CLC5622

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SNOS907D - AUGUST 2000 - REVISED APRIL 2013

# **Dual, High Output, Video Amplifier**

Check for Samples: CLC5622

#### **FEATURES**

- 130mA Output Current
- 0.05%, 0.03° Differential Gain, Phase
- 3.0mA/ch Supply Current
- 160MHz Bandwidth  $(A_V = +2)$
- -90/-97dBc HD2/HD3 (1MHz)
- 18ns Settling to 0.05%
- 370V/µs Slew Rate
- Stable for Capacitive Loads up to 1000pf
- Single 5V or ±5V Supplies

#### **APPLICATIONS**

- Video Line Driver
- ADSL/HDSL Driver
- Coaxial Cable Driver
- UTP Differential Line Driver
- Transformer/coil Driver
- High Capacitive Load Driver
- Portable/Battery Powered Applications
- Differential A/D Driver

#### DESCRIPTION

The CLC5622 has a new output stage that delivers high output drive current (130mA), but consumes minimal quiescent supply current (3.0mA/ch) from a single 5V supply. Its current feedback architecture, fabricated in an advanced complementary bipolar process, maintains consistent performance over a wide range of gains and signal levels, and has a linear phase response up to one half of the -3dB frequency.

The CLC5622 offers 0.1dB gain flatness to 30MHz and differential gain and phase errors of 0.05% and 0.02°. These features are ideal for professional and consumer video applications.

The CLC5622 offers superior dynamic performance with a 160MHz small-signal bandwidth, 370V/µs slew rate and 4.4ns rise/fall times (2V<sub>STEP</sub>). The combination of low quiescent power, high output current drive, and high speed performance make the CLC5622 well suited for many battery powered personal communication/computing systems.

The ability to drive low impedance, highly capacitive loads, makes the CLC5622 ideal for single ended cable applications. It also drives low impedance loads with minimum distortion. The CLC5622 will drive a  $100\Omega$  load with only -95/-95 dBc second/third harmonic distortion (A $_{\rm V}$  = +2, V $_{\rm OUT}$  = 2V $_{\rm PP}$ , f = 1MHz). With a  $25\Omega$  load, and the same conditions, it produces only -72/-77 dBc second/third harmonic distortion.

The CLC5622 can also be used for driving differential-input step-up transformers for applications such as Asynchronous Digital Subscriber Lines (ADSL) or High-Bit-Rate Digital Subscriber Lines (HDSL).

When driving the input of high resolution A/D converters, the CLC5622 provides excellent -90/-97dBc second/third harmonic distortion (A<sub>V</sub> = +2, V<sub>OUT</sub> = 2V<sub>PP</sub>, f = 1MHz, R<sub>L</sub> = 1k $\Omega$ ) and fast settling time.

M

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



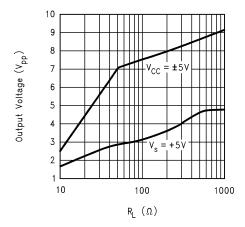
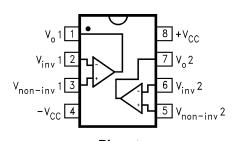


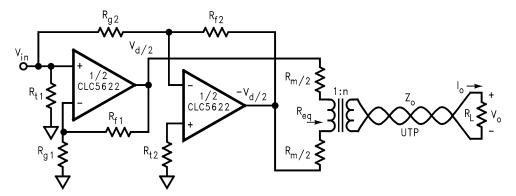
Figure 1. Maximum Output Voltage vs. R<sub>L</sub>

#### **CONNECTION DIAGRAM**



Pinout PDIP & SOIC See Package Numbers P and D

#### TYPICAL APPLICATION



**Differential Line Driver with Load Impedance Conversion** 



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.



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## **ABSOLUTE MAXIMUM RATINGS**(1)(2)

Supply Voltage (V <sub>CC</sub> -V <sub>EE</sub> )	+14V
Output Current (See (3))	140mA
Common-Mode Input Voltage	V <sub>EE</sub> to V <sub>CC</sub>
Maximum Junction Temperature	+150°C
Storage Temperature Range	−65 to +150°C
Lead Temperature (soldering 10 sec)	+300°C
ESD (Human Body Model)	1000V

- (1) "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be ensured. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
- (3) The short circuit current can exceed the maximum safe output current

#### **OPERATING RATINGS**

Thermal Resistance		
Package	$(\theta_{ m JC})$	$( heta_{JA})$
PDIP	65°C/W	130°C/W
SOIC	50°C/W	145°C/W

#### +5V ELECTRICAL CHARACTERISTICS

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_S = +5V^{(1)}, V_{CM} = V_{EE} + (V_S/2), RL$  tied to  $V_{CM}$ , unless specified

