tart Index		
10 0001	Clamp End	0001 1100	Not	Used			Clamp E	nd Index		
10 0010	Sample Start	0010 1000	Not	Used			Sample S	Start Index		
10 0011	Sample End	0011 1100	Not	Used			Sample E	End Index		
10 0100	Reserved	0011 0100		1		Rese	erved			
10 0101	INCLK Range	0000 0010	Not Used		INCLK Range		Not	Used	Rese	erved
10 0110	Reserved	0000 0000				Not	Used			
10 0111	Reserved	0000 0000				Not	Used			
10 1000	DLL Configuration	0000 1111				Reserved				DLL Reset
10 1001	Reserved	0000 0000				Not	Used			



#### SNAS461C - MAY 2010 - REVISED APRIL 2013

## Table 5. Configuration Registers (continued)

Registers need to be written with baseline values after power-up to place part in a valid state.											
Address	Register Title	Baseline	Register/Bit Description								
(Binary)	(Mnemonic)	(Binary)	Bit 7	Bit 7 Bit 6 Bit 5 Bit				Bit 2	Bit 1	Bit 0	
10 1010	Reserved	0000 0000				Not	Used				
10 1011	Reserved	0000 0000				Not	Used				
10 1100	Reserved	0000 0000				Not	Used				
10 1101	Reserved	0000 0000				Not	Used				
10 1110	Reserved	0000 0000				Not	Used				
10 1111	Reserved	0000 0000				Not	Used				
Digital Co	Digital Configuration Registers										
11 0000	Test Pattern Start	0000 0000		Start Upper Bits							
11 0001	Test Pattern Start	0000 0000				Start Lo	ower Bits				
11 0010	Test Pattern Width	0000 0000		Width Upper Bits							
11 0011	Test Pattern Width	0000 0000	Width Lower Bits								
11 0100	Test Pattern Control	0000 0000	Pattern Pattern Mode				Pseudo Random Enable	Seed Enable	Pattern Out	put Channel	
11 0101	Test Pattern Pitch	0000 0000				Test Pat	tern Pitch				
11 0110	Test Pattern Step	0000 0000				Test Pattern	n Step Code				
11 0111	Test Pattern Channel Offset	0000 0000		Not	Used			Test Pattern (	Channel Offset		
11 1000	Test Pattern Value	0000 0000				Pattern L	Jpper Bits				
11 1001	Test Pattern Value	0000 0000				Pattern L	ower Bits				
11 1010	Reserved	0000 0000				Not	Used				
11 1011	Reserved	0000 0000				Not	Used				
11 1100	Digital Configuration	0000 0000				Not Used				Auto Read	
11 1101	Test & Scan Control	0000 0000	Not U	Jsed	Pattern Voting Enable	U-Wire Voting Enable	Not Used	Test Reset	Test Mode	Not Used	
11 1110	Device ID	0000 0001				Device R	evision ID				
11 1111	Reserved	0000 0000				Not	Used				



### www.ti.com

## **Register Definitions**

## Table 6. Register Definitions - Analog Configuration

Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description		
00 0000	Main Configuration	0000 0100	[7:0]	Main Configuration		
			[7]	Not Used		
			[6]	Coarse DAC Enable		
				0 Disable		
				1 Enable		
			[5]	Fine DAC Enable		
				0 Disable		
				1 Enable		
			[4]	Reserved		
			[3]	CLPIN Gating Enable		
				0 CLPIN not gated by CLAMP		
				1 CLPIN gated by CLAMP (=logical "and" of CLPIN and CLAMP)		
			[2]	Gain Mode Select. Selects either a 1x or 2x gain mode in the CDS/Sample/Hold Block		
				0 1x Gain in the CDS/Sample/Hold Block		
				1 2x Gain in the CDS/Sample/Hold Block		
			[1]	Reserved. Set to 0.		
			[0]	CDS / Sample/Hold Mode select.		
				0 Disabled. Correlated Double Sample Mode disabled.		
				1 Enabled. Correlated Double Sample Mode enabled.		

