

# Synchronous Boost Flash Driver With Dual 1-A High-Side Current Sources (2-A Total Flash Current)

Check for Samples: [LM3560](#)

## FEATURES

- Dual High-Side Current Sources Allow for Grounded Cathode LED Operation
- Accurate and Programmable LED Current from 31.25 mA to 2 A
- Independent LED Current Source Programmability
- Up to 90% Efficient
- Ultra-Small Solution Size: < 26 mm<sup>2</sup>
- Four Operating Modes: Torch, Flash, Privacy Indicate, and Message Indicator
- 4-Bit ADC for V<sub>LED</sub> Monitoring
- LED Thermal Sensing and Current Scale-Back
- Hardware Flash and Torch Enable
- Dual Synchronization Inputs for RF Power Amplifier Pulse Events
- LED and Output Disconnect During Shutdown
- Open and Short LED Detection
- 400-kHz I<sup>2</sup>C-Compatible Interface
- Active Low Hardware Reset
- 16-Bump (1.97mm x 1.97mm x 0.6mm) DSBGA

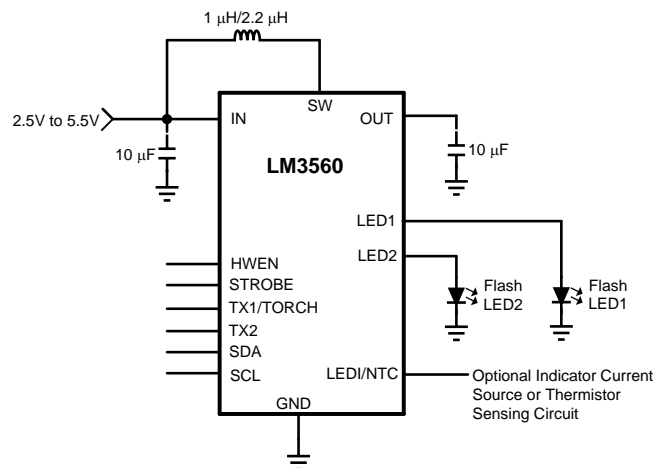
## APPLICATIONS

- Camera Phone LED Flash
- White LED Biasing

## DESCRIPTION

The LM3560 is a 2MHz fixed frequency synchronous boost converter with two 1000 mA constant current drivers for high-current white LEDs. The dual high-side current sources allow for grounded cathode LED operation and can be tied together for providing flash currents at up to 2A through a single LED. An adaptive regulation method ensures the current for each LED remains in regulation and maximizes efficiency.

## Typical Application Circuit



**Table 1. Application Circuit Component List**

Component	Manufacturer	Value	Part Number	Size (mm)	Rating
L	Toko	1µH	FDSD0312-1R0	3 x 3 x 1.2	3.3A
COU	Murata	10 µF	GRM188R60J106M	1.6 x 0.8 x 0.8 (0603)	6.3V
CIN	Murata	10 µF	GRM188R60J106M	1.6 x 0.8 x 0.8 (0603)	6.3V
LEDs	Lumiled	Flash LED	PWF-4		VF = 3.6V @1A



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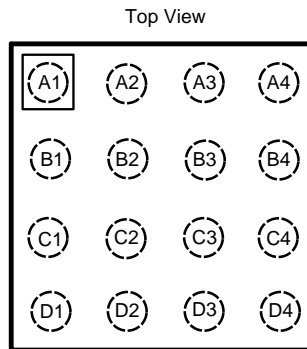
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## DESCRIPTION (CONTINUED)

The LM3560 is controlled via an I<sup>2</sup>C-compatible interface. Features include: an internal 4-bit ADC to monitor the LED voltage, independent LED current control, a hardware flash enable allowing a logic input to trigger the flash pulse, dual TX inputs which force the flash pulse into a low-current torch mode allowing for synchronization to RF power amplifier events or other high-current conditions, and an integrated comparator designed to monitor an NTC thermistor and provide an interrupt to the LED current. Additionally, an active high HWEN input provides a hardware shutdown during system software failures.

The 2MHz switching frequency, over-voltage protection and adjustable current limit allow for the use of tiny, low-profile (1  $\mu$ H and 2.2  $\mu$ H) inductors and (10  $\mu$ F) ceramic capacitors. The device is available in a ultra-small 16-bump (1.97mm x 1.97mm x 0.6mm) DSBGA package and operates over the -40°C to +85°C temperature range.

## Connection Diagram



**16-Bump 1.97 mm x 1.97 mm x 0.6 mm DSBGA Package YZR0016**

## PIN DESCRIPTIONS

Pin	Name	Function
A1	LED1	High Side Current Source Output for Flash LED.
A2, B2	OUT	Step-Up DC/DC Converter Output. Connect a 10 $\mu$ F ceramic capacitor between this pin and GND.
A3, B3	SW	Drain Connection for Internal NMOS and Synchronous PMOS Switches.
A4, B4	GND	Ground
B1	LED2	High-Side Current Source Output for Flash LED.
C1	LEDI/NTC	Configurable as a High-Side Current Source Output for Indicator LED or Comparator Input for LED Temperature Sensing.
C2	TX1/TORCH/ GPIO1	Configurable as a Dual-Polarity RF Power Amplifier Synchronization Input, an Interrupt Output, or as a General Purpose Logic I/O. This pin has an internal 300k $\Omega$ pull down to GND.
C3	STROBE	Active High Hardware Flash Enable. Drive STROBE high to turn on the Flash pulse. This pin has an internal 300 k $\Omega$ pull down to GND.
C4	IN	Input Voltage Connection. Connect IN to the input supply, and bypass to GND with a minimum 10 $\mu$ F ceramic capacitor.
D1	TX2/INT/GPIO2	Configurable as a Dual-Polarity Power Amplifier Synchronization Input, an Interrupt Output, or as a General Purpose Logic I/O. This pin has an internal 300 k $\Omega$ pull down to GND.
D2	SDA	Serial Data Input/Output. High impedance in shutdown or in power down.
D3	SCL	Serial Clock Input. High impedance in shutdown or in power down.
D4	HWEN	Logic High Hardware Enable. HWEN is a high impedance input and is normally connected with an external pull up resistor to a logic high voltage.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

**Absolute Maximum Ratings** (1) (2)(3)

$V_{IN}$ , $V_{SW}$ , $V_{OUT}$	-0.3V to 6V
$V_{SCL}$ , $V_{SDA}$ , $V_{HWEN}$ , $V_{STROBE}$ , $V_{TX1}$ , $V_{TX2}$ , $V_{LED1}$ , $V_{LED2}$ , $V_{LED1/NTC}$	-0.3V to the lesser of ( $V_{IN}+0.3V$ ) or 6.0V
Continuous Power Dissipation <sup>(4)</sup>	Internally Limited
Junction Temperature ( $T_{J-MAX}$ )	+150°C
Storage Temperature Range	-65°C to +150°C
Maximum Lead Temperature (Soldering)	<sup>(5)</sup>

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply specified performance limits. For performance limits and associated test conditions, see the Electrical Characteristics table.
- (2) All voltages are with respect to the potential at the GND pin.
- (3) If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.
- (4) Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at  $T_J=+150^\circ\text{C}$  (typ.) and disengages at  $T_J=+135^\circ\text{C}$  (typ.). Thermal shutdown is specified by design.
- (5) For detailed soldering specifications and information, see Application Note AN1112 *DSBGA Wafer Level chip Scale Package*.

**Operating Ratings** (1) (2)

$V_{IN}$	2.5V to 5.5V
Junction Temperature ( $T_J$ )	-40°C to +125°C
Ambient Temperature ( $T_A$ ) <sup>(3)</sup>	-40°C to +85°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply specified performance limits. For performance limits and associated test conditions, see the Electrical Characteristics table.
- (2) All voltages are with respect to the potential at the GND pin.
- (3) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature ( $T_{A-MAX}$ ) is dependent on the maximum operating junction temperature ( $T_{J-MAX-OP} = +125^\circ\text{C}$ ), the maximum power dissipation of the device in the application ( $P_{D-MAX}$ ), and the junction-to-ambient thermal resistance of the part/package in the application ( $\theta_{JA}$ ), as given by the following equation:  $T_{A-MAX} = T_{J-MAX-OP} - (\theta_{JA} \times P_{D-MAX})$ .

**Thermal Properties**

Thermal Junction-to-Ambient Resistance ( $\theta_{JA}$ ) <sup>(1)</sup>	50.4°C/W
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- (1) Junction-to-ambient thermal resistance ( $\theta_{JA}$ ) is taken from a thermal modeling result, performed under the conditions and guidelines set forth in the JEDEC standard JESD51-7. The test board is a 4-layer FR-4 board measuring 102 mm x 76 mm x 1.6 mm with a 2x1 array of thermal vias. The ground plane on the board is 50 mm x 50 mm. Thickness of copper layers are 36  $\mu\text{m}$ /18  $\mu\text{m}$ /18  $\mu\text{m}$ /36  $\mu\text{m}$  (1.5 oz/1oz/1oz/1.5 oz). Ambient temperature in simulation is 22°C, still air. Power dissipation is 1W.

**Electrical Characteristics** (1) (2)

Limits in standard typeface are for  $T_A = +25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ ). Unless otherwise specified,  $V_{IN} = 3.6V$ ,  $V_{HWEN} = V_{IN}$ .

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit		
<b>Current Source Specifications</b>								
$I_{LED}$	Current Source Accuracy	$I_{LED1}+I_{LED2}$ , $V_{OUT} = 4.5V$ , $3.0V \leq V_{IN} \leq 4.2V$	1000mA Flash Current Setting, per current source	$-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$	<b>-5%</b>	2000	<b>+5%</b>	mA
				$T_A = +25^\circ\text{C}$	-3.5%		<b>+3.5%</b>	
			31.25mA Torch Current Setting, per current source	$-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$	<b>-10%</b>	62.5	<b>+10%</b>	
$V_{OUT} - V_{LED1/2}$	Current Source Regulation Voltage	$I_{LED} = 2A$ , ( $I_{LED1} + I_{LED2}$ ) $V_{OUT} = 4.5V$		300			mV	

- (1) All voltages are with respect to the potential at the GND pin.
- (2) Min and Max limits are specified by design, test, or statistical analysis. Typical (Typ) numbers represent the most likely norm. Unless otherwise specified, conditions for typical specifications are:  $V_{IN} = 3.6V$  and  $T_A = +25^\circ\text{C}$ .

## Electrical Characteristics <sup>(1)</sup> <sup>(2)</sup> (continued)

Limits in standard typeface are for  $T_A = +25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ ). Unless otherwise specified,  $V_{IN} = 3.6\text{V}$ ,  $V_{HWEN} = V_{IN}$ .

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$V_{OVP}$	Output Over-Voltage Protection Trip Point <sup>(3)</sup>	ON Threshold	<b>4.925</b>	5	<b>5.075</b>	V
		OFF Threshold		4.8		
<b>Step-Up DC/DC Converter Specifications</b>						
$R_{PMOS}$	PMOS Switch On-Resistance	$I_{PMOS} = 1\text{A}$		80		m $\Omega$
$R_{NMOS}$	NMOS Switch On-Resistance	$I_{NMOS} = 1\text{A}$		65		m $\Omega$
$I_{CL}$	Switch Current Limit <sup>(4)</sup>	CL bits = 00, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>1.44</b>	1.6	<b>1.76</b>	A
		CL bits = 01, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>2.02</b>	2.3	<b>2.58</b>	
		CL bits = 10, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>2.64</b>	3.0	<b>3.36</b>	
		CL bits = 11, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>3.17</b>	3.6	<b>4.03</b>	
$I_{OUT\_SC}$	Output Short Circuit Current Limit	$V_{OUT} < 2.3\text{V}$		300		mA
$I_{LED/NTC}$	Indicator Current	Message Indicator Register, bits[2:0] = 111, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$ , $V_{LED/NTC} = 2\text{V}$	<b>16</b>	18	<b>20</b>	mA
$V_{TRIP}$	Comparator Trip Threshold	Configuration Register 1, bit4 = 1, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>0.97</b>	1	<b>1.03</b>	V
$f_{SW}$	Switching Frequency	$3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>1.8</b>	2	<b>2.2</b>	MHz
$t_{TIMEOUT}$	Timeout Duration <sup>(5)</sup> , <sup>(6)</sup>	$3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>-10%</b>		<b>+10%</b>	ms
$I_Q$	Quiescent Supply Current	Device Not Switching, $V_{OUT} = 3\text{V}$		900		$\mu\text{A}$
		Device Switching, $V_{OUT} = 4.5\text{V}$		1.97		mA
		Indicate Mode, Message Indicator Register, bits[2:0] = 111, $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$		590		$\mu\text{A}$
$I_{SHDN}$	Shutdown Supply Current	$V_{HWEN} = \text{GND}$ , $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$		0.02	<b>1.25</b>	$\mu\text{A}$
$I_{STBY}$	Standby Supply Current	$V_{HWEN} = V_{IN}$ , $3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$		1.25	<b>2</b>	
$V_{IN\_TH}$	VIN Monitor Threshold	VIN Monitor Register = 0x01	<b>2.85</b>	2.9	<b>2.95</b>	V
$V_{IN\_FLASH\_TH}$	VIN Flash Monitor Threshold	VIN Monitor Register = 0x08	<b>2.85</b>	2.9	<b>2.95</b>	V
$t_{TX}$	Flash to Torch LED Current Settling Time	TX_Low to High, $I_{LED1} + I_{LED2} = 2\text{A to } 187.5\text{mA}$		2		$\mu\text{s}$
	Torch to Flash LED Current Settling Time	TX_High to Low, $I_{LED1} + I_{LED2} = 187.5\text{mA to } 2\text{A}$		160		

(3) The typical curve for Over-Voltage Protection (OVP) is measured in closed loop using the typical application circuit. The OVP value is found by forcing an open circuit in the LED1 and LED2 path and recording the peak value of  $V_{OUT}$ . The value given in the Electrical Table is found in an open loop configuration by ramping the voltage at OUT until the OVP comparator trips. The closed loop data can appear higher due to the stored energy in the inductor being dumped into the output capacitor after the OVP comparator trips. At worst case is an open circuit condition where the output voltage can continue to rise after the OVP comparator trips by approximately  $I_{IN} \times \sqrt{L/C_{OUT}}$ .

(4) The typical curve for Current Limit is measured in closed loop using the typical application circuit by increasing  $I_{OUT}$  until the peak inductor current stops increasing. The value given in the Electrical Table is measured open loop and is found by forcing current into SW until the current limit comparator threshold is reached. Closed loop data appears higher due to the delay between the comparator trip point and the NFET turning off. This delay allows the closed loop inductor current to ramp higher after the trip point by approximately  $20\text{ns} \times V_{IN}/L$ .

(5) Specified by design. Not production tested.

(6) The timeout period is a divided down representation of the 2MHz clock and thus the accuracy spec is the same as the switching frequency.

**Electrical Characteristics <sup>(1)</sup> <sup>(2)</sup> (continued)**

 Limits in standard typeface are for  $T_A = +25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ ). Unless otherwise specified,  $V_{IN} = 3.6\text{V}$ ,  $V_{HWEN} = V_{IN}$ .

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$t_D$	Time from when $I_{LED}$ hits target until VLED data is available	ADC Delay Register Bit [5] = 1		16		$\mu\text{s}$
		ADC Delay Register Bit [5] = 0 ADC Delay Register Bits [4:0] = 0000		250		
$V_{F\_ADC}$	ADC Threshold	$3.0\text{V} \leq V_{IN} \leq 4.2\text{V}$ , VLED Monitor Register Bits [3:0] = 1111	<b>4.05</b>	4.2	<b>4.35</b>	V
<b>HWEN, STROBE, TX1/TORCH/GPIO1, TX2/INT/GPIO2 Voltage Specifications</b>						
$V_{IL}$	Input Logic Low	$2.7\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>0</b>		<b>0.4</b>	V
$V_{IH}$	Input Logic High	$2.7\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>1.2</b>		<b><math>V_{IN}</math></b>	V
$R_{PD}$	Internal Pull Down Resistance on TX1, TX2, STROBE			300		k $\Omega$
<b>I<sup>2</sup>C-Compatible Voltage Specifications (SCL, SDA)</b>						
$V_{IL}$	Input Logic Low	$2.7\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>0</b>		<b>0.4</b>	V
$V_{IH}$	Input Logic High	$2.7\text{V} \leq V_{IN} \leq 4.2\text{V}$	<b>1.2</b>		<b><math>V_{IN}</math></b>	V
$V_{OL}$	Output Logic Low (SDA)	$I_{LOAD} = 3\text{mA}$ , $2.7\text{V} \leq V_{IN} \leq 4.2\text{V}$			<b>400</b>	mV
<b>I<sup>2</sup>C-Compatible Timing Specifications (SCL, SDA) <sup>(7)</sup>, see Figure 42</b>						
$f_{SCL}$	SCL(Clock Frequency)		<b>0</b>		<b>400</b>	kHz
$t_{RISE}$	Rise Time of Both SDA and SCL		<b>20ns + 0.1 × C<sub>BUS</sub></b>		<b>300</b>	ns
$t_{FALL}$	Fall Time of Both SDA and SCL		<b>20ns + 0.1 × C<sub>BUS</sub></b>		<b>300</b>	ns
$t_{LOW}$	Low Period of SCL Clock		<b>1.3</b>			$\mu\text{s}$
$t_{HIGH}$	High Period of SCL Clock		<b>600</b>			ns
$t_{HD;STA}$	Hold Time for Start (or Repeated Start)Condition		<b>600</b>			ns
$t_{SU;STA}$	Set-up Time for a Repeated Start		<b>600</b>			ns
$t_{HD;DAT}$	Data Hold Time		<b>0</b>			ns
$t_{SU;DAT}$	Data Setup Time		<b>100</b>			ns
$t_{SU;STO}$	Set-up Time for Stop Condition		<b>600</b>			ns
$t_{VD;DAT}$	Data Valid Time				<b>900</b>	ns
$t_{VD;ACK}$	Data Valid Acknowledge Time				<b>900</b>	ns
$t_{BUF}$	Bus Free Time Between a Start and a Stop Condition		<b>1.3</b>			$\mu\text{s}$

(7) Specified by design. Not production tested.