Symbol	Parameter	Conditions	Тур	Min/Max Ratings <sup>(2)</sup>		s <sup>(2)</sup>	Units
Ambient T	Temperature Temperature	CLC5622IN/IM	+25°C	+25°C	0 to 70°C	−40 to 85°C	
Frequenc	y Domain Response						
	-3dB Bandwidth	$V_O = 0.5V_{PP}$	130	100	90	85	MHz
		$V_O = 2.0V_{PP}$	95	80	77	75	MHz
	-0.1dB Bandwidth	$V_O = 0.5V_{PP}$	30	25	20	20	MHz
	Gain Peaking	$<200MHz, V_O = 0.5V_{PP}$	0	0.5	0.9	1.3	dB
	Gain Rolloff	$<30MHz, V_O = 0.5V_{PP}$	0.1	0.4	0.6	0.6	dB
	Linear Phase Deviation	$<30MHz, V_O = 0.5V_{PP}$	0.15	0.3	0.4	0.4	deg
	Differential Gain	NTSC, $R_L = 150\Omega$ to $-1V$	0.03	_	-	_	%
	Differential Phase	NTSC, $R_L = 150\Omega$ to $-1V$	0.07	_	_	_	deg
Time Don	nain Response						
	Rise and Fall Time	2V Step	4.5	6.0	6.4	6.8	ns
	Settling Time to 0.05%	1V Step	17	25	40	60	ns
	Overshoot	2V Step	11	15	18	18	%
	Slew Rate	2V Step	280	195	165	150	V/µs
Distortion	n And Noise Response						
	2nd Harmonic Distortion	2V <sub>PP</sub> ,1MHz	-79	-76	-73	-73	dBc
		$2V_{PP}$ ,1MHz; $R_L = 1k\Omega$	-80	-78	<b>-</b> 75	<del>-</del> 75	dBc
		2V <sub>PP</sub> ,5MHz	-66	-60	-58	-58	dBc
	3rd Harmonic Distortion	2V <sub>PP</sub> ,1MHz	-85	-82	-79	<del>-</del> 79	dBc
		$2V_{PP}$ ,1MHz; $R_L = 1k\Omega$	-83	-81	-78	<del>-</del> 78	dBc
		2V <sub>PP</sub> , 5MHz	-65	-62	-60	-60	dBc
	Equivalent Input Noise						
	Voltage (e <sub>ni</sub> )	>1MHz	3.4	4.4	4.9	4.9	nV/√Hz
	Non-Inverting Current (i <sub>bn</sub> )	>1MHz	6.3	8.2	9.0	9.0	pA/√Hz

<sup>(1)</sup>  $V_S = V_{CC} - V_{EE}$ 

<sup>2)</sup> Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

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## +5V ELECTRICAL CHARACTERISTICS (continued)

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_S = +5V^{(1)}, V_{CM} = V_{EE} + (V_S/2), RL \text{ tied to } V_{CM}, \text{ unless specified}$ 

Symbol	Parameter	Parameter Conditions Typ	Min	Min/Max Ratings (2)		Units	
	Inverting Current (i <sub>bn</sub> )	>1MHz	8.7	11.3	12.4	12.4	pA/√ <del>Hz</del>
	Crosstalk (Input Referred)	10MHz, 1V <sub>PP</sub>	-72	_	_	_	dB
Static, DO	Performance			•			
	Input Offset Voltage (3)		1	4	6	6	mV
	Average Drift		8	_	_	_	μV/°C
	Input Bias Current (Non-Inverting) (3)		6	18	22	24	μΑ
	Average Drift		40	_	_	_	nA/°C
	Input Bias Current (Inverting) (3)		6	14	16	17	μΑ
	Average Drift		25	_	_	_	nA/°C
	Power Supply Rejection Ratio	DC	48	45	43	43	dB
	Common Mode Rejection Ratio	DC	47	45	43	43	dB
	Supply Current (3)	R <sub>L</sub> = ∞	3.0	3.4	3.6	3.6	mA
Miscellan	eous Performance						
	Input Resistance (Non-Inverting)		0.36	0.26	0.23	0.23	МΩ
	Input Capacitance (Non-Inverting)		1.8	2.75	2.75	2.75	pF
	Input Voltage Range, High		4.2	4.1	4.1	4.0	V
	Input Voltage Range, Low		0.8	0.9	0.9	1.0	V
	Output Voltage Range, High	$R_L = 100\Omega$	4.0	3.9	3.9	3.8	V
	Output Voltage Range, Low	$R_L = 100\Omega$	1.0	1.1	1.1	1.2	V
	Output Voltage Range, High	R <sub>L</sub> = ∞	4.1	4.0	4.0	3.9	V
	Output Voltage Range, Low	R <sub>L</sub> = ∞	0.9	1.0	1.0	1.1	V
	Output Current (4)		100	80	65	40	mA
	Output Resistance, Closed Loop	DC	70	105	105	140	mΩ

#### ±5V ELECTRICAL CHARACTERISTICS

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_{CM} = \pm 5V, Unless Specified)$ 

Symbol	Parameter	Conditions	Тур	Min/Max Ratings <sup>(1)</sup>		Units	
Ambient T	emperature	CLC5622IN/IM	+25°C	+25°C	0 to 70°C	-40 to 85°C	
Frequenc	y Domain Response						
	-3dB Bandwidth	V <sub>O</sub> =1.0V <sub>PP</sub>	160	135	120	115	MHz
		V <sub>O</sub> =4.0V <sub>PP</sub>	75	60	57	55	MHz
	-0.1dB Bandwidth	V <sub>O</sub> =1.0V <sub>PP</sub>	30	25	20	20	MHz
	Gain Peaking	<200MHz, V <sub>O</sub> =1.0V <sub>PP</sub>	0	1.5	0.9	1.3	dB
	Gain Rolloff	<30MHz, V <sub>O</sub> =1.0V <sub>PP</sub>	0.1	0.2	0.3	0.3	dB
	Linear Phase Deviation	<30MHz, V <sub>O</sub> =1.0V <sub>PP</sub>	0.15	0.3	0.4	0.4	deg
	Differential Gain	NTSC, $R_L = 150\Omega$	0.05	0.06	_	_	%
	Differential Phase	NTSC, $R_L = 150\Omega$	0.03	0.06	_	_	deg
Time Don	nain Response	•					
	Rise and Fall Time	2V Step	4.4	5.8	6.2	6.8	ns
	Settling Time to 0.05%	2V Step	18	25	40	60	ns
	Overshoot	2V Step	19	21	23	24	%
	Slew Rate	2V Step	370	280	260	240	V/µs