## 38 Submit Documentation Feedback

Copyright © 2010–2013, Texas Instruments Incorporated

LM98640QML-SP

## Table 6. Register Definitions - Analog Configuration (continued)

Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description		
00 0001	Powerdown Control	0000 0000	[7:0]	Powerdown Control Register		
			[7]	Master Powerdown		
				0 Fully Powered.		
				1 Powerdown Mode. Over rides bits [6:0].		
			[6]	VCLP Powerdown		
				0 VCLP Fully Powered.		
				1 VCLP Powerdown Mode.		
			[5]	Channel 2 Reference Buffer Powerdown		
				0 Reference Buffer Fully Powered.		
				1 Reference Buffer Powerdown Mode.		
			[4]	Channel 1 Reference Buffer Powerdown		
				0 Reference Buffer Fully Powered.		
				1 Reference Buffer Powerdown Mode.		
			[3]	Channel 2 PGA Powerdown		
				0 OpAmp Fully Powered.		
				1 OpAmp Powerdown Mode.		
			[2]	Channel 1 PGA Powerdown		
				0 OpAmp Fully Powered.		
				1 OpAmp Powerdown Mode.		
			[1]	Channel 2 ADC Powerdown		
				0 Amplifier Fully Powered.		
				1 Amplifier Powerdown Mode.		
			[0]	Channel 1 ADC Powerdown		
				0 ADC Fully Powered.		
				1 ADC Powerdown Mode.		
00 0010	PGA Power Trimming	0010 0100	[7:0]	PGA Power Trimming Register.		
			[7:6]	Not Used		
			[5:3]	PGA Stage 1 Current Trimming		
				Tunable between 000-Weak to 111-Strong (Default 100)		
			[2:0]	PGA Stage 2 Current Trimming		
				Tunable between 000-Weak to 111-Strong (Default 100)		



www.ti.com



## SNAS461C - MAY 2010 - REVISED APRIL 2013

## Table 6. Register Definitions - Analog Configuration (continued)

	Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description			
00 0011	ADC Power Trimming	0101 1011	[7:0]	ADC Power Trimming Register.			
			[7:6]	Reserved. Set to 2'b01.			
			[5:3]	ADC Current Trimming 2(Not Binary Weighted)			
				000 25% Power			
				<b>001</b> 50% Power			
				011 75% Power (Default)			
				<b>111</b> 100% Power			
			[2:0]	ADC Current Trimming 1 (Not Binary Weighted)			
				000 25% Power			
				<b>001</b> 50% Power			
				011 75% Power (Default)			
				111 100% Power			
00 0100	VCLP Control	0111 0100	[7:0]	Voltage Clamp Buffer Control Register.			
			[7]	Not Used			
			[6]	Buffer Enable			
				<b>0</b> Disabled. Resistor Ladder is driving VCLP pin.			
				1 Enabled. Resistor Ladder is buffered to VCLP pin.			
			[5]	VCLP Enable			
				<b>0</b> Disabled. VCLP pin can be externally driven.			
				1 Enabled. VCLP pin is in output mode.			
			[4:0]	Voltage Level of VCLP pin.			
				VCLP range is 200mV to 3.1V in 100mV steps for (binary) settings 00000 to 11101. Settings 11110 and 11111 are not used.			
00 0101	LVDS Output Modes	0000 1110	[7:0]	LVDS Output Configuration Register.			
			[7]	Serializer Data Reset. (Not self-clearing)			
			[6:4]	Not Used.			
			[3]	LVDS Output Mode			
				0 Dual Lane Mode (see Output Mode 1 - Dual Lane)			
				1 Quad Lane Mode (see Output Mode 2 - Quad Lane)			
			[2]	LVDS Driver Enable.			
				0 LVDS Drivers Disabled			
				1 LVDS Drivers Enabled			
				(Note: In Dual Lane Mode TX0 and TX3 are disabled regardless of driver enable)			
			[1:0]	LVDS Amplitude and Common Mode Voltage.			
				00 250mV (1.2V DC Offset)			
				01 300mV (1.2V DC Offset)			
				10 350mV (1.1V DC Offset)			
				11 400mV (1.1V DC Offset)			