Typical Performance Characteristics

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1 \mu H$  (TOKO FSD0312-1R0),  $R_L = 43 m\Omega$ ,  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

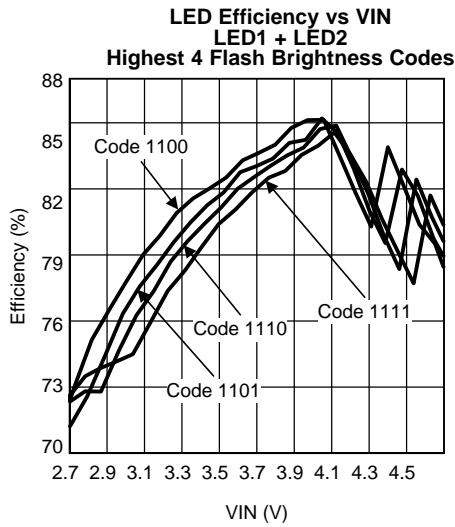


Figure 1.

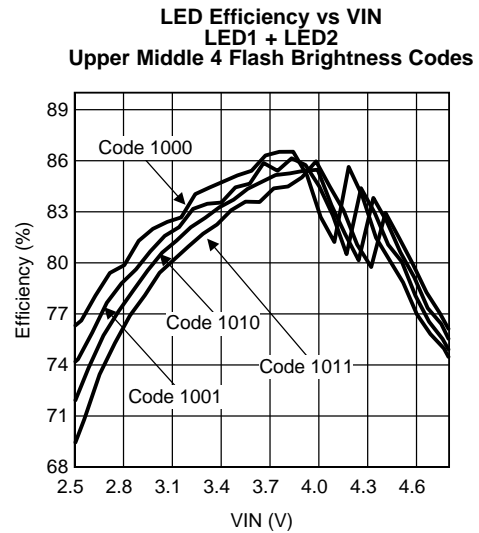


Figure 2.

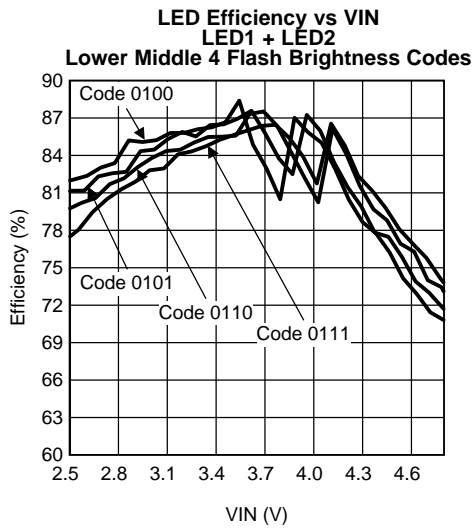


Figure 3.

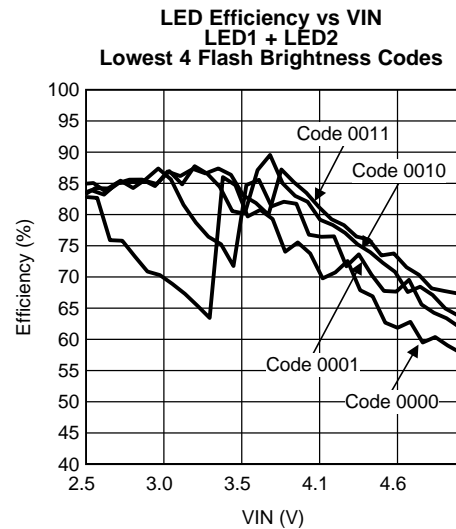


Figure 4.

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Typical Performance Characteristics (continued)

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1 \mu H$  (TOKO FDSD0312-1R0,  $R_L = 43 \text{ m}\Omega$ ),  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

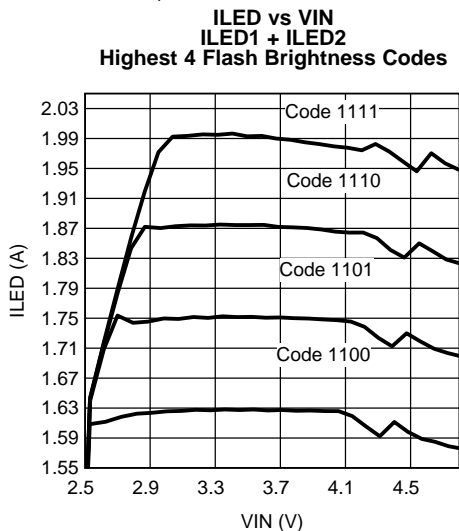


Figure 5.

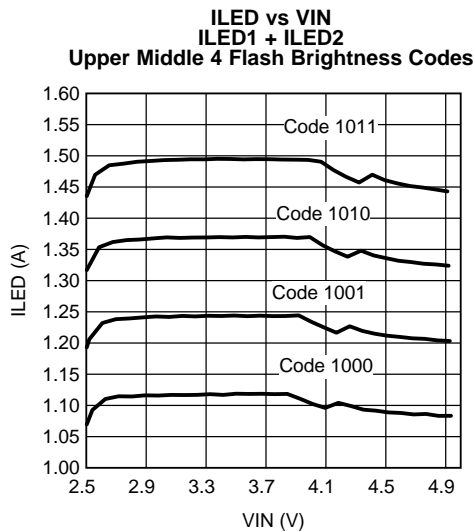


Figure 6.

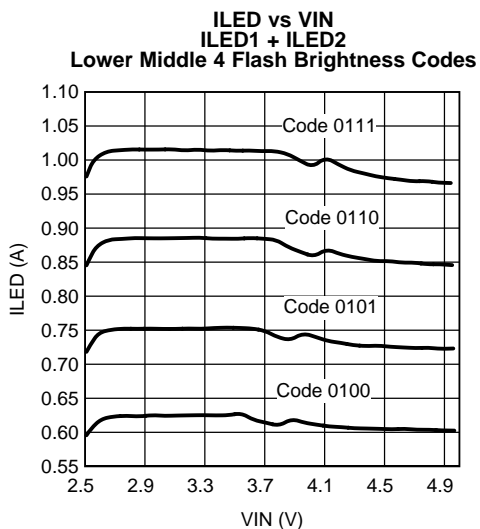


Figure 7.

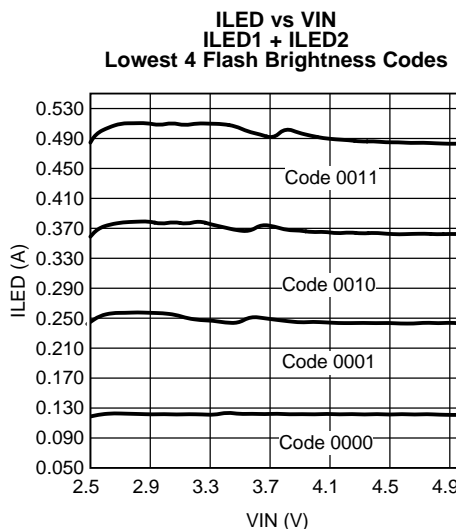


Figure 8.

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**Typical Performance Characteristics (continued)**

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1 \mu H$  (TOKO FDSD0312-1R0,  $R_L = 43 m\Omega$ ),  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

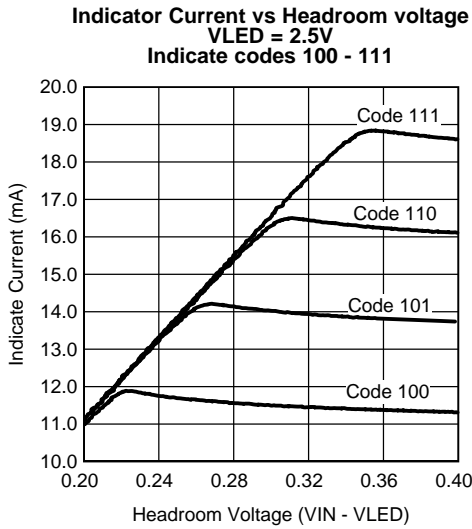


Figure 9.

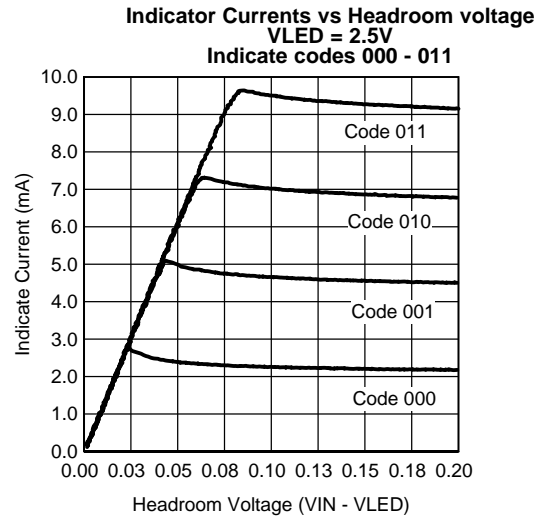


Figure 10.

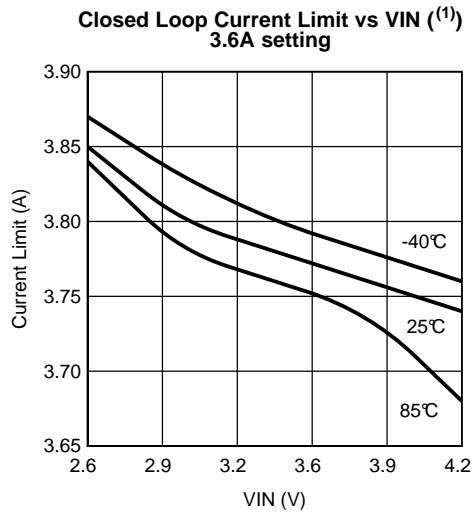


Figure 11.

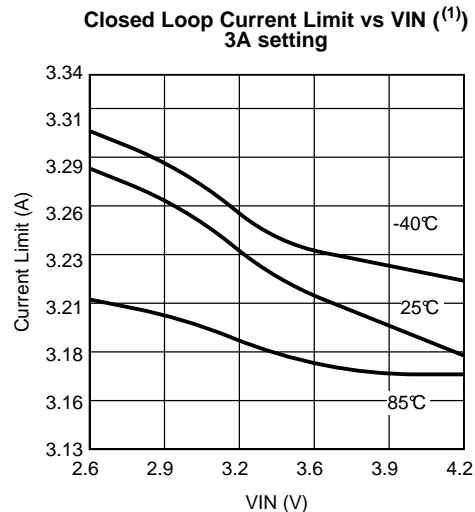


Figure 12.

(1) The typical curve for Current Limit is measured in closed loop using the typical application circuit by increasing  $I_{OUT}$  until the peak inductor current stops increasing. The value given in the Electrical Table is measured open loop and is found by forcing current into SW until the current limit comparator threshold is reached. Closed loop data appears higher due to the delay between the comparator trip point and the NFET turning off. This delay allows the closed loop inductor current to ramp higher after the trip point by approximately  $20ns \times V_{IN}/L$

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Typical Performance Characteristics (continued)

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1\mu H$  (TOKO FDSD0312-1R0,  $R_L = 43 m\Omega$ ),  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

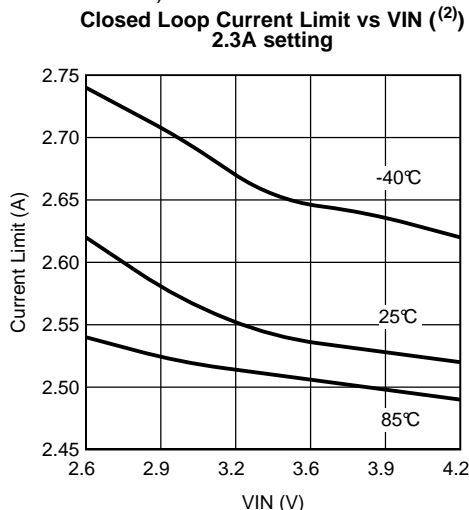


Figure 13.

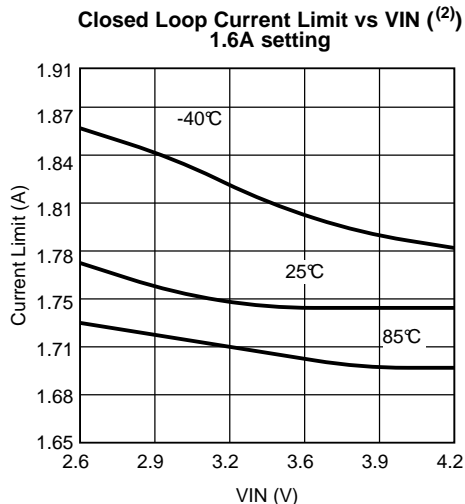


Figure 14.

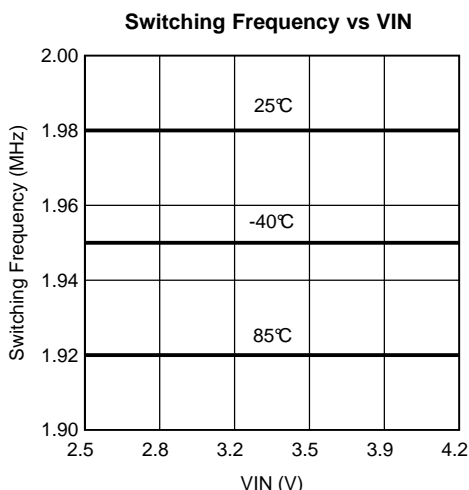


Figure 15.

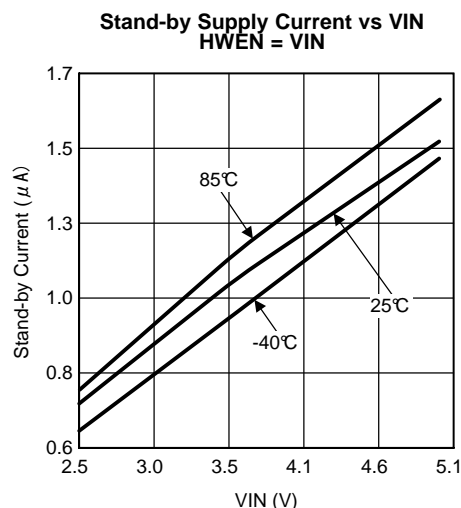


Figure 16.

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(2) The typical curve for Current Limit is measured in closed loop using the typical application circuit by increasing  $I_{OUT}$  until the peak inductor current stops increasing. The value given in the Electrical Table is measured open loop and is found by forcing current into SW until the current limit comparator threshold is reached. Closed loop data appears higher due to the delay between the comparator trip point and the NFET turning off. This delay allows the closed loop inductor current to ramp higher after the trip point by approximately  $20ns \times V_{IN}/L$

Typical Performance Characteristics (continued)

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1 \mu H$  (TOKO FDSD0312-1R0,  $R_L = 43 m\Omega$ ),  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

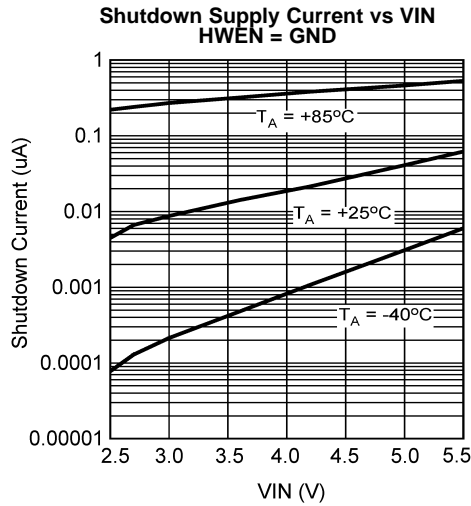


Figure 17.

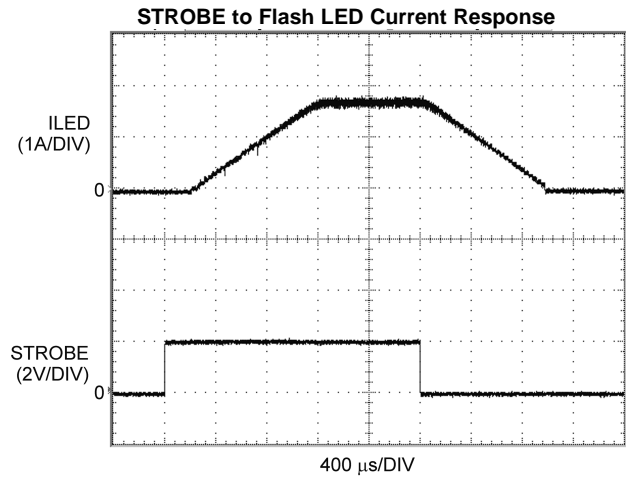


Figure 18.

**VIN Monitor Operation**  
 $V_{IN\_TH} = 3.2V$   
Force Torch Mode, TX2 set for Interrupt Output (INT)  
Circuit of Figure 37 (Note B)

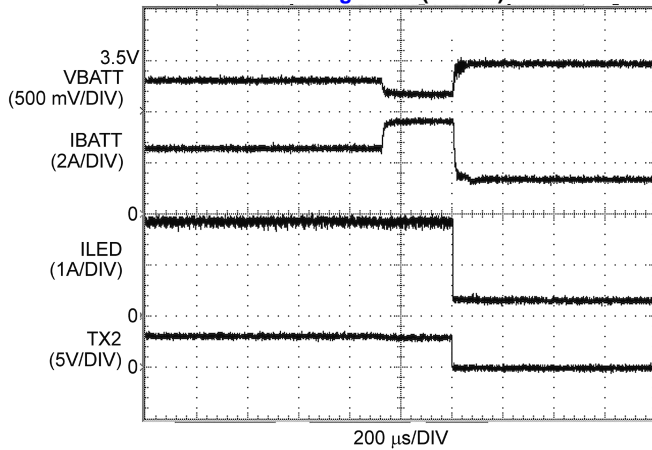


Figure 19.