<sup>(1)</sup> Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

AJ-level: spec. is 100% tested at +25°C. The short circuit current can exceed the maximum safe output current



# ±5V ELECTRICAL CHARACTERISTICS (continued)

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_{CM} = \pm 5V, Unless Specified)$ 

Symbol	Parameter	Conditions	Тур	Min	/Max Rating	gs <sup>(1)</sup>	Units
Distortion	n And Noise Response						
	2nd Harmonic Distortion	2V <sub>PP</sub> ,1MHz	-95	-88	-385	-385	dBc
		$2V_{PP}$ ,1MHz; $R_L$ =1 $k\Omega$	-90	-88	-85	-85	dBc
		2V <sub>PP</sub> ,5MHz	-74	-66	-64	-64	dBc
	3rd Harmonic Distortion	2V <sub>PP</sub> ,1MHz	-95	-91	-88	-88	dBc
		$2V_{PP}$ ,1MHz; $R_L = 1$ kΩ	-97	-93	-90	-90	dBc
		2V <sub>PP</sub> ,5MHz	-73	-64	-62	-62	dBc
	Equivalent Input Noise						
	Voltage (e <sub>ni</sub> )	>1MHz	3.4	4.4	4.9	4.9	nV/√Hz
	Non-Inverting Current (i <sub>bn</sub> )	>1MHz	6.3	8.2	9.0	9.0	pA/√ <del>Hz</del>
	Inverting Current (ibi)	>1MHz	8.7	11.3	12.4	12.4	pA/√Hz
	Crosstalk (Input Referred)	10MHz, 1V <sub>PP</sub>	-72	_	_	_	dB
Static, Do	C Performance	,	•		'		
	Input Offset Voltage		1	6	7	8	mV
	Average Drift		10	_	_	_	μV/°C
	Input Bias Current (Non-Inverting)		8	18	23	25	μA
	Average Drift		40	_	_	_	nA/°C
	Input Bias Current (Inverting)		9	24	28	28	μA
	Average Drift		30	_	_	_	nA/°C
	Power Supply Rejection Ratio	DC	48	45	43	43	dB
	Common Mode Rejection Ratio	DC	48	46	44	44	dB
	Supply Current (Per Channel)	R <sub>L</sub> = ∞	3.2	3.8	4.0	4.0	mA
Miscellar	neous Performance		<u> </u>				
	Input Resistance (Non-Inverting)		0.48	0.34	0.31	0.31	МΩ
	Input Capacitance (Non-Inverting)		1.45	2.15	2.15	2.15	pF
	Common-Mode Input Range		±4.2	±4.1	±4.1	±4.0	V
	Output Voltage Range	$R_L = 100\Omega$	±3.8	±3.6	±3.6	±3.5	V
	Output Voltage Range	R <sub>L</sub> = ∞	±4.0	±3.8	±3.8	±3.7	V
	Output Current (2)		130	100	80	50	mA
	Output Resistance, Closed Loop	DC	60	90	90	120	mΩ

<sup>(2)</sup> The short circuit current can exceed the maximum safe output current



#### +5V TYPICAL PERFORMANCE CHARACTERISTICS

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_S = +5V \ (V_S = V_{CC} - V_{EE}), V_{CM} = V_{EE} + (V_S/2), R_L \ tied \ to \ V_{CM}, \ unless \ specified).$ 

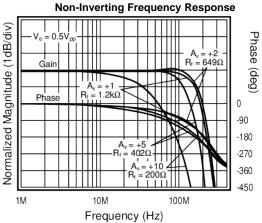


Figure 2.

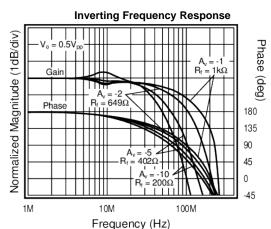


Figure 3.

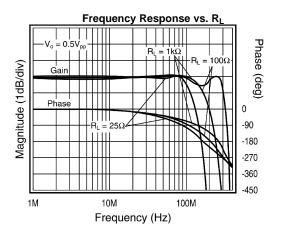
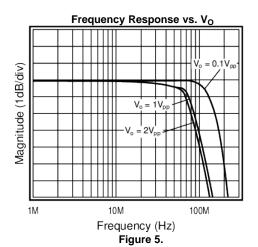
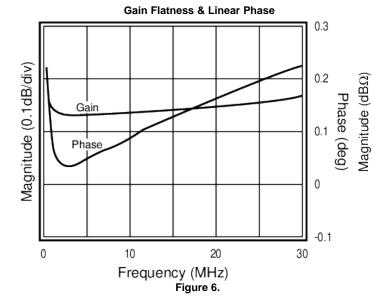


Figure 4.





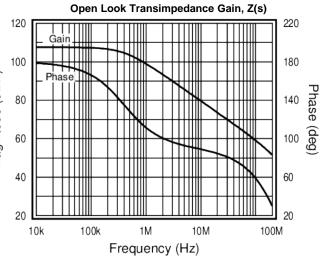
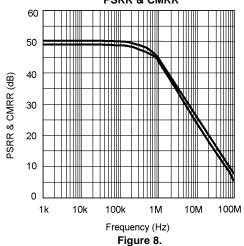


Figure 7.