TEXAS INSTRUMENTS

SNAS461C - MAY 2010 - REVISED APRIL 2013

www.ti.com

## Table 6. Register Definitions - Analog Configuration (continued)

	Registers need to be written with baseline values after power-up to place part in a valid state.					
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description		
00 0110	Sample & Hold	1000 0001	[7:0]	Sample & Hold Mode Register		
			[7]	Sample & Hold Mode Enable		
				0 Disabled.		
				1 Enabled.		
			[6:3]	Not Used.		
			[2:1]	Reference Buffer Power Level		
				<b>11</b> 100% Power. Used for $F_{INCLK} = 20-40MHz$ .		
				<b>10</b> 60% Power. Used for $F_{INCLK}$ = 10-20MHz.		
				<b>01</b> 60% Power. Used for $F_{INCLK} = 10-20MHz$ .		
				<b>00</b> 30% Power. Used for $F_{INCLK} = 5-10MHz$ .		
			[0]	Reserved.		
00 0111	Status	0000 0000	[7:0]	Status Register. (Read Only)		
			[7:1]	Not Used.		
			[0]	False Lock Detect.		
				Indicates if DLL is locked into a half frequency state.		
00 1001	Clock Monitor	0000 0000	[7:0]	Internal Clock Signal Monitor Register		
			[7:5]	Not Used.		
			[4:3]	Enable and select clocks to be monitored on the Digital Timing Monitor. (DTM)		
				00 Disable Digital Timing Monitor Pins (DTM0, DTM1)		
				<b>01</b> Send CLAMP <sub>EVEN</sub> to DTM0 pin, and SAMPLE <sub>EVEN</sub> to DTM1		
				10 Send CLAMP <sub>ODD</sub> to DTM0 pin, and SAMPLE <sub>ODD</sub> to DTM1		
				11 Send ODD tag and ADC Clock to the DTM.		
			[2:0]	Reserved. Set to 000.		

## Table 7. Register Definitions - GAIN & Offset DAC Configuration

	Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description			
01 0000	CDAC1	0000 0000	[7:0]	Channel 1 Coarse DAC Register.			
			[7:1]	Not Used.			
			[0]	Bit 8 of Channel 1 Coarse DAC Offset Value.			
01 0001	CDAC1	1111 1111	[7:0]	Channel 1 Coarse DAC Offset Value bits 7:0.			
01 0010	FDAC1	0000 0000	[7:0]	Channel 1 Fine DAC Register.			
			[7:1]	Not Used.			
			[0]	Bit 8 of Channel 1 Fine DAC Offset Value.			
01 0011	FDAC1	1111 1111	[7:0]	Channel 1 Fine DAC Offset Value bits 7:0.			
01 0101	PGA1	0110 0001	[7:0]	Channel 1 Programmable Gain Amplifier Value.			
01 1000	CDAC2	0000 0000	[7:0]	Channel 2 Coarse DAC Register.			
			[7:1]	Not Used.			
			[0]	Bit 8 of Channel 2 Coarse DAC Offset Value.			
01 1001	CDAC2	1111 1111	[7:0]	Channel 2 Coarse DAC Offset Value bits 7:0.			



SNAS461C - MAY 2010 - REVISED APRIL 2013

## Table 7. Register Definitions - GAIN & Offset DAC Configuration (continued)

Registers need to be written with baseline values after power-up to place part in a valid state.							
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description			
01 1010	FDAC2	0000 0000	[7:0] Channel 2 Fine DAC Register.				
			[7:1]	Not Used.			
			[0]	Bit 8 of Channel 2 Fine DAC Offset Value.			
01 1011	FDAC2	1111 1111	[7:0]	Channel 2 Fine DAC Offset Value bits 7:0.			
01 1100	PGA2	0110 0001	[7:0]	0] Channel 2 Programmable Gain Amplifier Value.			