**Vin Flash Monitor Operation**  
 $V_{IN\_FLASH\_TH} = 3.2V$   
TX2 set for Interrupt Output (INT)  
Circuit of Figure 37 (Note A)

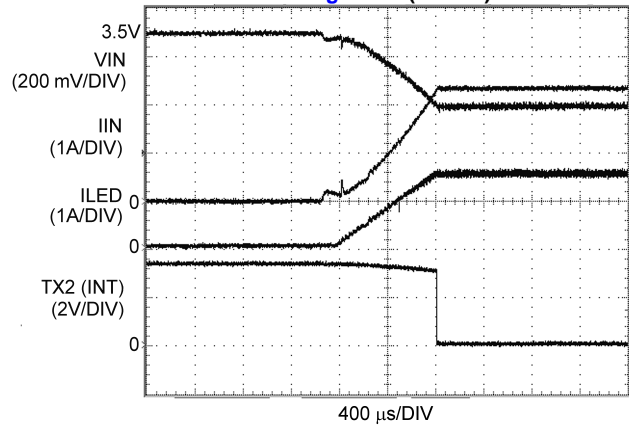


Figure 20.

PRODUCT PREVIEW

Typical Performance Characteristics (continued)

( $V_{IN} = 3.6V$ ,  $C_{OUT} = 10 \mu F$ ,  $C_{IN} = 10 \mu F$ ,  $L = 1 \mu H$  (TOKO FDSD0312-1R0,  $R_L = 43 \text{ m}\Omega$ ),  $T_A = 25^\circ C$ ,  $I_{LED} = I_{LED1} + I_{LED2}$ , unless otherwise noted).

**NTC Operation**  
 NTC set to force torch mode  
 TX2 set for Interrupt Output (INT)  
 Circuit of Figure 45,  $R_3 = 1.3 \text{ k}\Omega$ ,  $R_{NTC} = 10 \text{ k}\Omega @ +25^\circ C$ ,  
 Beta = 3380K

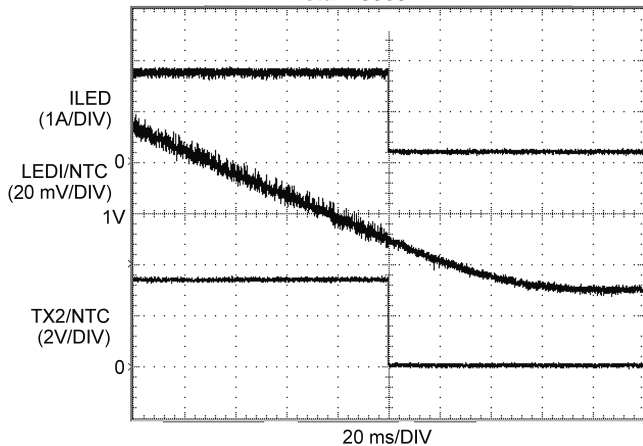


Figure 21.

**AET Operation**

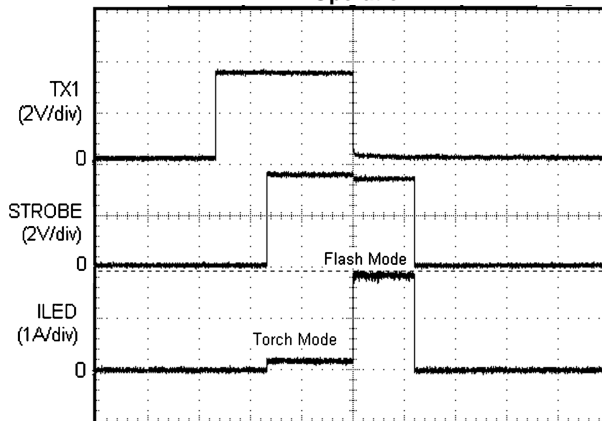


Figure 22.

**HWEN Operation**  
 Device Enabled in Flash Mode

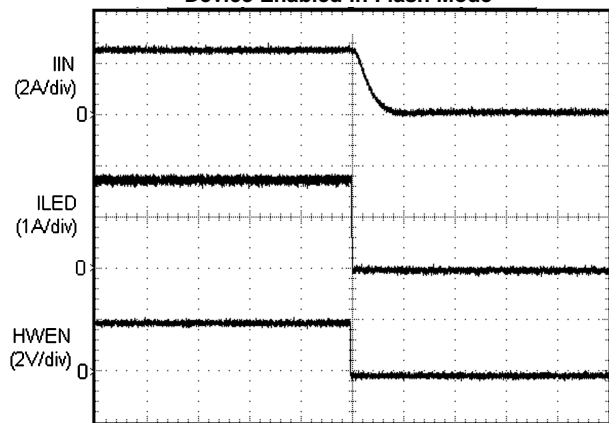


Figure 23.

**TX1 Interrupt (Force Torch)**

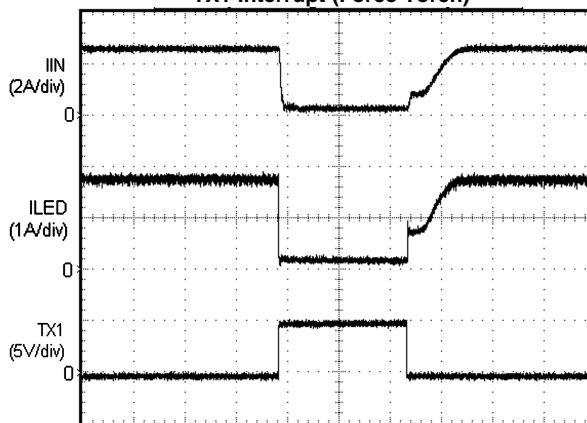
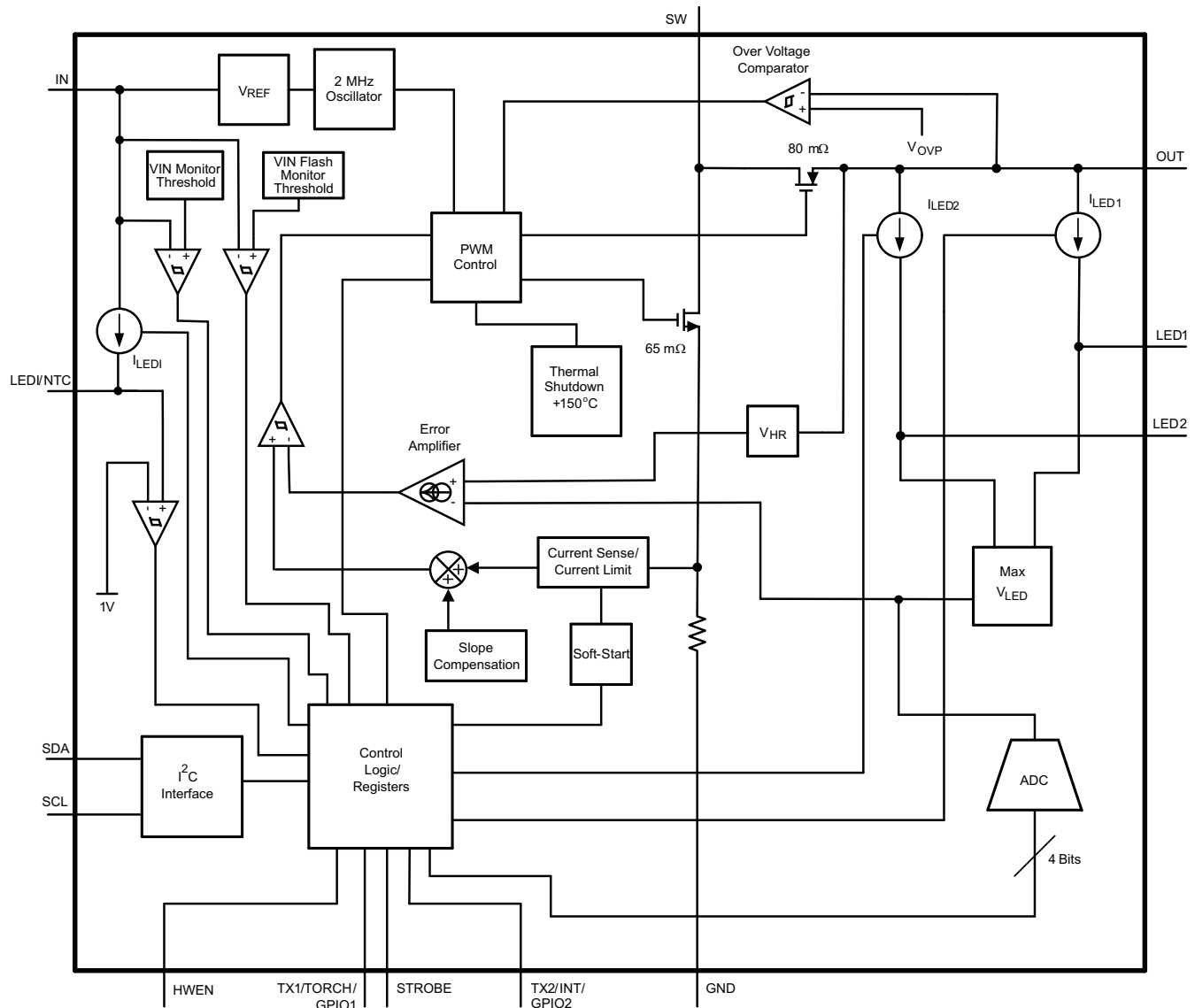


Figure 24.

PRODUCT PREVIEW

## BLOCK DIAGRAM



## DEVICE INFORMATION

### Overview

The LM3560 is a high-power white LED flash driver capable of delivering up to 2A of LED current into a single LED, or up to 1A into two parallel LEDs. The device incorporates a 2MHz constant frequency, synchronous boost converter, and two high-side current sources to regulate the LED current over the 2.5V to 5.5V input voltage range.

During operation when the output voltage is greater than  $V_{IN} - 150\text{ mV}$  the boost converter switches and maintains at least 300 mV across both current sources (LED1 and LED2). This minimum headroom voltage ensures that the current sources remain in regulation. When the input voltage rises above the LED voltage + current source headroom voltage, the device stops switching and turns the PFET on continuously (Pass mode). In Pass mode the difference between  $(V_{IN} - I_{LED} \times R_{ON\_P})$  and the voltage across the LED's is dropped across the current sources.

Four hardware control pins provide control of the LM3560. These include a hardware Flash Enable (STROBE), Dual Flash Interrupt inputs (TX1 and TX2) designed to interrupt the flash pulse during high battery current conditions, and a logic high hardware enable (HWEN) that can be pulled low to rapidly place the device into shutdown. Additional features of the LM3560 include an internal 4-bit ADC for LED voltage monitoring, an internal comparator for LED thermal sensing via an external NTC thermistor, an input voltage monitor that can reduce the Flash current during input undervoltage conditions, a low-power message indicator LED current source, and a mode for utilizing the flash LEDs as a privacy indicator.

Control of the LM3560 is done via an I<sup>2</sup>C-compatible interface. This includes adjustment of the Flash and Torch current levels, adjustment of the indicator LED currents, changing the Flash Timeout Duration, changing the switch current limit, and reading back the ADC results. Additionally, there are 8 flag bits that indicate flash current time-out, LED over-temperature, LED failure (LED short or output OVP condition), device thermal shutdown, V<sub>IN</sub> under voltage condition, V<sub>IN</sub> Flash Monitor undervoltage condition, and the occurrence of a TX1 or TX2 interrupt.

## STARTUP (ENABLING THE DEVICE)

Turn-on of the LM3560 is done through bits [1:0] of the Enable Register. These bits enable the device in Torch mode, Flash mode, or Privacy Indicate mode. Additionally, bit 6 of the Enable Register enables the message indicator at the LED1/NTC pin. On startup, when V<sub>OUT</sub> is less than V<sub>IN</sub>, the internal synchronous PFET turns on as a current source and delivers 350 mA to the output capacitor. During this time both current sources (LED1, and LED2) are off. When the voltage across the output capacitor reaches 2.2V the current sources can turn on. At turn-on the current sources step through each FLASH and TORCH level until their target LED current is reached (32 μs/step). This gives the device a controlled turn-on and limits inrush current from the V<sub>IN</sub> supply.

## INDEPENDENT LED CONTROL

Bits [4:3] of the Enable register provide for independent turn-on and turn-off of the LED1 or LED2 current sources. Once enabled, the LED current is adjusted by writing to the Torch Brightness or Flash Brightness Registers depending on whether Flash or Torch mode is selected. Both the Torch Brightness and the Flash Brightness Registers provide for independent current programming for the LED currents in either LED1 or LED2. (See [TORCH BRIGHTNESS REGISTER DESCRIPTIONS \(Address 0xA0\)](#) and [FLASH BRIGHTNESS REGISTER \(Address 0xB0\)](#).)

## PASS MODE

On turn-on when the output voltage charges up to (V<sub>IN</sub> – 150 mV), the LM3560 will decide if the part operates in Pass Mode or Boost mode. If the voltage difference between V<sub>OUT</sub> and V<sub>LED</sub> is less than 300 mV, the device operates in Boost Mode. If the difference between V<sub>OUT</sub> and V<sub>LED</sub> is greater than 300 mV, the device operates in Pass Mode. In Pass Mode the boost converter stops switching and the synchronous PFET turns fully on bringing V<sub>OUT</sub> up to (V<sub>IN</sub> – I<sub>IN</sub> × R<sub>PMOS</sub>) where R<sub>PMOS</sub> = 80 mΩ. In Pass Mode the inductor current is not limited by the peak current limit. In this situation the output current must be limited to 3A.

## OVER-VOLTAGE PROTECTION

The output voltage is limited to typically 5V (5.075V max). In situations such as the current source open, the LM3560 will raise the output voltage to try to keep the LED current at its target value. When V<sub>OUT</sub> reaches 5V the over-voltage comparator will trip and turn off both the internal NFET and PFET. When V<sub>OUT</sub> falls below 4.8V (typical), the LM3560 will begin switching again.

## CURRENT LIMIT

The LM3560 features 4 selectable current limits of 1.6A, 2.3A, 3.0A, and 3.6A. These are programmable through the I<sup>2</sup>C-compatible interface via bits [6:5] of the Flash Duration Register. When the current limit is reached, the LM3560 stops switching for the remainder of the switching cycle.

Since the current limit is sensed in the NMOS switch there is no mechanism to limit the current when the device operates in Pass Mode. In situations where there could potentially be large load currents at OUT, and the LM3560 is operating in Pass mode, the load current must be limited to 3A. In Boost mode or Pass mode if V<sub>OUT</sub> falls below approximately 2.3V, the part stops switching and the PFET operates as a current source, limiting the current to typically 350 mA. This prevents damage to the LM3560 and excessive current draw from the battery during output short-circuit conditions.

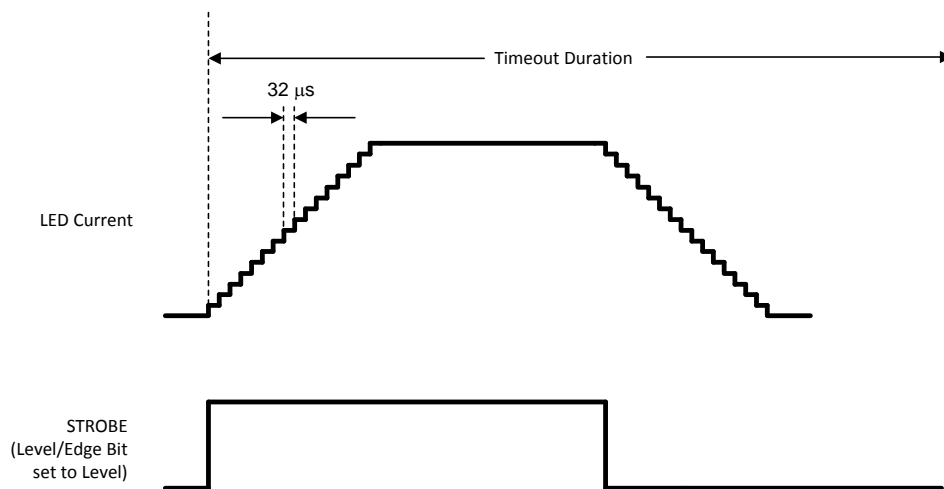
## THERMAL SHUTDOWN

The LM3560 features a thermal shutdown threshold of typically +150°C. When the device's die temperature reaches +150°C the active current sources (LED1 and/or LED2) will shut down, and the TSD flag in the Flags register is written high. The device cannot be started up again until the Flags register is read back. Once the Flags register is read back either current source can be re-enabled into Privacy, Torch, or Flash Mode. The thermal shutdown (TSD) circuitry has an internal 250  $\mu$ s de-glitch timer which helps prevent unwanted noise from falsely triggering a TSD event. However, when the LM3560 is in boost mode at higher flash currents, the de-glitch timer can get reset by the high currents in the LM3560's GND. As a result the thermal shutdown's internal de-glitch timer can be reset before the TSD event can get latched in. This prevents a TSD event from being triggered until the LM3560's flash pulse reaches the end of the flash duration, when the noisy currents have dropped to a lower level. However, once the noise is lower, and a TSD event is triggered, the next flash pulse is not allowed until the flags register is read back. In pass mode the boost switcher is off and the lower noise environment allows the device's TSD circuitry to shut down immediately when the die temperature reaches +150°C.