## +5V TYPICAL PERFORMANCE CHARACTERISTICS (continued)

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_S = +5V (V_S = V_{CC} - V_{EE}), V_{CM} = V_{EE} + (V_S/2), R_L \text{ tied to } V_{CM}, \text{ unless specified}).$  PSRR & CMRR Equivalent Input Noise



3.6
(Noise Current 10.8pA/\Hz)
3.4
(PA/\AU)
3.3
(Non-Inverting Current 7.6pA/\Hz)
7
(Noise Current 10.8pA/\Hz)
7
(Noise Current (pA/\Hz)
7
(Noise Current 10.8pA/\Hz)
7
(Noise Current 10.8pA/

2nd & 3rd Harmonic Distortion

Figure 9.

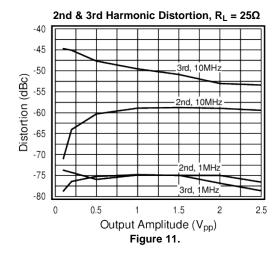
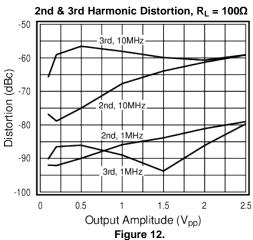
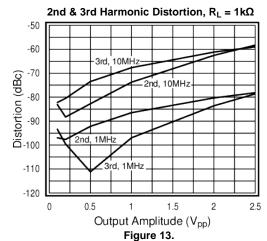


Figure 10.



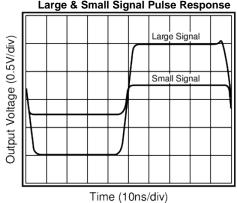


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## +5V TYPICAL PERFORMANCE CHARACTERISTICS (continued)

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_S = +5V (V_S = V_{CC} - V_{EE}), V_{CM} = V_{EE} + (V_S/2), R_L \text{ tied to } V_{CM}, \text{ unless specified)}.$   $\underline{\text{Large \& Small Signal Pulse Response}}$ Output Impedance vs. Frequency



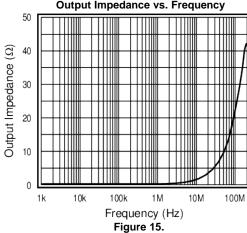


Figure 14.

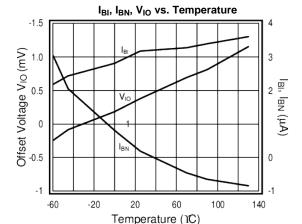


Figure 16.

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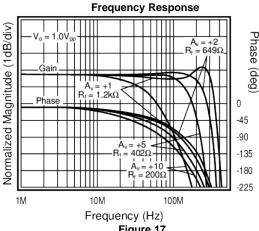
Magnitude (1dB/div)

1M



#### ±5V TYPICAL PERFORMANCE

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_{CC} = \pm 5V, unless specified)$ 



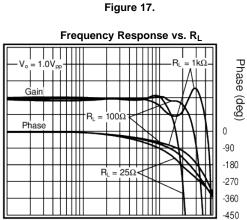
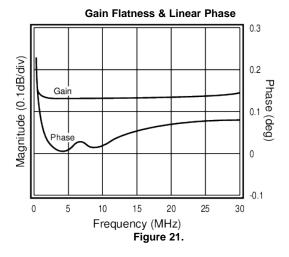
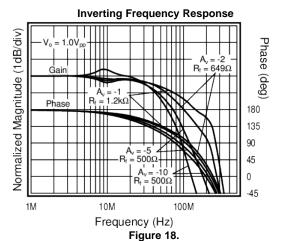


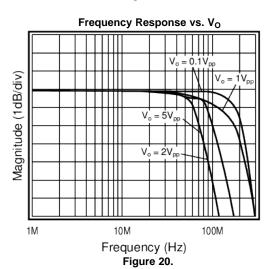
Figure 19.

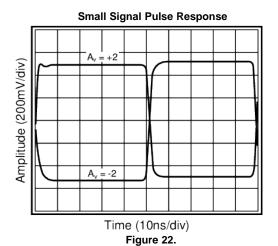
Frequency (Hz)

10M









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## ±5V TYPICAL PERFORMANCE (continued)

 $(A_V = +2, R_f = 750\Omega, R_L = 100\Omega, V_{CC} = \pm 5V, unless specified)$ 

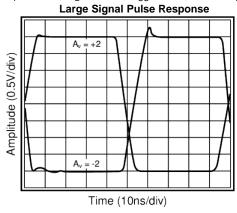
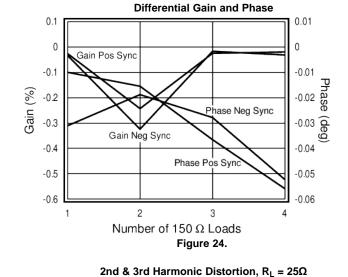
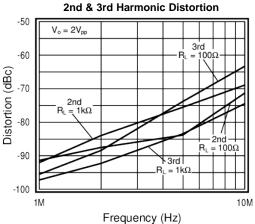
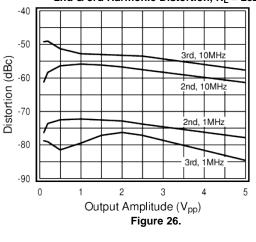


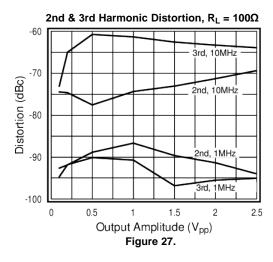
Figure 23.