### Table 8. Register Definitions - Timing Configuration

	Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description			
10 0000	Clamp Start	0000 1000	[7:0]	Clamp Start Register.			
			[7:6]	Not Used.			
			[5:0]	CLAMP Starting Index. 0-63d position for rising edge of CLAMP signal. Valid only in CDS Mode.			
10 0001	Clamp End	0001 1100	[7:0]	Clamp End Register.			
			[7:6]	Not Used.			
			[5:0]	CLAMP End Index. 0-63d position for falling edge of CLAMP signal. Valid only in CDS Mode.			
10 0010	Sample Start	0010 1000	[7:0]	Sample Start Register.			
			[7:6]	Not Used.			
			[5:0]	SAMPLE starting Index. 0-63d position for rising edge of SAMPLE signal.			
10 0011	Sample End	0011 1100	[7:0]	Sample End Register.			
			[7:6]	Not Used.			
			[5:0]	SAMPLE End Index. 0-63d position for falling edge of SAMPLE signal.			
10 0101	INCLK Range	0000 0010	[7:0]	INCLK Range Register.			
			[7]	Not Used.			
			[6:4]	INCLK Range.			
				000 25-40MHz Operation			
				001 14-25MHz Operation			
				010 10-14MHz Operation			
				011 7.5-10MHz Operation			
				100 6-7.5MHz Operation			
				101 5-6MHz Operation			
				110 Not Used			
				111 Not Used			
			[3:2]	Not Used.			
			[1:0]	DLL Range			
				11 Reserved			
				10 14-40MHz Operation			
				01 7.5-14MHz Operation			
				00 5 -7.5MHz Operation			

٦

#### SNAS461C - MAY 2010 - REVISED APRIL 2013

## Table 8. Register Definitions - Timing Configuration (continued)

### Registers need to be written with baseline values after power-up to place part in a valid state

Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description		
10 1000	DLL Configuration	0000 1111	[7:0]	DLL Configuration Register		
			[7:1]	Reserved		
			[0]	DLL Reset. (Self Clearing)		

### Table 9. Register Definitions - Digital Configuration

Registers need to be written with baseline values after power-up to place part in a valid state.						
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description		
11 0000	Test Pattern Start	0000 0000	[15:8]	Upper 8 bits of the Test Pattern start value. Specifies the number of pixels after the leading edge of CLPIN to the Valid Pixel region.		
11 0001	Test Pattern Start	0000 0000	[7:0]	Lower 8 bits of the Test Pattern start value. Specifies the number of pixels after the leading edge of CLPIN to the Valid Pixel region.		
11 0010	Test Pattern Width	0000 0000	[15:8]	Upper 8 bits of the Test Pattern Width value. Specifies, in number of pixels, the width of the Valid Pixel region.		
11 0011	Test Pattern Width	0000 0000	[7:0]	Lower 8 bits of the Test Pattern Width value. Specifies, in number of pixels, the width of the Valid Pixel region.		
11 0100	Test Pattern Control	0000 0000	[7:0]	Test Pattern Control Register.		
			[7]	Programmable Pattern Switch		
				<b>0</b> Disabled. Normal LVDS output operation.		
				1 Enabled. AFE outputs LVDS test patterns.		
			[6:4]	Test Pattern Mode		
			1- 1	000 Fixed Code		
				001 Horizontal Gradient Scan (Main Scan)		
				010 Vertical Gradient Scan (Sub Scan)		
				011 Grid Scan (Lattice Pattern)		
				100 Strip Pattern		
				101 LVDS Test Pattern. (Synchronous to CLPIN)		
				110   VDS Test Pattern, (Asynchronous)		
				111 Not Used.		
			[3]	Pseudo Random Pattern Enable.		
				Overrides Programmable Patter Switch setting (bit 7). Normally only one should be on.		
			[2]	Load Seed Enable.		
				When set, the seed value in the Test Pattern Value Register is loaded in the LFSR at the leading edge of CLPIN.		
			[1:0]	Test Pattern Output Channel Select.		
				00 Both Channels		
				01 Channel 1		
				10 Channel 2		
				11 Not Used		
11 0101	Test Pattern Pitch	0000 0000	[7:0]	Test Pattern pitch, specifies number of pixels for H Gradient pattern and Stripe pattern, or number of lines in the V Gradient pattern, or specifies pixels & lines in the Lattice pattern.		
11 0110	Test Pattern Step	0000 0000	[7:0]	Test Pattern Step Code. Specifies step size in LSB codes the pattern is incremented in H Gradient and V Gradient pattern. In Lattice and Stripe pattern it specifies the code during the lower step.		