## FLASH MODE

In Flash mode the LED current sources (LED1 and LED2) each provide 16 different current levels from typically 62.5 mA (total) to 2A (total) in steps of 62.5 mA. The Flash currents are adjusted via the Flash Brightness Register. Flash mode is activated by writing a (1, 1) to bits [1:0] of the Enable Register or by enabling the hardware flash input (STROBE) via bit [2] of Configuration Register 1, and then pulling the STROBE pin high (high polarity). Once the Flash sequence is activated the active current sources (LED1 and/or LED2) will ramp up to their programmed Flash current level by stepping through all Torch and Flash levels (32  $\mu$ s/step) until the programmed current is reached.

Bit [5] of the Enable Register (STROBE Level/Edge bit) determines how the Flash pulse terminates after STROBE goes high. With the Level/Edge bit = 1, the Flash current will only terminate when it reaches the end of the Flash Timeout period. With the Level/Edge bit = 0, Flash mode can be terminated by pulling STROBE low, programming bits [1:0] of the Enable Register with (0,0), or by allowing the Flash Timeout period to elapse. If the Level/Edge bit = 0 and STROBE is toggled before the end of the Flash Timeout period, the Timeout period will reset. [Figure 25](#) and [Figure 26](#) detail the Flash pulse termination for the different Level/Edge bit settings.



**Figure 25. LED Current for STROBE (Level Triggered, Enable Register Bit 5 = 0)**

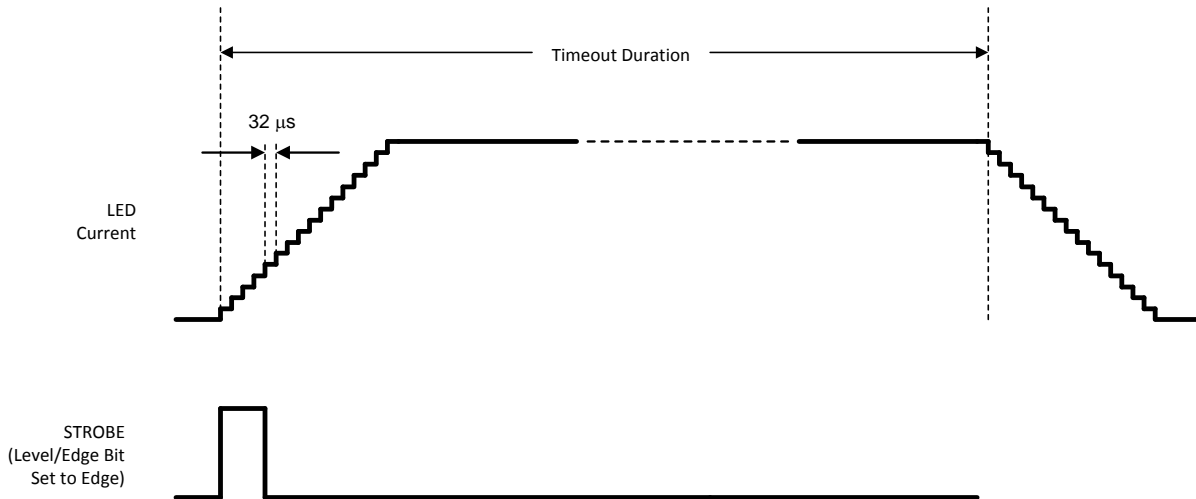


Figure 26. LED Current for STROBE (Edge Triggered, Enable Register Bit 5 = 1)

After the Flash pulse terminates, either by a flash timeout, pulling STROBE low, or disabling it via the I<sup>2</sup>C-compatible interface, LED1 and LED2 turn completely off. This happens even when Torch is enabled via the I<sup>2</sup>C-compatible interface and the Flash pulse is turned on by toggling STROBE. After a Flash event ends, bits [1:0] of the Enable Register are automatically reset with (0, 0). The exception occurs when the Privacy Terminate Bit is low (bit [3]) in the Privacy Register. In this case, the specific current source that is enabled for privacy mode will turn back on after the flash pulse.

### FLASH TIMEOUT

The Flash Timeout period sets the maximum amount of time that the Flash Current will be sourced from current sources LED1 and LED2. Bits [4:0] of the Flash Duration Register set the Flash Timeout period. There are 32 different Flash Timeout durations in steps of 32 ms giving a Flash Timeout range of 32 ms to 1024 ms (see Table 16).

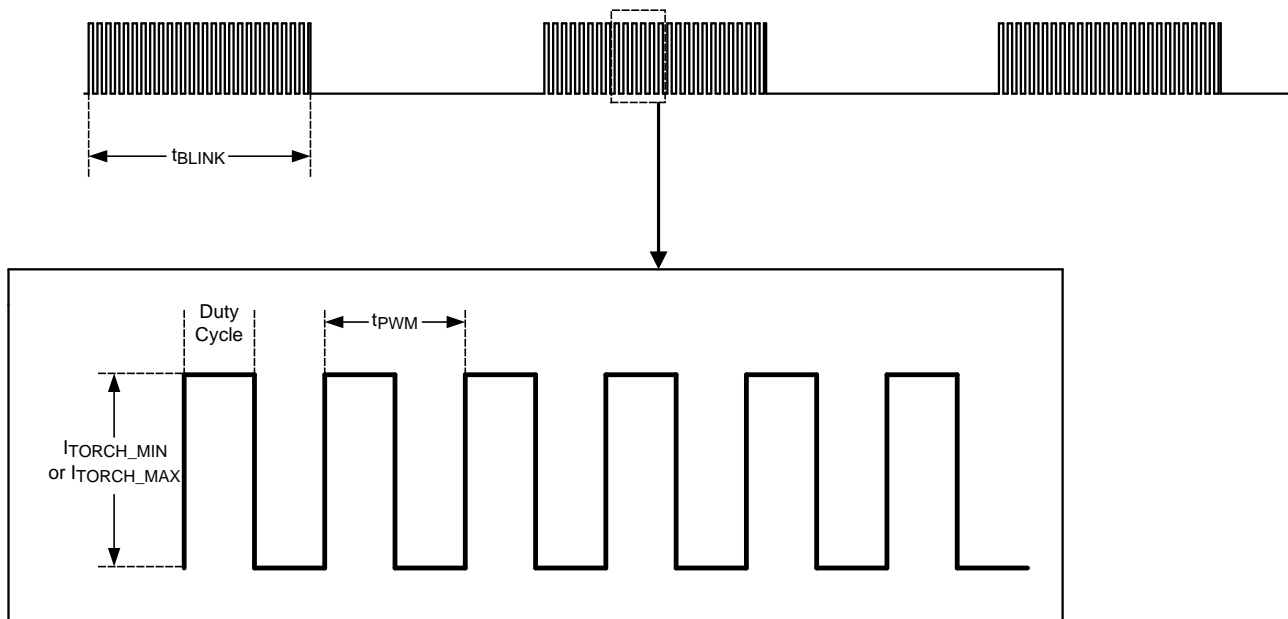
### TORCH MODE

In Torch mode the current sources LED1 and LED2 each provide 8 different current levels (Table 14). Torch mode is activated by setting Enable Register bits [1:0] to (1, 0). Once Torch mode is enabled, the current sources will ramp up to the programmed Torch current level by stepping through all of the Torch currents at (32 µs/step) until the programmed Torch current level is reached.

### PRIVACY INDICATOR MODE

The current sources (LED1 and/or LED2) can also be used as a privacy indicator before and after flash mode. Privacy indicate mode is enabled by setting the Enable Register bit [1:0] to (0, 1). Privacy mode is configured via the Privacy Register. This allows the selection of which current source to use as the privacy indicator (either LED1, LED2, or both), whether or not the privacy indicate mode turns off at the end of the flash pulse, the 3 selectable privacy blink periods ( $t_{BLINK}$ ), and the 8 duty cycle settings for the privacy indicator average current.

The intensity of the LEDs in privacy indicate mode is set by PWM controlling either the lowest Torch current level (31.25 mA per current source) or the highest Torch current level (250 mA per current source). Bit [2] in the Enable register selects between these two levels. Bits [2:0] in the Privacy Register select the 8 different duty cycles of 10%, 20%, 30%, 40%, 50%, 60%, 70%, and 80%. This enables privacy mode to have a PWM-controlled torch current with a wide number of values (see Table 2). The privacy blink options ( $t_{BLINK}$ ) are set via bit [7:6] of the Privacy Register. Selectable options are 128 ms, 256 ms, 512 ms, or always on. The blink pulse period is set to  $2 \times t_{BLINK}$ . Figure 27 details the timing for the Privacy Indicate Mode timing on ILED1 or ILED2.



- $t_{BLINK}$  set via bits [7:6] of Privacy Register
- Duty cycle set via bits [2:0] of Privacy Register
- $t_{PWM}$  set via bits [2:0] of the Privacy PWM Register

**Figure 27. Privacy Indicate Timing**

**Table 2. Privacy Indicate (PWM'd Torch) Possible Current Settings<sup>(1)</sup>**

Privacy Current Setting (Enable Register Bit [2]) 0 = 31.25mA peak 1 = 250mA peak	Privacy Indicate Duty Cycle Privacy Register Bits[2:0] see (Table 5)	ILED1 or ILED2 (Single LED)
0	000	3.125 mA
0	001	6.25 mA
0	010	9.375 mA
0	011	12.5 mA
0	100	15.625 mA
0	101	18.75 mA
0	110	21.875 mA
0	111	25 mA
1	000	25 mA
1	001	50 mA
1	010	75 mA
1	011	100 mA
1	100	125 mA
1	101	150 mA
1	110	175 mA
1	111	200 mA

(1) The listed current is with 1 current source active



## POWER AMPLIFIER SYNCHRONIZATION (TX1)

The TX1/TORCH/GPIO1 pin has a triple function. With Configuration Register 1 Bit [7] = 0 (default) TX1/TORCH/GPIO1 is a Power Amplifier Synchronization input (TX1 mode). This mode is designed to reduce the flash LED current when TX1 is driven high (active high polarity) or driven low (active low polarity). When the LM3560 is engaged in a Flash event and TX1/TORCH is driven high, the active current sources (LED1 and/or LED2) are forced into Torch mode at the programmed Torch current setting. If TX1 is then pulled low before the Flash pulse terminates, the LED current will return to the previous Flash current level. At the end of the Flash timeout, whether the TX1/TORCH pin is high or low, the LED current will turn off.

The polarity of TX1 can be changed from active high to active low by writing a 0 to bit [5] of Configuration Register 1. With this bit set to '0' the LM3560 will be forced into Torch mode when TX1/TORCH is pulled low. [Figure 28](#) details the functionality of the TX1 Interrupt.

### TX1 Shutdown

TX1 also has the capability to force shutdown. Bit [4] of Configuration Register 2 set to a '1', changes TX1 from a force Torch when active to a force shutdown when active. For example, if TX1/TORCH/GPIO1 is configured for TX1 mode with active high polarity, and bit[4] of Configuration Register 2 is set to '1', then when TX1 is driven high, the active current sources (LED1 and/or LED2) will be forced into shutdown. Once the active current sources are forced into shutdown by activating TX1, the current sources can only be re-enabled into flash mode if TX1 is pulled low and the Flags Register is read back. If only the Flags register is read back and TX1 is kept high the device will be re-enabled into torch mode and not shutdown. This occurs because the TX1 shutdown feature is an edge-triggered event. With active high polarity the TX1 shutdown requires a rising edge at TX1 in order to force the current source into shutdown. Once shut down, it takes a read back of the flags Register and another rising edge at TX1 to force shutdown again. [Figure 30](#) details the different responses of the TX1 shutdown mode.

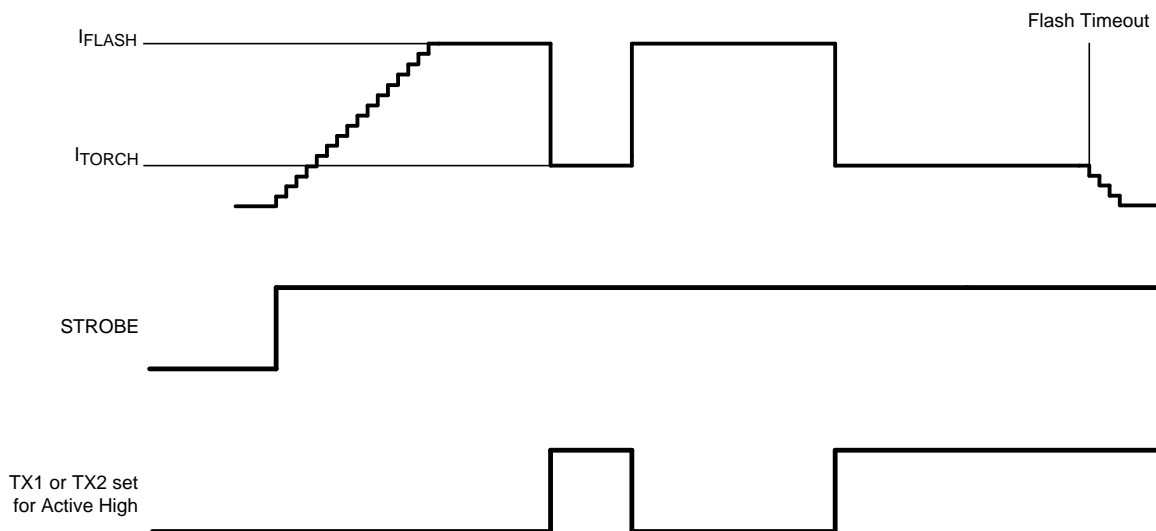
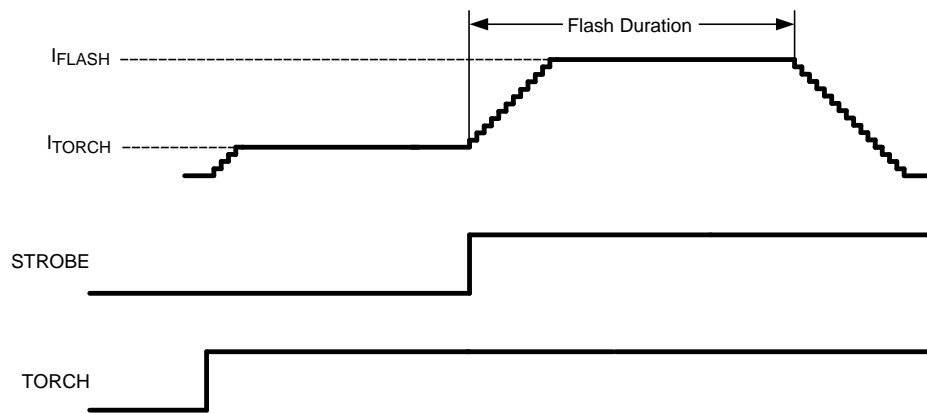


Figure 28. TX1 or TX2 Interrupt (Force Torch) Response

### HARDWARE TORCH

With Configuration Register 1 Bit [7] = 1, TX1/TORCH/GPIO1 is configured as a hardware Torch mode enable. In this mode, a high at TX1/TORCH turns on the LED current at the programmed Torch current setting. The STROBE input and I<sup>2</sup>C Enabled flash takes precedence over TORCH mode. In hardware torch mode, both LED1 and LED2 current sources will turn off after a flash event and Configuration Register 1 Bit [7] will be reset to 0. In this situation, to re-enter torch mode via hardware torch, the hardware torch enable bit (Configuration Register 1 Bit [7]) must be reset to 1. [Figure 29](#) details the functionality of hardware torch mode.



**Figure 29. Hardware Torch Mode**

### GPIO1 MODE

With Bit [0] of the GPIO Register set to 1, the TX1/TORCH/GPIO1 pin is configured as a logic I/O. In this mode the TX1/TORCH/GPIO1 pin is readable and writable as a logic input/output via bits [2:1] of the GPIO Register. See [GPIO REGISTER \(Address 0x20\)](#) for programming the GPIO1 output.

### TX2/INT/GPIO2

The TX2/INT/GPIO2 pin has a triple function. In TX2 mode (Default) the TX2/INT/GPIO2 pin is an active high Flash interrupt. With GPIO Register bit [3] = 1 the TX2/INT/GPIO2 pin is configured as general purpose logic I/O (GPIO2). With GPIO Register bit [6] = 1 and with GPIO2 set for GPIO output, the TX2/INT/GPIO2 pin is an interrupt output

### TX2 MODE

In TX2 mode, when Configuration Register 1, bit [6] = 0, TX2 is an active low flash interrupt. Under this condition when the LM3560 is engaged in a Flash event and TX2 is pulled low, the active current source (LED1 and/or LED2) are forced into Torch mode. In TX2 mode with Configuration Register 1, bit [6] = 1, TX2 is configured for active high polarity. Under this condition, when the LM3560 is engaged in a Flash event and TX2 is driven high, the active current source (LED1 and/or LED2) are forced into Torch mode. During a TX2 interrupt event, if the TX2 input is disengaged, the LED current will return to the previous flash current level. [Figure 28](#) details the functionality of the TX2 Interrupt.

### TX2 Shutdown

TX2 also has the capability to force shutdown. When bit [0] of Configuration Register 2 is set to a '1', TX2 will force shutdown when active. For example, if TX2 is configured for TX2 mode with active high polarity, and bit [0] of Configuration Register 2 is set to '1' then when TX2 is driven high, the active current sources (LED1 and/or LED2) will be forced into shutdown. Once the active current sources are forced into shutdown by activating TX2, the current sources can only be re-enabled in flash mode if TX2 is pulled low and the Flags register is read back. If only the Flags register is read back and TX2 is kept high, the device will be re-enabled into torch mode and not shutdown. This occurs because the TX2 shutdown feature is an edge-triggered event. With active high polarity the TX2 shutdown requires a rising edge at TX2 in order to force the current sources into shutdown. Once shut down, it takes a read back of the flags Register and another rising edge at TX2 to force shutdown again. [Figure 30](#) details TX2 shutdown mode.