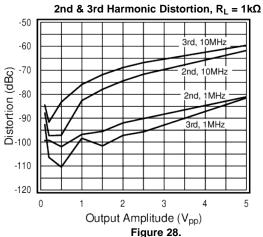




Frequency (Hz) Figure 25.

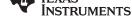






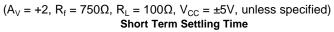
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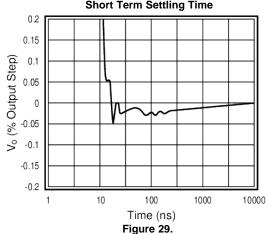
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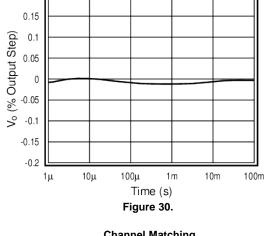


## ±5V TYPICAL PERFORMANCE (continued)

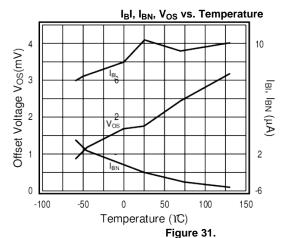
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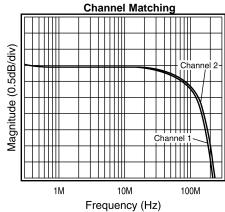






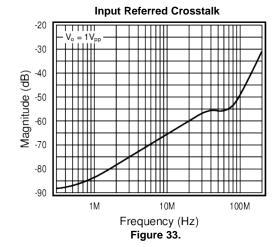
**Long Term Settling Time** 











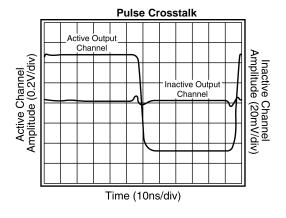


Figure 34.

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#### **APPLICATION DIVISION**

#### **CLC5622 OPERATION**

The CLC5622 is a current feedback amplifier fabricated in an advanced complementary bipolar process. The CLC5622 operates from a single 5V supply or dual ±5V supplies. Operating from a single supply, the CLC5622 has the following features:

- Provides 100mA of output current while consuming 15mW of power
- Offers low -80/-83dB 2nd and 3rd harmonic distortion
- Provides BW>80MHz and 1MHz distortion <-75dBc at V<sub>O</sub> = V<sub>PP</sub>

The CLC5622 performance is further enhanced in ±5V supply applications as indicated in the +5V ELECTRICAL CHARACTERISTICS table and +5V ELECTRICAL CHARACTERISTICS plots.

#### **CURRENT FEEDBACK AMPLIFIERS**

Some of the key features of current feedback technology are:

- · Independence of AC bandwidth and voltage gain
- · Inherently stable at unity gain
- Adjustable frequency response with feedback resistor
- · High slew rate
- Fast Settling

Current feedback operation can be described using a simple equation. The voltage gain for a non-inverting or inverting current feedback amplifier is approximated by Equation 1.

$$\frac{V_o}{V_{in}} = \frac{A_v}{1 + \frac{R_f}{Z(i\omega)}}$$

#### where

- ullet A<sub>V</sub> is the closed loop DC voltage gain
- · R<sub>f</sub> is the feedback resistor
- Z(<sub>i(ω)</sub>) is the CLC5622's open loop transimpedance gain
- Z<sub>i(ω)</sub>Rf is the loop gain

(1)

The denominator of Equation 1 is approximately equal to 1 at low frequencies. Near the -3dB corner frequency, the interaction between  $R_f$  and  $Z(j(\omega))$  dominates the circuit performance. The value of the feedback resistor has a large affect on the circuits performance. Increasing  $R_f$  has the following affects:

- Decreases loop gain
- Decreases bandwidth
- · Reduces gain peaking
- Lowers pulse response overshoot
- Affects frequency response phase linearity

Refer to the Feedback Resistor Selection section for more details on selecting a feedback resistor value.

## CLC5622 Design Information Single Supply Operation ( $V_{CC} = +5V$ , $V_{EE} = GND$ )

The specifications given in the +5V ELECTRICAL CHARACTERISTICS table for single supply operation are measured with a common mode voltage ( $V_{cm}$ ) of 2.5V.  $V_{cm}$  is the voltage around which the inputs are applied and the output voltages are specified.

Operating from a single +5V supply, the Common Mode Input Range (CMIR) of the CLC5622 is typically +0.8V to +4.2V. The typical output range with  $R_L$ =100 $\Omega$  is +1.0V to +4.0V.

For single supply DC coupled operation, keep input signal levels above 0.8V DC. For input signals that drop below 0.8V DC, AC coupling and level shifting the signal are recommended. The non-inverting and inverting configurations for both input conditions are illustrated in the following 2 sections.

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## **DC Coupled Single Supply Operation**

Figure 35 and Figure 36 show the recommended non-inverting and inverting configurations for input signals that remain above 0.8V DC. Note:  $R_f$ ,  $R_L$ , and  $R_g$  are tied to  $V_{cm}$  for minimum power consumption and maximum output swing.