#### SNAS461C - MAY 2010 - REVISED APRIL 2013

## Table 9. Register Definitions - Digital Configuration (continued)

Registers need to be written with baseline values after power-up to place part in a valid state.					
Address (Binary)	Register Title	Baseline (Binary)	Bit(s)	Description	
11 0111	Test Pattern Channel	0000 0000	[7:0]	Test Pattern Channel Offset Register.	
	Oliset		[7:4]	Not Used.	
			[3:0]	Test Pattern Channel Offset. This specifies the number of lines the pattern on Channel 2 is delayed from Channel 1. This offset is maintained throughout the pattern.	
11 1000	Test Pattern Value	0000 0000	[15:8]	Upper 8 bits of Test Pattern Value Register. Specifies the upper 8 bits of the test value code during Fixed Pattern and LVDS test, initial value during H Gradient & V Gradient pattern, and higher value in the Lattice and Stripe Pattern.	
11 1001	Test Pattern Value	0000 0000	[7:0]	Lower 6 bits of Test Pattern Value Register. Specifies the lower 6 bits of the test code value during Fixed Pattern and LVDS test, initial value during H Gradient & V Gradient pattern, and higher value in the Lattice and Stripe Pattern.	
11 1100	Digital Configuration	0000 0000	[7:0]	Serial Communication Configuration Register.	
			[7:1]	Not Used.	
			[0]	Micro-Wire Automatic Read Disable.	
				<b>0</b> Read data is always sent out on SDO during the first 8 SCLK cycles.	
				The register is selected by the register address in the previous cycle. (read or write)	
				1 Automatic read is disabled.	
				To read from a register two cycles need to be initiated by the master, first cycle should be a read with the correct register address and second can be a dummy read or read from another address or a write cycle, and the data is sent first 8 SCLK of the second cycle. After a write command SDO remains in Tri-State during first 8 SCLK.	
11 1101	Test & Scan Control	0000 0000	[7:0]	Test & Scan Control Register	
			[7:6]	Not Used.	
			[5]	Test Pattern Voting Switch.	
				<b>0</b> Enable. Circuit Redundancy Voting is active.	
				1 Disable. First redundancy block output is used.	
			[4]	Micro-wire Voting Switch.	
				<b>0</b> Enable. Circuit Redundancy Voting is active.	
				1 Disable. First Micro-wire block output is used.	
			[3]	Not Used.	
			[2]	Test Reset. Resets the test block when High, normal test block function when Low. This bit is not self-clearing.	
			[1]	Test Mode Enable.	
				0 Disable.	
				1 Enable. Needed to run Test Pattern functions.	
			[0]	Not Used.	
11 1110	Device ID	0000 0001	[7:0]	Device Revision ID.	



## **Revision History**

Date Released	Revision	Section	Changes
5/10/2010	A	Initial Release	New Product Initial Release
1/13/2011	В	Abs Max & Elec. Tables	Changed Thermal Res. Unit of measure & Tjc Limit
4/16/2013	С	-	Changed layout of National Data Sheet to TI format



16-Apr-2013

## **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Top-Side Markings	Samples
	(1)		Drawing		Qty	(2)		(3)		(4)	
LM98640W-MLS	ACTIVE	CFP	NBB	68		Green (RoHS & no Sb/Br)	NIAU	Level-1-NA-UNLIM	-55 to 125	LM98640W-MLS	Samples
LM98640W-MPR	ACTIVE	CFP	NBB	68		Green (RoHS & no Sb/Br)	NIAU	Level-1-NA-UNLIM	25	LM98640W-MPR ES	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# **MECHANICAL DATA**

# NBB0068D





#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products		Applications				
Audio	www.ti.com/audio	Automotive and Transportation	www.ti.com/automotive			
Amplifiers	amplifier.ti.com	Communications and Telecom	www.ti.com/communications			
Data Converters	dataconverter.ti.com	Computers and Peripherals	www.ti.com/computers			
DLP® Products	www.dlp.com	Consumer Electronics	www.ti.com/consumer-apps			
DSP	dsp.ti.com	Energy and Lighting	www.ti.com/energy			
Clocks and Timers	www.ti.com/clocks	Industrial	www.ti.com/industrial			
Interface	interface.ti.com	Medical	www.ti.com/medical			
Logic	logic.ti.com	Security	www.ti.com/security			
Power Mgmt	power.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense			
Microcontrollers	microcontroller.ti.com	Video and Imaging	www.ti.com/video			
RFID	www.ti-rfid.com					
OMAP Applications Processors	www.ti.com/omap	TI E2E Community	e2e.ti.com			
Wireless Connectivity	www.ti.com/wirelessconr	elessconnectivity				

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2013, Texas Instruments Incorporated