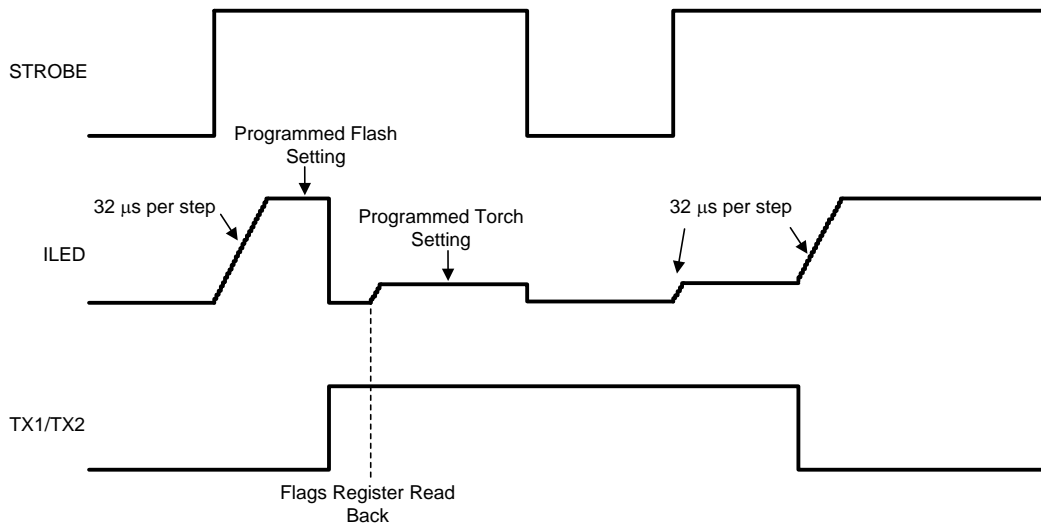


Figure 30. TX1 or TX2 (Force Shutdown) Response

### GPIO2 MODE

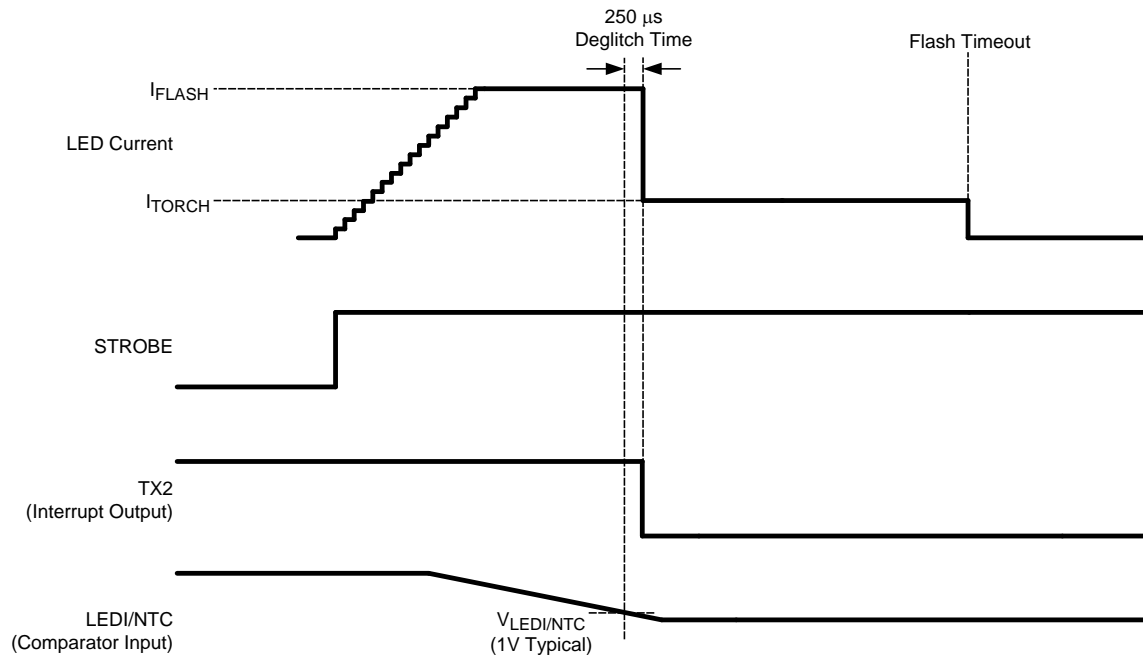
With Bit [3] of the GPIO Register set to 1, the TX2/INT/GPIO2 pin is configured as a logic I/O. In this mode the TX2/INT/GPIO2 pin is readable and writable as a logic input/output via bits [5:4] of the GPIO Register. See [Table 9](#) for programming the GPIO2 output.

### INTERRUPT OUTPUT (INT MODE)

The TX2/INT/GPIO2 pin can be reconfigured as an active low interrupt output by setting bit [6] in the GPIO Register to '1' and configuring TX2/INT/GPIO2 as a GPIO2 output (bits [4:3] of GPIO Register = 11). In this mode, TX2/INT/GPIO2 will pull low when any of these conditions exist.

1. The LM3560 is configured for NTC mode (Configuration Register 1 bit [4] = 1), and the voltage at LEDI/NTC has fallen below VTRIP (1V typical).
2. The LM3560 is configured for VIN Monitor mode (VIN Monitor Register bit [0] = 1), and VIN falls below the programmed VIN Monitor Threshold.
3. The LM3560 is configured for VIN Flash Monitor mode (VIN Monitor Register bit [3] = 1), and VIN falls below the programmed VIN Flash Monitor Threshold.

Once INT is pulled low due to any of the above conditions having been met, INT will only go high again if any of the conditions are no longer true and the Flags Register is read.



**Figure 31. TX2 As an Interrupt Output (During an NTC Event)**

### INDICATOR LED/THERMISTOR (LED1/NTC)

The LEDI/NTC pin serves a dual function: either as a programmable LED message indicator driver, or as a comparator input for negative temperature coefficient (NTC) thermistors.

### MESSAGE INDICATOR CURRENT SOURCE (LEDI/NTC)

LEDI/NTC is configured as a message indicator current source by setting Configuration Register 1 bit [4] = (0) default. The indicator current source is enabled/disabled via the Enable Register bit [6] = (1). Bit [7] of the Enable Register enables the Message Indicator in blink mode. If the message indicator is set for blinking mode, the pattern programmed into the Indicator Register, and Indicator Blinking Register is output on the Indicator current source.

The Indicator Blinking Register controls the following (see [Table 7](#)):

1. Number of blank periods (BLANK #). This has 16 settings.  $t_{BLANK} = t_{ACTIVE} \times BLANK\#$ , where  $t_{ACTIVE} = t_{PERIOD} \times PERIOD\#$
2. Pulse width ( $t_{PULSE}$ ) has 16 settings between 0 and 480 ms in steps of 32 ms. The pulse width is the duration that the indicator current is at its programmed set point at the end of the ramp-up time.

The Indicator Register controls the following (see [Table 6](#)):

1. Indicator current level ( $I_{IND}$ ). There are 8 indicator current levels from 2.25 mA to 18 mA in steps of 2.25 mA.
2. Number of periods (PERIOD #). This has 8 steps. A period ( $t_{PERIOD}$ ) is found by ( $t_{PERIOD} = t_R + t_F + 2 \times t_{PULSE}$ ). (see [Figure 32](#) for indicator timing).
3. Ramp times ( $t_R$  or  $t_F$ ) for turn-on and turn-off of the indicator current source. Four programmable times of 78 ms, 156 ms, 312 ms, and 624 ms are available. The ramp times apply for both ramp-up and ramp-down and are not independently changeable.

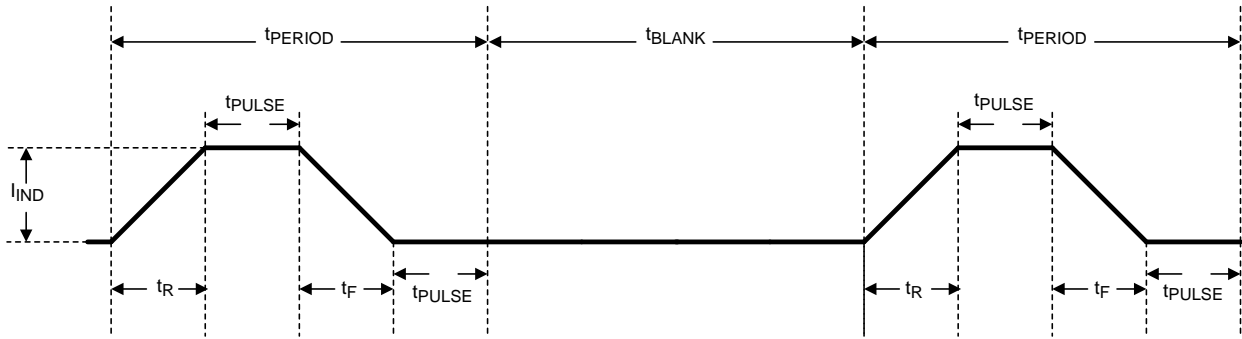


Figure 32. Message Indicator Timing Diagram

**MESSAGE INDICATOR EXAMPLE 1 (Single Pulse with Dead Time):**

As an example, to set up the message indicator for a 312 ms ramp-up and ramp-down, 192 ms pulse width, and 1 pulse followed by a 5s delay. The indicator settings will be as follows.  $t_R = t_F = 312$  ms,  $t_{WIDTH} = 192$  ms ( $t_{PERIOD} = 312$  ms  $\times$  2 + 192 ms  $\times$  2 = 1016 ms). BLANK# setting will be: 5s/1016 ms  $\times$  1 (PERIOD# = 1). Giving a BLANK# setting of 5. The resulting waveform will appear as:

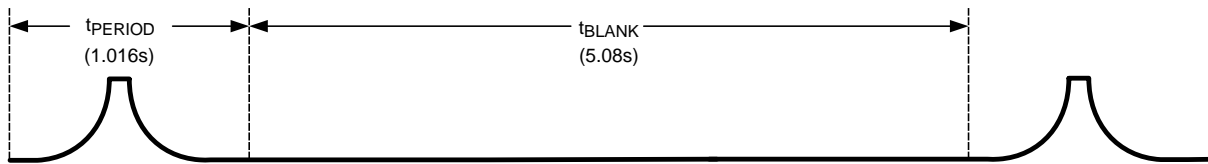


Figure 33. Message Indicator Example 1

**MESSAGE INDICATOR EXAMPLE 2 (Multiple Pulses with Dead Time):**

Another example has the same  $t_R$ ,  $t_F$ ,  $t_{PULSE}$ , and  $t_{BLANK}$  times as before, but this time the PERIOD# is set to 3. Now the  $t_{ACTIVE}$  time is  $t_{PERIOD} \times 3 = 1016$  ms  $\times$  3 = 3048 ms. This results in a blank time of  $t_{BLANK} = t_{ACTIVE} \times BLANK\# = 3.048$  s  $\times$  5 = 15.24s

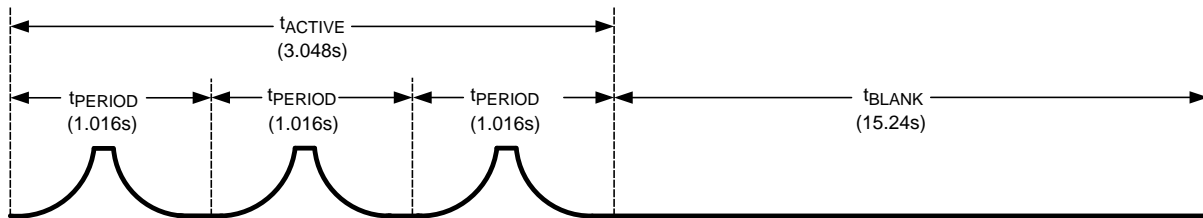


Figure 34. Message Indicator Example 2

**UPDATING THE MESSAGE INDICATOR**

The best way to update the message indicator is to disable the Message Indicator output via the Enable Register bit [6], then write the new sequence to the Indicator Register and/or Indicator Blinking Register, and then re-enable the Message Indicator. Updating the Indicator Registers while it is active can lead to long delays between pattern changes. This is especially true if the PERIOD#, or BLANK# setting is changed from a high setting to a lower setting.

**NTC MODE**

Writing a (1) to Configuration Register 1 bit [4] configures the LEDI/NTC pin for NTC mode. In this mode the indicator current source is disabled, and LEDI/NTC becomes the positive input to the an internal comparator. NTC mode operates as a LED current interrupt that is triggered when the voltage at LEDI/NTC goes below 1V.

PRODUCT PREVIEW

Two actions can be taken when the NTC comparator is tripped. With Configuration Register 2 bit [1] set to '0' the NTC interrupt will force the LED current from Flash mode into Torch mode. With Configuration Register 2 bit [1] set to '1', the NTC interrupt will force the LED current into shutdown.

Whether in NTC force torch or NTC shutdown, in order to re-enter flash mode after an NTC event, two things must occur. First, the NTC input must be above the 1V threshold. Secondly, the Flags Register must be read.

To avoid noise from falsely triggering the NTC Comparator, this mode incorporates a 250  $\mu$ s de-glint timer. With NTC mode active,  $V_{LED/NTC}$  must go below the trip point ( $V_{TRIP}$ ) and remain below it for 250  $\mu$ s before the LEDs are forced into Torch mode (or shutdown) and the NTC Flag is written.

### ALTERNATE EXTERNAL TORCH (AET MODE)

With Configuration Register 2 bit [2] set to '1', the LM3560 is configured for AET mode, and the operation of TX1/TORCH becomes dependent on its occurrence relative to the STROBE input. In this mode, if TX1/TORCH goes high first, then STROBE goes high, the LEDs are forced into Torch mode with no timeout. In this mode, if TX1/TORCH goes high after STROBE has gone high, then the TX1/TORCH pin operates as a normal LED current interrupt (TX1), and the LEDs will turn off at the end of the timeout duration (see Figure 35).

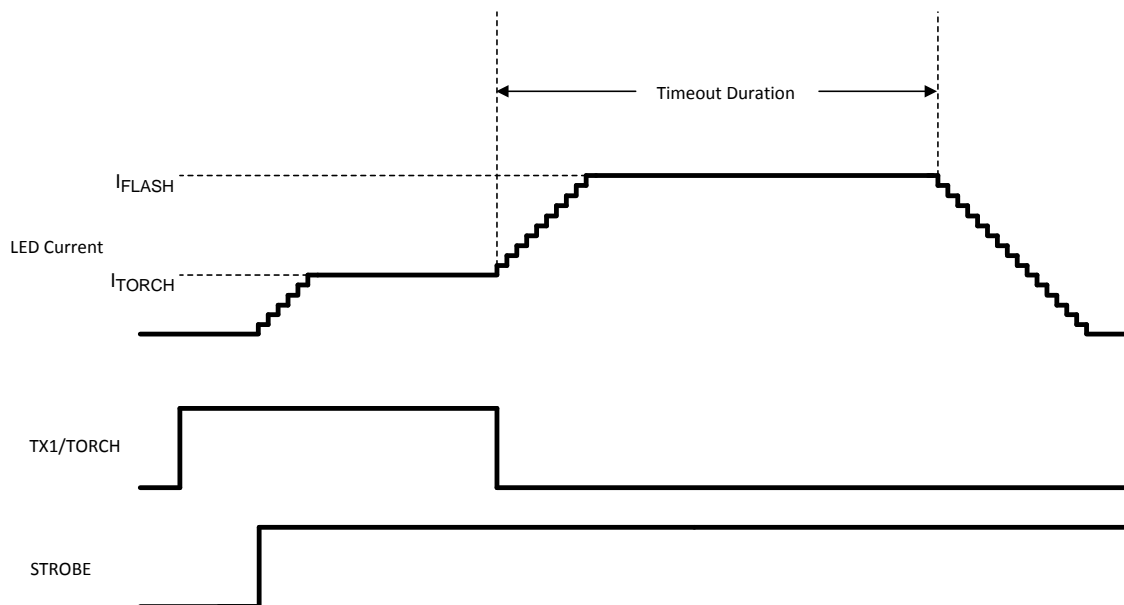


Figure 35. AET Mode Timing

### INPUT VOLTAGE MONITOR

The LM3560 has an internal comparator at IN which monitors the input voltage and can force the LED current into Torch mode or into shutdown if  $V_{IN}$  falls below the programmable VIN Monitor Threshold. Bit 0 in the VIN Monitor Register enables or disables this feature. When enabled, Bits [2:1] program the 4 adjustable thresholds of 2.9V, 3.0V, 3.1V, and 3.2V. Bit 3 in Configuration Register 2 selects whether a VIN Monitor event forces Torch mode or forces LED1 and/or LED2 into shutdown. See Table 12 for additional information. When the input voltage monitor is active, and  $V_{IN}$  falls below the programmed VIN Monitor threshold, the LEDs will either turn off or be forced into the Torch current setting. To reset the LED current to its previous level, two things must occur. First,  $V_{IN}$  must go above the VIN Monitor threshold, and the Flags register must be read back. See Figure 36 for the VIN Monitor Timing Waveform.

To avoid noise from falsely triggering the VIN Monitor, this mode incorporates a 250  $\mu$ s de-glint timer. With the VIN Monitor active,  $V_{IN}$  must go below the VIN Monitor Threshold ( $V_{IN\_TH}$ ), and remain below it, for 250  $\mu$ s before the LEDs are forced into Torch mode (or shutdown) and the VIN Monitor Flag is written.