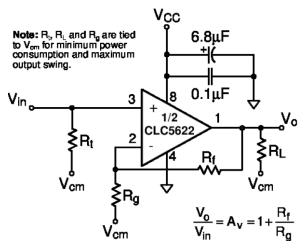


Figure 35. Non-Inverting Configuration

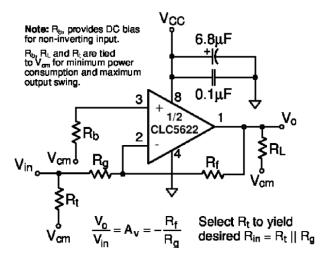


Figure 36. Inverting Configuration

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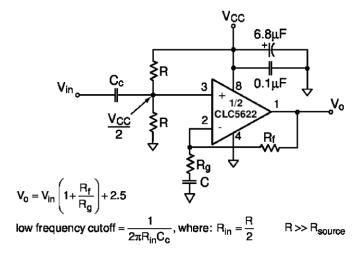


Figure 37. AC Coupled Non-Inverting Configuration

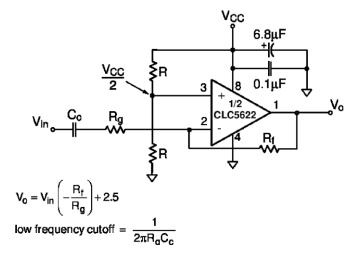


Figure 38. Dual Supply Non-Inverting Configuration

## **AC Coupled Single Supply Operation**

Figure 37 and Figure 38 show possible non-inverting and inverting configurations for input signals that go below 0.8V DC. The input is AC coupled to prevent the need for level shifting the input signal at the source. The resistive voltage divider biases the non-inverting input to  $V_{CC} \div 2 = 2.5V$  (For  $V_{CC} = +5V$ ).

## **Dual Supply Operation**

The CLC5622 operates on dual supplies as well as single supplies. The non-inverting and inverting configurations are shown in Figure 39 and Figure 40.

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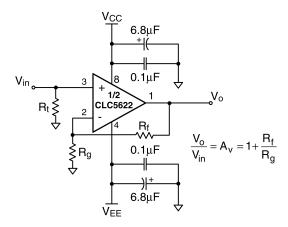


Figure 39. Dual Supply Non-Inverting Configuration

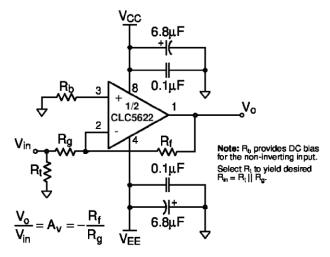


Figure 40. Dual Supply Inverting Configuration

#### **Feedback Resistor Selection**

The feedback resistor,  $R_f$ , affects the loop gain and frequency response of a current feedback amplifier. Optimum performance of the CLC5622, at a gain of +2V/V, is achieved with  $R_f$  equal to 750 $\Omega$ . The frequency response plots in the Typical Performance sections illustrate the recommended  $R_f$  for several gains. These recommended values of  $R_f$  provide the maximum bandwidth with minimal peaking. Within limits,  $R_f$  can be adjusted to optimize the frequency response.

- Decrease R<sub>f</sub> to peak frequency response and extend bandwidth
- Increase R<sub>f</sub> to roll off frequency response and compress bandwidth

As a rule of thumb, if the recommended R<sub>f</sub> is doubled, then the bandwidth will be cut in half.

## **Unity Gain Operation**

The recommended  $R_f$  for unity gain (+1V/V) operation is 1.2k $\Omega$ .  $R_g$  is left open. Parasitic capacitance at the inverting node may require a slight increase in  $R_f$  to maintain a flat frequency response.

#### **Load Termination**

The CLC5622 can source and sink near equal amounts of current. For optimum performance, the load should be tied to  $V_{CM}$ .



## **Driving Cables and Capacitive Loads**

When driving cables, double termination is used to prevent reflections. For capacitive load applications, a small series resistor at the output of the CLC5622 will improve stability and settling performance. The **Frequency Response vs. C**<sub>L</sub> plot, shown below in Figure 41, gives the recommended series resistance value for optimum flatness at various capacitive loads.

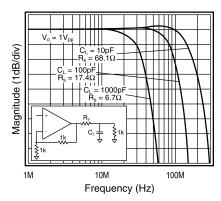


Figure 41. Frequency Response vs. C<sub>L</sub>

## **Transmission Line Matching**

One method for matching the characteristic impedance ( $Z_0$ ) of a transmission line or cable is to place the appropriate resistor at the input or output of the amplifier. Figure 42 shows typical inverting and non-inverting circuit configurations for matching transmission lines.

Non-inverting gain applications:

- Connect R<sub>3</sub> directly to ground.
- Make R<sub>1</sub>, R<sub>2</sub>, R<sub>6</sub>, and R<sub>7</sub> equal to Z<sub>0</sub>.
- Use R<sub>3</sub> to isolate the amplifier from reactive loading caused by the transmission line, or by parasitics.

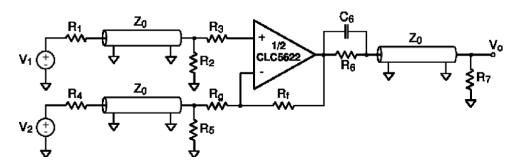


Figure 42. Transmission Line Matching

Inverting gain applications:

- Connect R<sub>3</sub> directly to ground.
- Make the resistors R<sub>4</sub>, R<sub>6</sub>, and R<sub>7</sub> equal to Z<sub>0</sub>.
- Make R<sub>5</sub> | R<sub>g</sub> = Z<sub>0</sub>

The input and output matching resistors attenuate the signal by a factor of 2, therefore additional gain is needed. Use  $C_6$  to match the output transmission line over a greater frequency range.  $C_6$  compensates for the increase of the amplifier's output impedance with frequency.

(2)

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## **Power Dissipation**

Follow these steps to determine the power consumption of the CLC5622.

- 1. Calculate the quiescent (no-load) power:  $P_{amp} = |_{CC} (V_{CC} V_{EE})$
- 2. Calculate the RMS power at the output stage:  $P_0 = (V_{CC} V_{load})$  ( $|_{load}$ ), where  $V_{load}$  and  $|_{load}$  are the RMS voltage and current across the external load.
- 3. Calculate the total RMS power:  $P_t = P_{amp} + P_0$

The maximum power that the PDIP and SOIC packages can dissipate at a given temperature is illustrated in Figure 43. The power derating curve for any CLC5622 package can be derived by utilizing the following equation:

$$\frac{(150^{\circ} - T_{amb})}{\theta_{JA}}$$

#### where

- T<sub>amb</sub>=Ambient temperature (°C)
- $\theta_{JA}$ =Thermal resistance, from junction to ambient, for a given package (°C/W)

1.0
0.8
IM
IN
0.6
0.4
0.2
0-40 -20 0 20 40 60 80 100 120 140 160 180
Ambient Temperature (°C)

Figure 43. Power Derating Curves

#### **Layout Considerations**

A proper printed circuit layout is essential for achieving high frequency performance. TI provides evaluation boards for the CLC5622 (CLC730038-PDIP, CLC730036-SOIC) and suggests their use as a guide for high frequency layout and as an aid for device testing and characterization.

General layout and supply bypassing play major roles in high frequency performance. Follow these steps below as a basis for high frequency layout:

- Include 6.8µF tantalum and 0.1µF ceramic capacitors on both supplies.
- Place the 6.8µF capacitors within 0.75 inches of the power pins.
- Place the 0.1µF capacitors less than 0.1 inches from the power pins.
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance.
- · Minimize all trace lengths to reduce series inductances.
- Use flush-mount printed circuit board pins for prototyping, never use high profile PDIP sockets.

#### **Evaluation Board Information**

A data sheet is available for the CLC730038/CLC730036 evaluation boards. The evaluation board data sheet provides:

- Evaluation board schematics
- Evaluation board layouts
- General information about the boards

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The evaluation boards are designed to accommodate dual supplies. The boards can be modified to provide single supply operation. For best performance; 1) do not connect the unused supply, 2) ground the unused supply pin.

#### **SPICE Models**

SPICE models provide a means to evaluate amplifier designs. Free SPICE models are available for TI's monolithic amplifiers that:

- Support Berkeley SPICE 2G and its many derivatives
- Reproduces typical DC, AC, Transient, and Noise performance
- Support room temperature simulations

The *readme* file that accompanies the diskette lists released models, and provides a list of modeled parameters. The application note OA-18, Simulation SPICE Models for TI's Op Amps, contains schematics and a reproduction of the readme file.

# Application Circuits Single Supply Cable Driver

The typical application shown below shows one of the CLC5622 amplifiers driving 10m of 75 $\Omega$  coaxial cable. The CLC5622 is set for a gain of +2V/V to compensate for the divide-by-two voltage drop at  $V_{\Omega}$ .

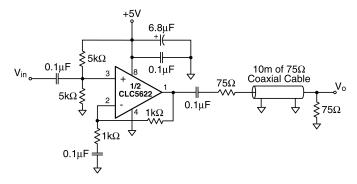


Figure 44. Single Supply Cable Driver

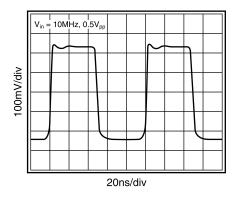


Figure 45. Response After 10m of Cable

#### Single Supply Lowpass Filter

Figure 46 and Figure 47 illustrate a lowpass filter and design equations. The circuit operates from a single supply of +5V. The voltage divider biases the non-inverting input to 2.5V. And the input is AC coupled to prevent the need for level shifting the input signal at the source. Use the design equations to determine  $R_1$ ,  $R_2$ ,  $C_1$ , and  $C_2$  based on the desired Q and corner frequency.



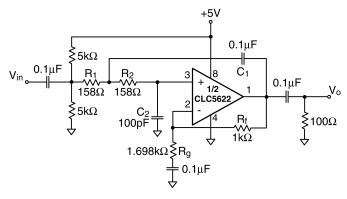


Figure 46. Lowpass Filter Topology

$$\begin{split} &\text{Gain} = \text{K} = 1 + \frac{R_f}{R_g} \\ &\text{Corner frequency} = \omega_c = \sqrt{\frac{1}{R_1 R_2 C_1 C_2}} \\ &\text{Q} = \frac{1}{\sqrt{\frac{R_2 C_2}{R_1 C_1}} + \sqrt{\frac{R_1 C_2}{R_2 C_1}} + (1 - \text{K}) \sqrt{\frac{R_1 C_1}{R_2 C_2}}} \\ &\text{For } R_1 = R_2 = R \ \text{and} \ C_1 = C_2 = C \\ &\omega_c = \frac{1}{RC} \\ &\text{Q} = \frac{1}{(3 - \text{K})} \end{split}$$

Figure 47. Design Equations

This example illustrates a lowpass filter with Q=0.707 and corner frequency  $f_c/10MHz$ . A Q of the 0.707 was chosen to achieve a maximally flat, Butterworth response. Figure 48 indicates the filter response.