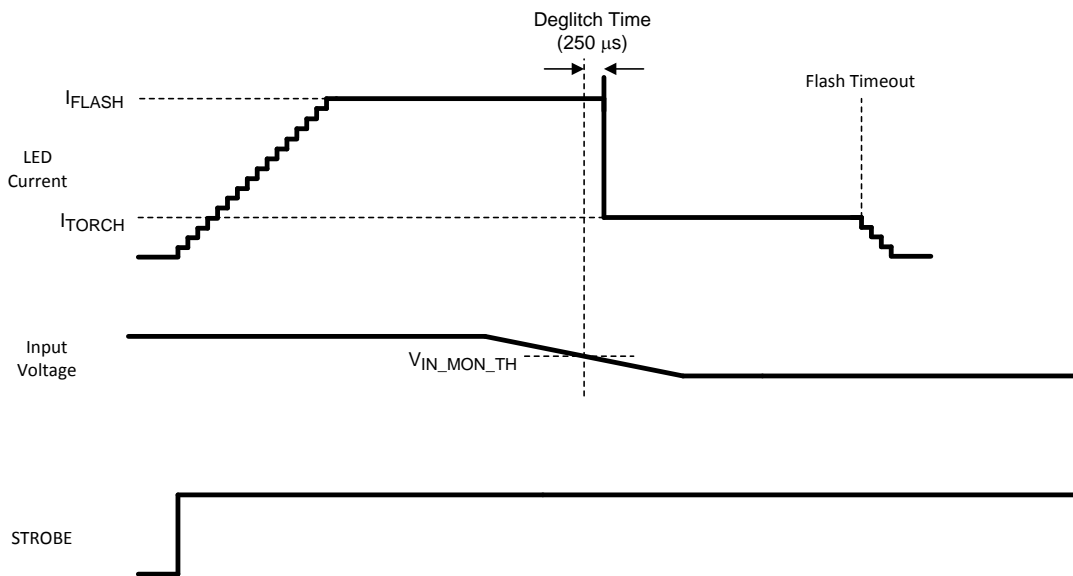
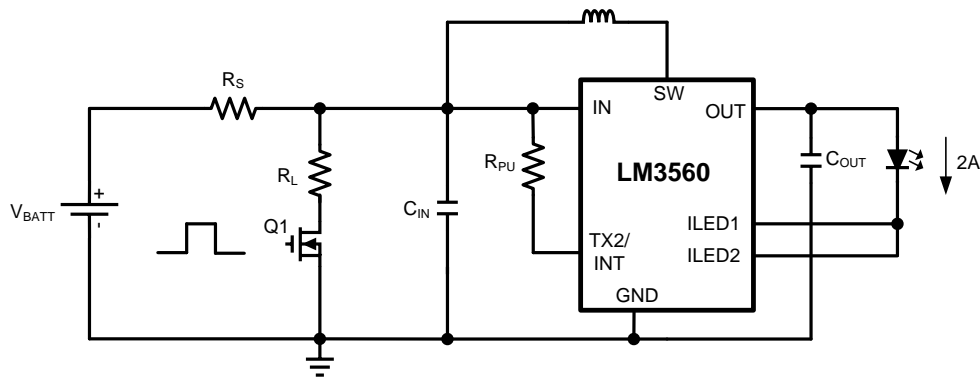


Figure 36. VIN Monitor Waveform



Note A: For the VIN flash monitor test, when the 2A flash starts up the voltage at IN begins to drop via the rising input current ramp and the source resistance  $R_S$ . As soon as the input voltage crosses the programmed VIN Flash Monitor Threshold the flash current ramp is stopped and the LM3560 flashes at the reduced current

Note B: For the VIN Monitor test, with a 2A flash current the voltage at IN is  $V_{BATT} - I_{BATT} \times R_S$ . When Q1 turns on the added load causes VIN to drop by the additional current ( $V_{IN}/R_L$ ) which flows through  $R_S$ . When VIN drops the programmed VIN Monitor threshold is crossed and the flash current pulse steps to the programmed torch current level causing VIN to step up.

Figure 37. VIN Monitor/VIN Flash Monitor Test Circuit

### INPUT VOLTAGE FLASH MONITOR (FLASH CURRENT RISING)

A second comparator at the IN terminal is available to monitor the input voltage during the flash current turn-on (Input Voltage Flash Monitor). Bit [3] of the VIN Monitor Register enables/disables this feature. With this bit set to '1', the VIN Flash Monitor is active, and bits [5:4] of the VIN Monitor Register program the 4 selectable thresholds of (2.9V, 3.0V, 3.1V, and 3.2V). The VIN Flash Monitor operates as follows: during flash current turn-on the current sources will transition through each of the lower flash current levels until the target flash current is reached. With the Input Voltage Flash Monitor active, if during the flash current turn-on the input voltage falls below the VIN Flash Monitor threshold, the flash current is stopped at the level that the current ramp had risen to, at the time of the VIN Flash Monitor event. The VIN Flash Monitor only operates during the ramping up of the flash LED current.

The VIN Flash Monitor ignores the first 2 flash codes during the flash current turn-on. As a result, if the VIN Flash Monitor is enabled and VIN were to fall below the VIN Flash Threshold as the LED current ramps up through either of the first two levels, then the flash pulse would not be halted until code #3 (168.75mA per current source).

To avoid noise from falsely triggering the VIN Flash Monitor, this mode incorporates an 8 $\mu$ s de-glitch timer as well as an internal analog filter at the input of the VIN Flash Monitor Comparator. With the VIN Flash Monitor active,  $V_{IN}$  must go below the VIN Flash Monitor Threshold ( $V_{IN\_FLASH}$ ), and remain below it, for 8 $\mu$ s before the flash current ramp is halted and the VIN Flash Monitor Flag is written.

### LAST FLASH REGISTER

Once the VIN Flash Monitor is tripped, the flash code that corresponded to the LED current at which the flash current ramp was halted is written to the Last Flash Register. The Last Flash Register is a read only register and has the lower 4 bits available to latch the code for LED1 and the upper 4 bits to latch the code for LED2.

For example, suppose that the LM3560 is set-up for a single LED with a target flash current of 1250 mA and the VIN Flash Monitor is enabled with the VIN Flash Monitor threshold set to 3.0V (VIN Monitor Register bits [5:4] = 0, 1). When the STROBE input is brought high, the LED current begins ramping up through the torch and flash current codes at 32  $\mu$ s/code. As the input current increases, the input voltage at the LM3560's IN pin begins to fall due to the source impedance of the battery. By the time the LED current has reached 1000 mA (code 0x77 or 500 mA per current source), VIN falls below 3.0V. The VIN Flash Monitor will then stop the flash current ramp and the LM3560 will continue to proceed with the flash pulse, but at 1000 mA instead of 1250 mA. [Figure 38](#) details this sequence.

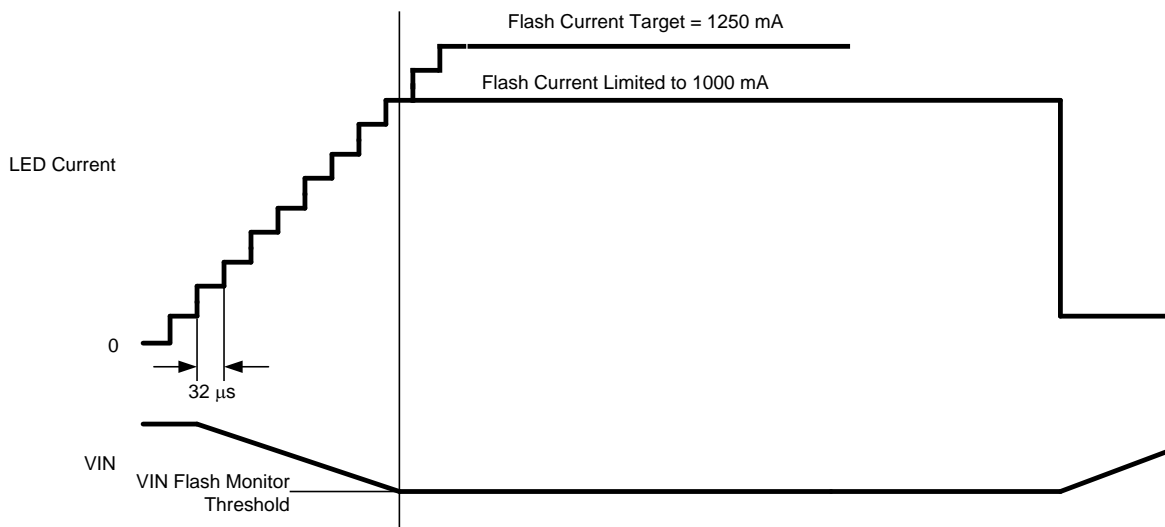


Figure 38. VIN Flash Monitor Example

### LED VOLTAGE MONITOR

The LM3560 includes a 4-bit ADC which monitors the LED forward voltage ( $V_{LED}$ ) and stores the digitized value in bits [3:0] of the  $V_{LED}$  Monitor Register. The highest voltage of  $V_{LED1}$  or  $V_{LED2}$  is automatically sensed, and that becomes the sample point for the ADC. Bit 5, the ADC shutdown bit, enables/disables the ADC with the default state set to enable (bit [5] = 0).

### AUTOMATIC CONVERSION MODE

With the ADC enabled, a conversion is performed each time a flash pulse is started. When a flash pulse is started bit [6] of the  $V_{LED}$  Monitor Register (End of Conversion bit) is automatically written with a '0'. At the end of the conversion, bit [6] will go high signaling that the  $V_{LED}$  data is valid. A read back of the  $V_{LED}$  Monitor register will clear bit [6]. [Figure 39](#) details the  $V_{LED}$  Monitor Automatic Conversion.



### MANUAL CONVERSION MODE

The VLED Monitor can be set up for manual conversion mode by setting bit [4] of the VLED Monitor Register to '1'. When this bit is set high the EOC bit (bit [6]) goes low, and a conversion is performed. When the conversion is complete, the EOC bit goes high again. Subsequent conversions are performed in manual mode by reading back the VLED Monitor register. This resets the EOC bit and starts another conversion (see Figure 40).

### ADC DELAY

The ADC Delay register provides for a programmable delay from 250  $\mu$ s to 8ms in steps of 250  $\mu$ s. This delay is the delay from when the EOC bit goes low to when the VLED Monitor samples the LED voltage. In Automatic Mode the EOC bit goes low when the Flash LED current hits its target. In Manual mode the EOC bit goes low at the end of a read back of the VLED Monitor Register (or when the manual mode bit (bit 4) is re-written with a 1).

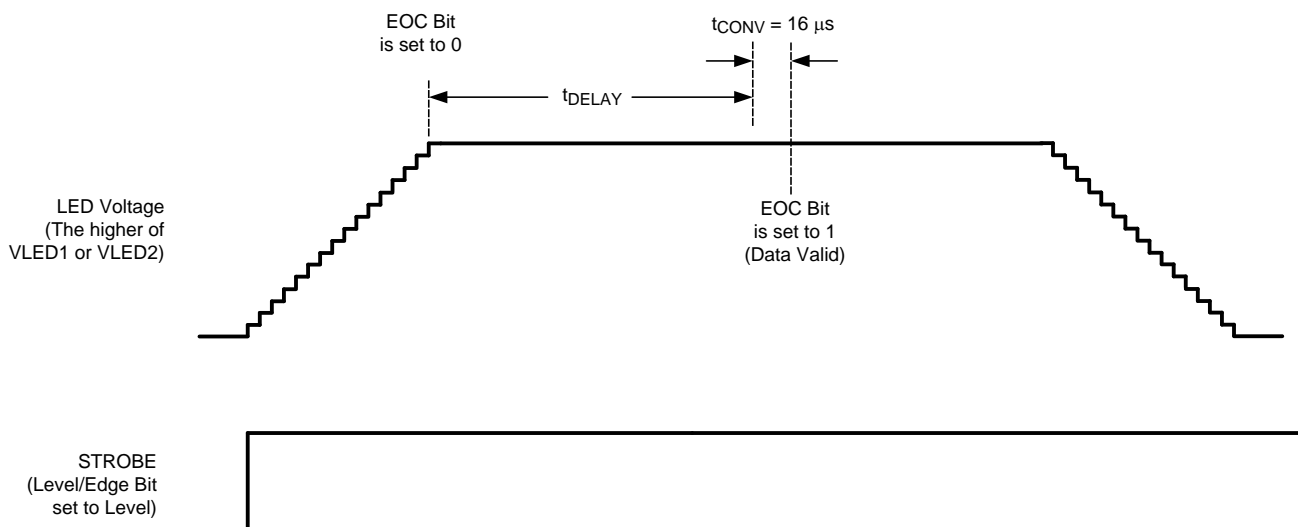


Figure 39. VLED Monitor Automatic Mode

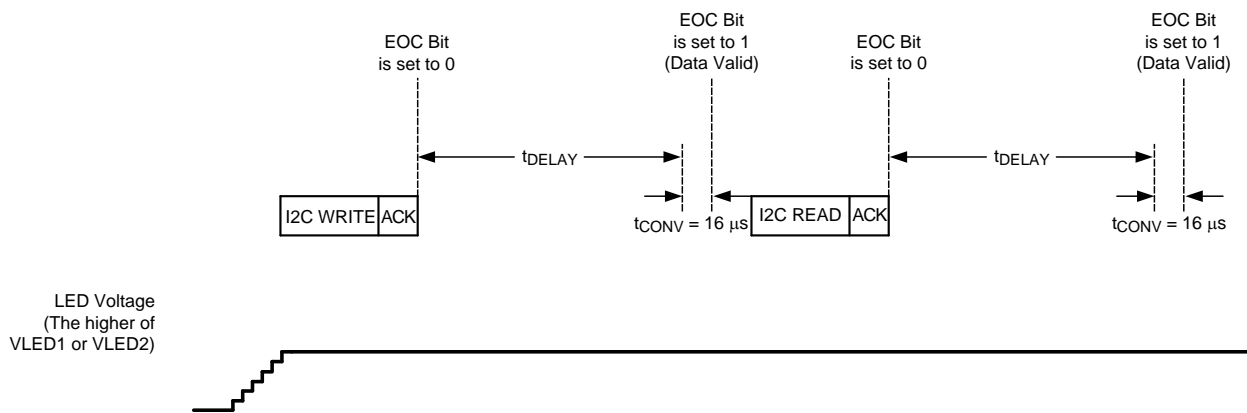


Figure 40. VLED Monitor Manual Mode

### FLAGS REGISTER AND FAULT INDICATORS

Eight fault flags are available in the LM3560. These include a Flash Timeout, a Thermal Shutdown, an LED Failure Flag (LED Shorted or Output going OVP indicating LED open), an LED Thermal Flag (NTC threshold tripping), a VIN Monitor Flag, and a VIN Flash Monitor Flag. Additionally, two LED interrupt flag bits (TX1 interrupt and TX2 interrupt) are set when the corresponding interrupt is activated. Reading back a '1' indicates the flagged event has happened. A read of the Flags Register resets these bits.

PRODUCT PREVIEW

## FLASH TIMEOUT

The Timeout or (TO flag), (bit [0] of the Flags Register) reads back a '1' if the LM3560 is active in Flash mode and the Timeout period expires before the Flash pulse is terminated. The flash pulse can be terminated before the Timeout period expires by pulling the STROBE pin low (with Enable Register bit [5] = 0), or by writing a (0,0) to bit [1:0] of the Enable Register. The TO flag is reset to '0' by pulling HWEN low, removing power to the LM3560, or reading the Flags Register.

## THERMAL SHUTDOWN FLAG

When the thermal shutdown threshold is tripped a '1' gets written to bit [1] of the Flags Register (Thermal Shutdown bit). The LM3560's flash, torch, or privacy modes cannot be restarted until the Flags Register has been read back, or when the device is shut down and started up again.

## LED FAULT

The LED Fault flag (bit 2 of the Flags Register) reads back a '1' if the part is active in Flash or Torch mode and either LED1 or LED2 experience an open or short condition. An LED open condition is signaled if the OVP threshold is crossed at the OUT pin while the device is in Flash, Torch, or Privacy mode. An LED short condition is signaled if the voltage at LED1 or LED2 goes below 500 mV while the device is in Flash, Torch, or Privacy mode. In an LED open condition there is a 2 $\mu$ s deglitch time from when the output voltage crosses the OVP threshold to when the LED Fault Flag is triggered. In an LED short condition there is a 250 $\mu$ s deglitch time from when the LED voltage falls below 500 mV until the LED Fault Flag is set. The LED Fault Flag can only be reset to '0' by pulling HWEN low, cycling power, or by removing the fault condition and reading back the Flags Register.

## TX1 AND TX2 INTERRUPT FLAGS

The TX1 and TX2 interrupt flags (bits [3] and [4]) indicate an interrupt event has occurred on the respective TX inputs. Bit 3 will read back a '1' if TX1 is in TX mode and there has been a TX1 event since the last read of the Flags Register. Bit 4 will read back a '1' if TX2 is in TX mode and there has been a TX2 event since the last read of the Flags Register. A read of the Flags Register automatically resets these bits. A TX event on TX1 or TX2, can be a high-to-low transition or a low-to-high transition depending on the setting of the TX1 and TX2 polarity bits (see Configuration Register 1 Bits [6:5]).

## LED THERMAL FAULT (NTC Flag)

The NTC flag (bit [5] of the Flags Register) reads back a '1' if the LM3560 is active in Flash or Torch mode, the device is in NTC mode, and the voltage at LED1/NTC has fallen below  $V_{TRIP}$  (1V typical). When this has happened, and the LM3560 has been forced into Torch mode or LED shutdown (depending on the state of Configuration Register 2 bit [1]), the Flags Register must be read, and  $V_{LED1/NTC}$  must go above 1V in order to place the device back in normal operation. (see [NTC MODE](#) section for more details).