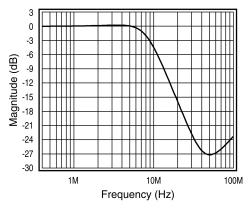


Figure 48. Lowpass Response

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## **Differential Line Driver With Load Impedance Conversion**

The circuit shown in the TYPICAL APPLICATION schematic on the front page and in Figure 49, operates as a differential line driver. The transformer converts the load impedance to a value that best matches the CLC5622's output capabilities. The single-ended input signal is converted to a differential signal by the CLC5622. The line's characteristic impedance is matched at both the input and the output. The schematic shows Unshielded Twisted Pair for the transmission line; other types of lines can also be driven.

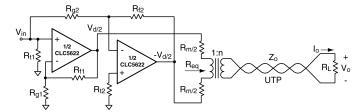


Figure 49. Differential Line Driver with Load Impedance Conversion

Set up the CLC5622 as a difference amplifier:

$$\frac{V_{d}}{V_{in}} = 2 \cdot \left(1 + \frac{R_{f1}}{R_{g1}}\right) = 2 \cdot \frac{R_{f2}}{R_{g2}}$$
(3)

Make the best use of the CLC5622's output drive capability as follows:

$$R_m + R_{eq} = \frac{2 \cdot V_{max}}{I_{max}}$$

where

- R<sub>eq</sub> is the transformed value of the load impedance
- $\bullet \quad \ \ V_{max} \ is \ the \ Output \ Voltage \ Range$

Match the line's characteristic impedance:

$$R_{L} = Z_{o}$$

$$R_{m} = R_{eq}$$

$$n = \sqrt{\frac{R_{L}}{R_{eq}}}$$

(5)

Select the transformer so that it loads the line with a value very near  $Z_0$  over frequency range. The output impedance of the CLC5622 also affects the match. With an ideal transformer we obtain:

$$Return \, Loss = -20 \cdot log_{10} \left| \, \frac{n^2 \cdot Z_{o(5622)}(j\omega)}{Z_o} \, \right|, dB$$

where

Z<sub>O(5622)</sub>(jω) is the output impedance of the CLC5622

• 
$$|Z_{O(5622)}(j\omega)| << R_m$$
 (6)

The load voltage and current will fall in the ranges:

$$|V_0| \le n \cdot V_{max}$$

$$\left| I_{o} \right| \leq \frac{I_{\text{max}}}{n} \tag{7}$$

The CLC5622's high output drive current and low distortion make it a good choice for the application.

20

## **Full Duplex Cable Driver**

RUMENTS

The circuit shown in Figure 50 below, operates as a full duplex cable driver which allows simultaneous transmission and reception of signals on one transmission line. The circuit on either side of the transmission line uses are CLC5622 as a cable drive, and the second CLC5622 as a receiver.  $V_{oA}$  is an attenuated version of  $V_{inA}$ , while  $V_{oB}$  is an attenuated version of  $V_{inB}$ .

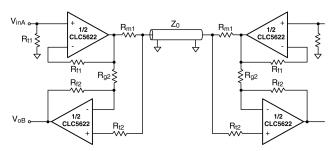


Figure 50. Full Duplex Cable Driver

 $R_{m1}$  is used to match the transmission line.  $R_{f2}$  and  $R_{g2}$  set the DC gain of the CLC5622, which is used in a difference mode.  $R_{t2}$  provides good CMRR and DC offset. The transmitting CLC5622's are shown in a unity gain configuration because they consume the least power of any gain, for a given load, for proper operation we need  $R_{f2} = R_{g2}$ .

The receiver output voltages are:

$$V_{outA(B)} \approx V_{inA(B)} \cdot A + \frac{V_{inB(A)}}{2} \cdot \left(1 - \frac{R_{f2}}{R_{\alpha 2}} + \frac{Z_{o(5622)}(j\omega)}{R_{m1}}\right)$$

where

- · A is the attenuation of the cable
- Z<sub>O(5622)</sub>(jω) is the output impedance of the CLC5622

• 
$$|Z_{O(5622)}(j\omega)| << R_{m1}$$
 (8)

(see the Closed-Loop Output Resistance plot)

We selected the component values as follows:

- $R_{f1} = 1.2k\Omega$ , the recommended value for CLC5622 at unity gain.
- $R_{m1} = Z_0 = 50\Omega$ , the characteristic impedance of the transmission line.
- $R_{f2} = R_{g2} = 750\Omega \ge R_{m1}$ , the recommended value for the CLC5622 at  $A_V = 2$
- $R_{t2} = (R_{f2}||R_{g2})-R_{m1}/2 = 25\Omega$

These values give excellent isolation from the other input:

$$\frac{V_{oA(B)}}{V_{inB(A)}} \approx -38dB, \ f = 5.0MHz$$

The CLC5622 provides large output current drive, while consuming little supply current, at the nominal bias point. It also produces low distortion with large signal swings and heavy loads. These features make the CLC5622 an excellent choice for driving transmission lines.

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# **REVISION HISTORY**

Cł	nanges from Revision C (April 2013) to Revision D	Paç	ge
•	Changed layout of National Data Sheet to TI format	2	21

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