## VIN FLASH MONITOR FAULT

The VIN Flash Monitor Flag (bit [6] of the Flags Register) reads back a '1' if the VIN Flash Monitor is enabled and VIN falls below the programmed VIN Flash Monitor threshold. This flag must be read back in order to resume normal operation after the LED current has been forced to the lower flash current setting.

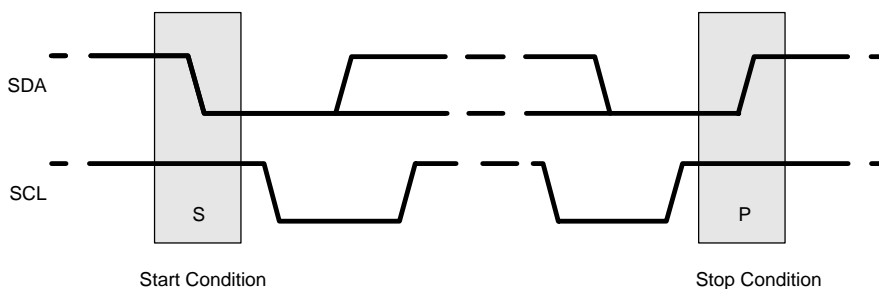
## VIN MONITOR FAULT

The VIN Monitor Flag (bit [7] of the Flag Register) reads back a '1' when the VIN Monitor is enabled and VIN falls below the programmed VIN Monitor threshold. This flag must be read back and VIN must go above the VIN Monitor Threshold in order to resume normal operation after the LED current has been forced to Torch mode or turned off due to a VIN Monitor event.

## I<sup>2</sup>C-Compatible Interface

### START AND STOP CONDITIONS

The LM3560 is controlled via an I<sup>2</sup>C-compatible interface. START and STOP conditions classify the beginning and end of the I<sup>2</sup>C session. A START condition is defined as SDA transitioning from HIGH-to-LOW while SCL is HIGH. A STOP condition is defined as SDA transitioning from LOW-to-HIGH while SCL is HIGH. The I<sup>2</sup>C master always generates the START and STOP conditions.



**Figure 41. Start and Stop Sequences**

The I<sup>2</sup>C bus is considered busy after a START condition and free after a STOP condition. During data transmission the I<sup>2</sup>C master can generate repeated START conditions. A START and a repeated START condition are equivalent function-wise. The data on SDA must be stable during the HIGH period of the clock signal (SCL). In other words, the state of SDA can only be changed when SCL is LOW. [Figure 42](#) shows the SDA and SCL signal timing for the I<sup>2</sup>C-Compatible Bus. See the **Electrical Table** for timing values.

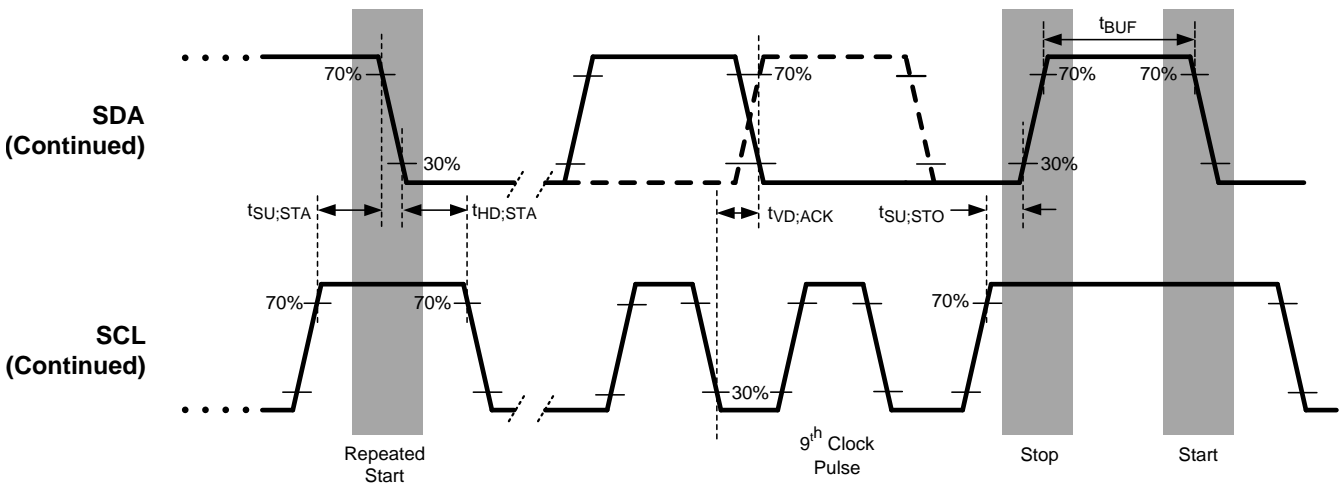
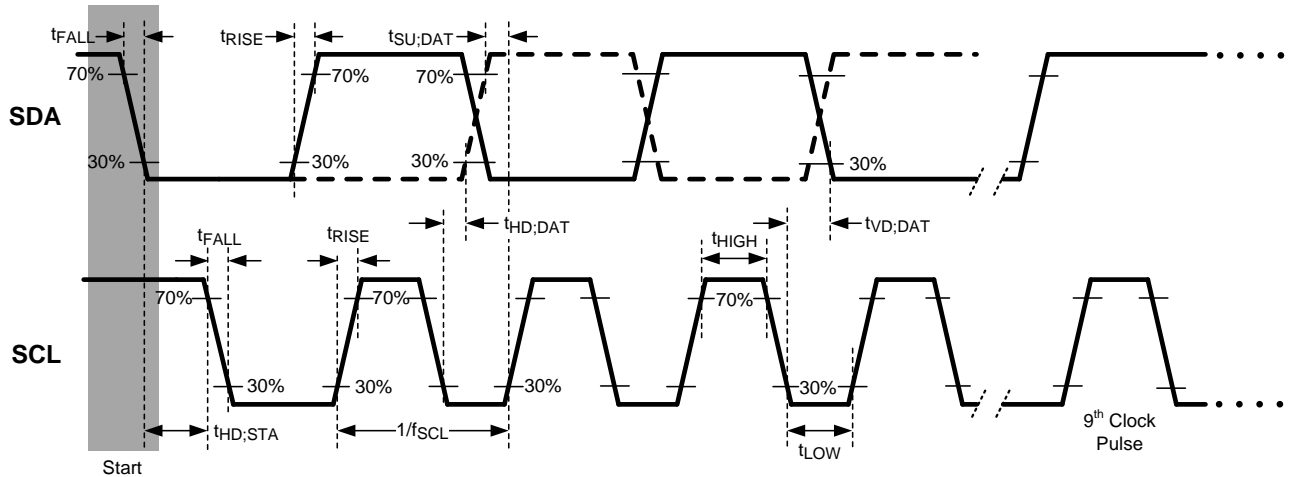


Figure 42. I<sup>2</sup>C-Compatible Timing

**I<sup>2</sup>C-COMPATIBLE CHIP ADDRESS**

The device address for the LM3560 is 1010011 (0xA7 for read and 0xA6 for write). After the START condition, the I<sup>2</sup>C master sends the 7-bit address followed by an eighth read or write bit (R/W). R/W = 0 indicates a WRITE and R/W = 1 indicates a READ. The second byte following the device address selects the register address to which the data will be written. The third byte contains the data for the selected register.

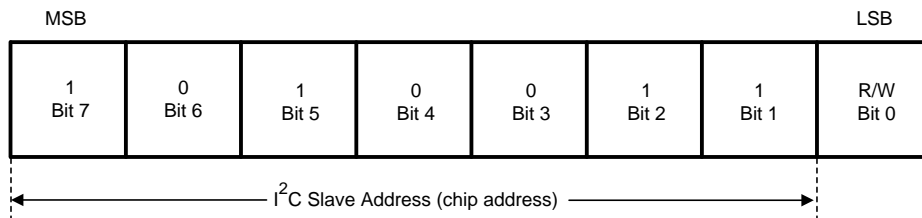


Figure 43. Device Address

PRODUCT PREVIEW

## TRANSFERRING DATA

Every byte on the SDA line must be eight bits long, with the most significant bit (MSB) transferred first. Each byte of data must be followed by an acknowledge bit (ACK). The acknowledge related clock pulse (9th clock pulse) is generated by the master. The master releases SDA (HIGH) during the 9th clock pulse (write mode). The LM3560 pulls down SDA during the 9th clock pulse, signifying an acknowledge. An acknowledge is generated after each byte has been received.

## Register Descriptions

**Table 3. LM3560 Internal Registers**

Register Name	Internal Hex Address	Power On/RESET Value
Enable	0x10	0x18
Privacy	0x11	0x58
Indicator	0x12	0x00
Indicator Blinking	0x13	0x00
Privacy PWM	0x14	0xF8
GPIO	0x20	0x80
VLED Monitor (ADC)	0x30	0x80
ADC Delay	0x31	0x90
VIN Monitor	0x80	0xC0
Last Flash	0x81	0x00
Torch Brightness	0xA0	0x52
Flash Brightness	0xB0	0xDD
Flash Duration	0xC0	0xEF
Flags	0xD0	0x00
Configuration 1	0xE0	0x6B
Configuration 2	0xF0	0xE0

### ENABLE REGISTER (Address 0x10)

Bits [1:0] of the Enable Register controls the on/off state of Torch mode, Flash mode, and Privacy Indicate mode. Bit 2 selects the peak current setting for Privacy Indicate mode (max or min torch current). Bits [4:3] turn on/off the main current sources (LED1 and LED2). Bit [5] sets the level or edge control for the STROBE input. Bits 7 and 6 control the Indicator current source (see [Table 4](#)).

**Table 4. Enable Register Descriptions**

Bit 7 (EN Blink)	Bit 6 (EN Message Indicator)	Bit 5 (STROBE Level/Edge)	Bit 4 (LED2 ENABLE)	Bit 3 (LED1 Enable)	Bit 2 (Privacy Mode Peak Current Setting)	Bit 1 (EN1)	Bit 0 (EN0)
0 = Message Indicator Blinking Function is disabled <sup>(1)</sup> <b>(default)</b> 1 = Message Indicator Blinking Function is enabled. The message indicator blinks the pattern programmed in the Indicator Register and Indicator Blinking Register	0 = Message Indicator is disabled <b>(Default)</b> 1 = Message Indicator is enabled.	0 = (Level Sensitive) When STROBE goes high, the Flash current will turn on and remain on for the duration the STROBE pin is held high or when the Flash Timeout occurs, whichever comes first. <b>(default)</b> 1 = (Edge Triggered) When STROBE goes high, the Flash current will turn on and remain on for the duration of the Flash Time-out.	0 = LED2 off 1 = LED2 on <b>(default)</b>	0 = LED1 off 1 = LED1 on <b>(default)</b>	0 = 31.25mA <b>(default)</b> 1 = 250 mA	<b>Enable Bits</b> 00 = Current Sources are Shutdown <b>(default)</b> 01 = Privacy Indicator Mode 10 = Torch Mode 11 = Flash Mode (bits reset at timeout)	

(1) Bit 7 Enables/Disables the Message Indicator Blinking Function. With this bit set to 0 and Bit 6 set to 1, the Message Indicator turns on constantly at the programmed current as set in Indicator Register bits [2:0].

### PRIVACY REGISTER (Address 0x11)

The Privacy Register contains the bits that control which current source is used for the privacy indicator (LED1 or LED2 or both), whether the privacy indicator turns off or remains on after the flash pulse terminates, and the duty cycle settings (between 10% and 80%) for setting the average privacy LED current (see [Table 5](#)).

**Table 5. Privacy Register**

Bit 7 (Blink 2)	Bit 6 (Blink 1)	Bit 5 (LED2 Privacy)	Bit 4 (LED1 Privacy)	Bit 3 (Privacy Terminate)	Bit 2 (PD2)	Bit 1 (PD1)	Bit 0 (PD0)
$t_{\text{BLINK}}$ 00 = No Blinking 01 = 128 ms Blink Period <b>(Default)</b> 10 = 256 ms Blink Period 11 = 512 ms Blink Period		0 = LED2 is off for privacy mode <b>(Default)</b> 1 = LED2 is on for privacy mode	0 = LED1 is off for privacy mode 1 = LED1 is on for privacy mode <b>(Default)</b>	0 = Privacy mode turns back on at the end of the flash pulse 1 = Privacy mode remains off at the end of the flash pulse <b>(Default)</b>	Privacy mode current levels (% of minimum or maximum torch current, depending on bit [2] of Enable Register) 000 = 10% <b>(Default)</b> 001 = 20% 010 = 30% 011 = 40% 100 = 50% 101 = 60% 110 = 70% 111 = 80%		

**INDICATOR REGISTER (Address 0x12)**

The Indicator Register contains the bits which control the following:

1. Indicator current level
2. Pulse width
3. Ramp times for turn-on and turn-off of the indicator current source (see Figure 44 for the message indicator timing diagram).

**Table 6. Indicator Register**

Bit 7 (R2)	Bit 6 (R1)	Bit 5 (P3)	Bit 4 (P2)	Bit 3 (P1)	Bit 2 (I3)	Bit 1 (I2)	Bit 0 (I1)
$(t_R \text{ and } t_F)$ 00 = 78 ms (default) 01 = 156 ms 10 = 312 ms 11 = 624 ms		(PERIOD#) 000 = 0 (default) 001 = 1 010 = 2 011 = 3 100 = 4 101 = 5 110 = 6 111 = 7			$(I_{IND})$ 000 = 2.25 mA (default) 001 = 4.5 mA 010 = 6.75 mA 011 = 9 mA 100 = 11.25 mA 101 = 13.5 mA 110 = 15.75 mA 111 = 18 mA		

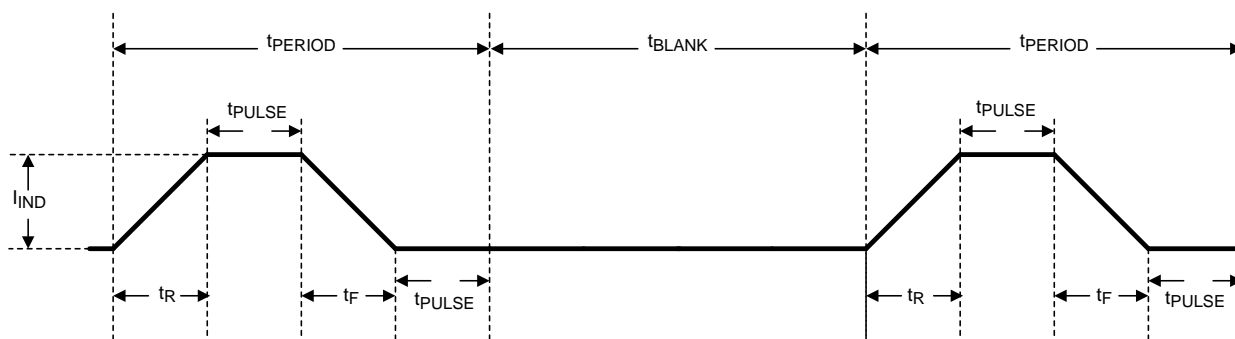
**INDICATOR BLINKING REGISTER (Address 0x13)**

The Indicator Blinking Register contains the bits which control the following:

1. Number of periods ( $t_{PERIOD} = t_R + t_F + 2 \times t_{PULSE}$ )
2. Active Time ( $t_{ACTIVE} = t_{PERIOD} \times PERIOD\#$ )
3. Blank Time ( $t_{BLANK} = t_{ACTIVE} \times BLANK\#$ )  
– (see Figure 44)

**Table 7. Indicator Blinking Register**

Bit 7 (N/A)	Bit 6 (M3)	Bit 5 (M2)	Bit 4 (M1)	Bit 3 (PW4)	Bit 2 (PW3)	Bit 1 (PW2)	Bit 0 (PW1)
Not used	BLANK# 0000 = 0 (default) 0001 = 1 0010 = 2 0011 = 3 0100 = 4 0101 = 5 0110 = 6 0111 = 7 1000 = 8 1001 = 9 1010 = 10 1011 = 11 1100 = 12 1101 = 13 1110 = 14 1111 = 15			Pulse Time ( $t_{PULSE}$ ) 0000 = 0 (default) 0001 = 32 ms 0010 = 64 ms 0011 = 92 ms 0100 = 128 ms 0101 = 160 ms 0110 = 196 ms 0111 = 224 ms 1000 = 256 ms 1001 = 288 ms 1010 = 320 ms 1011 = 352 ms 1100 = 384 ms 1101 = 416 ms 1110 = 448 ms 1111 = 480 ms			



**Figure 44. Message Indicator Timing Diagram**

### PRIVACY PWM PERIOD REGISTER (Address 0x14)

The Privacy PWM Register contains the bits to control the PWM period for the privacy indicate mode (see [Table 8](#)).

**Table 8. Privacy PWM Period Register**

Bits 7-3 (Not Used)	Bit 2 (P3)	Bit 1 (P2)	Bit 0 (P1)
	000 = 5.12 ms (default) 001 = 2.56 ms 010 = 1.28 ms 011 = 640 μs 1XX = 320 μs		

### GPIO REGISTER (Address 0x20)

The GPIO register contains the control bits which change the state of the TX1/TORCH/GPIO1 pin and the TX2/INT/GPIO2 pins to general purpose I/O's (GPIO's). Additionally, bit 6 of this register contains the interrupt configuration bit. [Table 9](#) describes the bit description and functionality of the GPIO register. To configure the TX1 or TX2 pins as GPIO outputs an initial double write is required to register 0x20. For example, to configure TX2 to output a logic high, an initial write of 0xB8 would need to occur twice, to force GPIO2 low. Subsequent writes to GPIO2 after the initial set-up, only requires a single write. To read back the GPIO inputs, a write then a read of register 0x20 must occur each time the data is read. For example, if GPIO2 is set-up as a GPIO input and the GPIO2 input has then changed state, first a write to 0x20 must occur, then the following read back of register 0x20 will show the updated data. When configuring TX2 as an interrupt output, the TX2/GPIO2/INT pin must first be configured as a GPIO output (double write). For example, to configure TX2/GPIO2/INT for INT mode a write of 0xF8 to register 0x20 must be done twice.

**Table 9. GPIO Register**

Bit 7 (Not Used)	Bit 6 (TX2/INT/GPIO2 Interrupt Enable)	Bit 5 (TX2/INT/GPI O2 data)	Bit 4 (TX2/INT/GPI O2 data direction)	Bit 3 (TX2/INT/GPIO2 Control)	Bit 2 (TX1/TORCH/G PIO1 data)	Bit 1 (TX1/TORCH/G PIO1 data direction)	Bit 0 (TX1/TORCH/G PIO1 Control)
N/A	0 = TX2/INT/GPIO2 is configured according to bit 3 of this register (default)	This bit is the read or write data for the TX2/INT/GPIO 2 pin in GPIO mode	0 = TX2/INT/GPIO 2 is a GPIO Input (default)	0 = TX2/INT/GPIO is configured as a TX interrupt (default)	This bit is the read or write data for the GPIO1 pin in GPIO mode	0 = TX1/TORCH/GPIO1 is a GPIO input (default)	0 = TX1/TORCH/GPIO1 pin is configured as TX interrupt (default)
	1 = with bits [4:3] = 11, TX2/INT/GPIO2 is an interrupt output. See <a href="#">INTERRUPT OUTPUT (INT MODE)</a> .		1 = TX2/INT/GPIO 2 is a GPIO output	1 = TX2/INT/GPIO2 is configured as a GPIO		1 = TX1/TORCH/GPIO1 is an output	1 = TX1/TORCH/GPIO1 pin is configured as a GPIO



**LED FORWARD VOLTAGE ADC (VLED MONITOR REGISTER, Address 0x30)**

The VLED Monitor Register controls the internal 4 bit analog to digital converter. Bits [3:0] of this register contain the 4-bit data of the LED voltage. This data is the digitized voltage of the highest of either VLED1 to GND or VLED2 to GND. Bit [4] is the Manual Mode enable which provides for a manual conversion of the ADC. In Manual Mode the Automatic Conversion is still performed. In automatic conversion mode a conversion is performed each time a flash pulse is initiated. Bit [5] is the ADC shutdown bit. Bit [6] signals the end of conversion. This is a read-only bit that goes high when a conversion is complete and data is ready. A read of the VLED Monitor Register clears the End of Conversion bit (see [Table 10](#)).

**Table 10. VLED Monitor Register Descriptions**

Bit 7 (Not Used)	Bit 6 (End of Conversion)	Bit 5 (ADC Shutdown)	Bit 4 (Manual Mode Enable)	Bit 3 (ADC3)	Bit 2 (ADC2)	Bit 1 (ADC1)	Bit 0 (ADC0)
N/A	0 = Conversion in progress( <b>default</b> )  1 = Conversion done	0 = ADC is enabled ( <b>default</b> )  1 = ADC is shutdown, no conversion is performed	0 = Manual Mode Disabled ( <b>default</b> )  1 = Manual Mode is Enabled	0000 = (VLED < 2.8V) ( <b>default</b> ) 0001 = (2.8V ≤ VLED < 2.9V) 0010 = (2.9V ≤ VLED < 3.0V) 0011 = (3.0V ≤ VLED < 3.1V) 0100 = (3.1V ≤ VLED < 3.2V) 0101 = (3.2V ≤ VLED < 3.3V) 0110 = (3.3V ≤ VLED < 3.4V) 0111 = (3.4V ≤ VLED < 3.5V) 1000 = (3.5V ≤ VLED < 3.6V) 1001 = (3.6V ≤ VLED < 3.7V) 1010 = (3.7V ≤ VLED < 3.8V) 1011 = (3.8V ≤ VLED < 3.9V) 1100 = (3.9V ≤ VLED < 4.0V) 1101 = (4.0V ≤ VLED < 4.1V) 1110 = (4.1V ≤ VLED < 4.2V) 1111 = (4.2V ≤ VLED)			

**ADC DELAY REGISTER (Address 0x31)**

The ADC Delay Register programs the delay from when the EOC bit goes low to when a conversion is initiated. This delay applies to both Manual Mode and Automatic Mode. Bit 5 is the No Delay bit and can set the delay to effectively 0.

**Table 11. ADC Delay Register Descriptions**

Bit 7 (Not Used)	Bit 6 (Not used)	Bit 5 (No Delay)	Bit 4 (D1)	Bit 3 (D2)	Bit 2 (D3)	Bit 1 (D4)	Bit 0 (D5)
N/A		0 = Delay is set by bits [4:0]( <b>default</b> )  1 = no delay from when the EOC goes low to when the conversion is started.	Bits [4:0] programs the delay from when the EOC bit goes low to when a conversion is started (250 μs/step). 00000 = 250 μs : 01111 = 4 ms ( <b>default</b> ) : 11111 = 8 ms				

### VIN MONITOR REGISTER (Address 0x80)

The VIN Monitor Register controls the Enable bit for the VIN Monitor, the threshold select for the VIN Monitor, the enable bit for the VIN Flash Monitor, and the threshold select for the VIN Flash Monitor (see [Table 12](#)).

**Table 12. VIN Monitor Register Descriptions**

Bit 7 (Not used)	Bit 6 (Not used)	Bit 5 (VIN Flash Monitor Threshold 1)	Bit 4 (VIN Flash Monitor Threshold 2)	Bit 3 (VIN Flash Monitor enable)	Bit 2 (VIN Monitor Threshold1)	Bit 1 (VIN Monitor Threshold0)	Bit 0 (VIN Monitor Enable)
N/A		00 = 2.9V (default) 01 = 3.0V 10 = 3.1V 11 = 3.2V		0 = VIN Flash Monitor is disabled (default)  1 = VIN Flash Monitor is enabled	00 = 2.9V Default 01 = 3.0V 10 = 3.1V 11 = 3.2V		0 = VIN Monitor disabled (default)  1 = VIN Monitor is enabled

### LAST FLASH REGISTER (Address 0x81)

The Last Flash Register is a read-only register which is loaded with the flash code corresponding to the flash level that the LM3560 was at if any of the following events happen:

1. Voltage at LED1/NTC falling below  $V_{TRIP}$  with the device in NTC mode (Configuration Register 1 bit[4] = 1);
2. Input voltage falling below the programmed VIN Monitor Threshold with device in VIN Monitor mode (VIN Monitor Register bit [0] = 1); or
3. Input voltage falling below the programmed VIN Flash Monitor Threshold with the device in VIN Flash Monitor mode (VIN Monitor Register bit [3] = 1).

The Last Flash Register is updated at the same time that the corresponding Flag bit is written to the Flags Register. This results in a delay of 250  $\mu$ s from when  $V_{LED1/NTC}$  (NTC mode) crosses  $V_{TRIP}$ , or  $V_{IN}$  (VIN Monitor enabled) crosses the  $V_{IN\_TH}$ . During VIN Flash Monitor there is a 8 $\mu$ s deglitch time so the VIN Flash Monitor Flag is written (and the Last Flash Register is updated) 8  $\mu$ s after  $V_{IN}$  falls below  $V_{IN\_FLASH}$ .

**Table 13. Last Flash Register Descriptions**

Bit 7 (LF2A)	Bit 6 (LF2B)	Bit 5 (LF2C)	Bit 4 (LF2D)	Bit 3 (LF1A)	Bit 2 (LF1B)	Bit 1 (LF1C)	Bit 0 (LF1D)
These bits are read only and represent the Flash Current Code for LED2 that the LM3560 was at during the interrupt. 0000 = 62.5 mA 0001 = 125 mA 0010 = 187.5 mA 0011 = 250 mA 0100 = 312.5 mA 0101 = 375 mA 0110 = 437.5 mA 0111 = 500 mA 1000 = 562.5 mA 1001 = 625 mA 1010 = 687.5 mA 1011 = 750 mA 1100 = 812.5 mA 1101 = 875 mA 1110 = 937.5 mA 1111 = 1000 mA				These bits are read only and represent the Flash Current Code for LED1 that the LM3560 was at during the interrupt. 0000 = 62.5 mA 0001 = 125 mA 0010 = 187.5 mA 0011 = 250 mA 0100 = 312.5 mA 0101 = 375 mA 0110 = 437.5 mA 0111 = 500 mA 1000 = 562.5 mA 1001 = 625 mA 1010 = 687.5 mA 1011 = 750 mA 1100 = 812.5 mA 1101 = 875 mA 1110 = 937.5 mA 1111 = 1000 mA			

**TORCH BRIGHTNESS REGISTER DESCRIPTIONS (Address 0xA0)**

Bits [2:0] of the Torch Brightness Register set the Torch current for LED1. Bits [5:3] set the Torch current for LED2 (see [Table 14](#)).

**Table 14. Torch Brightness Register Descriptions**

Bit 7 (N/A)	Bit 6 (N/A)	Bit 5 (TC2A)	Bit 4 (TC2B)	Bit 3 (TC2C)	Bit 2 (TC1A)	Bit 1 (TC1B)	Bit 0 (TC1C)
(Not Used)		<b>LED2 Torch Current Select Bits</b> 000 = 31.25 mA (62.5 mA total) 001 = 62.5 mA (125 mA total) 010 = 93.75 mA (187.5 mA total) <b>default</b> 011 = 125 mA (250 mA total) 100 = 156.25 mA (312.5 mA total) 101 = 187.5 mA (375 mA total) 110 = 218.75 mA (437.5 mA total) 111 = 250 mA (500 mA total)			<b>LED1 Torch Current Select Bits</b> 000 = 31.25 mA (62.5 mA total) 001 = 62.5 mA (125 mA total) 010 = 93.75 mA (187.5 mA total) <b>default</b> 011 = 125 mA (250 mA total) 100 = 156.25 mA (312.5 mA total) 101 = 187.5 mA (375 mA total) 110 = 218.75 mA (437.5 mA total) 111 = 250 mA (500 mA total)		

**FLASH BRIGHTNESS REGISTER (Address 0xB0)**

Bits [3:0] of the Flash Brightness Register set the Flash current for LED1. Bits [7:4] set the Flash current for LED2 (see [Table 15](#)).

**Table 15. Flash Brightness Register Descriptions**

Bit 7 (FC2A)	Bit 6 (FC2B)	Bit 5 (FC2C)	Bit 4 (FC2D)	Bit 3 (FC1A)	Bit 2 (FC1B)	Bit 1 (FC1C)	Bit 0 (FC1D)
<b>Flash Current Select Bits</b> 0000 = 62.5 mA 0001 = 125 mA 0010 = 187.5 mA 0011 = 250 mA 0100 = 312.5 mA 0101 = 375 mA 0110 = 437.5 mA 0111 = 500 mA 1000 = 562.5 mA 1001 = 625 mA 1010 = 687.5 mA 1011 = 750 mA 1100 = 812.5 mA 1101 = 875 mA <b>(default)</b> 1110 = 937.5 mA 1111 = 1000 mA				<b>Flash Current Select Bits</b> 0000 = 62.5 mA 0001 = 125 mA 0010 = 187.5 mA 0011 = 250 mA 0100 = 312.5 mA 0101 = 375 mA 0110 = 437.5 mA 0111 = 500 mA 1000 = 562.5 mA 1001 = 625 mA 1010 = 687.5 mA 1011 = 750 mA 1100 = 812.5 mA 1101 = 875 mA <b>(default)</b> 1110 = 937.5 mA 1111 = 1000 mA			

## FLASH DURATION REGISTER (Address 0xC0)

Bits [4:0] of the Flash Duration Register set the Flash Timeout duration. Bits [6:5] set the switch current limit (see [Table 16](#)).

**Table 16. Flash Duration Register Descriptions**

Bit 7 (Not used)	Bit 6 (CL1)	Bit 5 (CL0)	Bit 4 (T4)	Bit 3 (T3)	Bit 2 (T2)	Bit 1 (T1)	Bit 0 (T0)
N/A	<b>Current Limit Select Bits</b> 00 = 1.6A Peak Current Limit 01 = 2.3A Peak Current Limit 10 = 3.0A Peak Current Limit 11 = 3.6A Peak Current Limit <b>(default)</b>		<b>Flash Time-out Select Bits</b> 00000 = 32 ms time-out 00001 = 64 ms time-out 00010 = 96 ms time-out 00011 = 128 ms time-out 00100 = 160 ms time-out 00101 = 192 ms time-out 00110 = 224 ms time-out 00111 = 256 ms time-out 01000 = 288 ms time-out 01001 = 320 ms time-out 01010 = 352 ms time-out 01011 = 384 ms time-out 01100 = 416 ms time-out 01101 = 448 ms time-out 01110 = 480 ms time-out 01111 = 512 ms time-out <b>(default)</b> 10000 = 544 ms time-out 10001 = 576 ms time-out 10010 = 608 ms time-out 10011 = 640 ms time-out 10100 = 672 ms time-out 10101 = 704 ms time-out 10110 = 736 ms time-out 10111 = 768 ms time-out 11000 = 800 ms time-out 11001 = 832 ms time-out 11010 = 864 ms time-out 11011 = 896 ms time-out 11100 = 928 ms time-out 11101 = 960 ms time-out 11110 = 992 ms time-out 11111 = 1024 ms time-out				

## FLAGS REGISTER (Address 0xD0)

The Flags Register holds the flag bits indicating Flash Timeout, Thermal Shutdown, LED Fault (Open or Short), TX Interrupts (TX1 and TX2), LED Thermal Fault (NTC), VIN Monitor Trip, and VIN Flash Monitor Trip. All Flags are cleared on read back of the Flags Register. (See [Table 17](#)).

**Table 17. Flags Register Descriptions**

Bit 7 (VIN Monitor)	Bit 6 (VIN Flash Monitor)	Bit 5 (NTC Fault)	Bit 4 (TX2 Interrupt)	Bit 3 (TX1 Interrupt)	Bit 2 (LED Fault)	Bit 1 (Thermal Shutdown)	Bit 0 (Flash Time-out)
0 = $V_{IN}$ is above the VIN Monitor Threshold or VIN Monitor Threshold is Disabled <b>(default)</b>	$V_{IN}$ did not fall below the VIN Flash Monitor threshold during flash pulse turn-on or VIN Flash Monitor is disabled <b>(default)</b>	0 = LED/NTC pin is above 1V <b>(default)</b>	0 = TX2 has not changed state <b>(default)</b>	0 = TX1 has not changed state <b>(default)</b>	0 = Proper LED Operation <b>(default)</b>	0 = Die Temperature below Thermal Shutdown Limit <b>(default)</b>	0 = Flash Time-Out did not expire <b>(default)</b>

**Table 17. Flags Register Descriptions (continued)**

Bit 7 (V <sub>IN</sub> Monitor)	Bit 6 (VIN Flash Monitor)	Bit 5 (NTC Fault)	Bit 4 (TX2 Interrupt)	Bit 3 (TX1 Interrupt )	Bit 2 (LED Fault)	Bit 1 (Thermal Shutdown)	Bit 0 (Flash Time-out)
1 = VIN Monitor is enabled and V <sub>IN</sub> has fallen below the programmed threshold	1 = VIN Flash Monitor is enabled and V <sub>IN</sub> fell below the programmed VIN Flash Monitor threshold during flash pulse turn-on	1 = NTC mode is enabled and LEDI/NTC has fallen below 1V	1 = TX2 has changed state (TX2 mode only)	1 = TX1 has changed state (TX1 mode only)	1 = LED Failed (Open or Short)	1 = Die Temperature has crossed the Thermal Shutdown Threshold	1 = Flash Time-Out Expired

**CONFIGURATION REGISTER 1 (Address 0xE0)**

Configuration Register 1 holds the STROBE Enable bit, the STROBE polarity bit, the NTC Enable bit, the polarity selection bit for TX1 and TX2, and the Hardware Torch Enable bit (see [Table 18](#)).

**Table 18. Configuration Register 1 Descriptions**

Bit 7 (Hardware Torch Mode Enable)	Bit 6 (TX2 Polarity)	Bit 5 (TX1 Polarity)	Bit 4 (NTC Mode Enable)	Bit 3 (STROBE Polarity)	Bit 2 (STROBE Input Enable)	Bit 1 (Not Used)	Bit 0 (Not Used)
0 = TX1/TORCH is a TX input( <b>default</b> )	0 = TX2 is configured for active low polarity	0 = TX1 is configured for active low polarity	0 = LEDI/NTC pin is configured as an indicator output ( <b>default</b> )	0 = STROBE Input Enable is active low. Pulling STROBE low will turn on Flash current	0 = STROBE Input Disabled ( <b>Default</b> )	N/A	N/A
1 = TX1/TORCH pin is a hardware TORCH enable. This bit is reset to 0 after a flash pulse.	1 =TX2 pin is configured for active high polarity ( <b>default</b> )	1 = TX1 is configured for active high polarity ( <b>default</b> )	1 = LEDI/NTC is configured as a comparator input for an NTC thermistor	1 = STROBE Input is active high. Pulling STROBE high will turn on Flash current ( <b>default</b> )	1 = STROBE Input Enabled		

### CONFIGURATION REGISTER 2 (Address 0xF0)

Configuration Register 2 holds the TX2 shutdown select bit, the NTC shutdown select bit, the Alternate External Torch mode select bit, the VIN Monitor Shutdown bit, and the TX1 shutdown bit (see [Table 19](#)).

**Table 19. Configuration Register 2 Bit Descriptions**

Bit 7 (Not used)	Bit 6 (Not used)	Bit 5 (Not used)	Bit 4 (TX1 Shutdown)	Bit 3 (VIN Monitor Shutdown)	Bit 2 (AET mode)	Bit 1 (NTC Shutdown)	Bit 0 (TX2 Shutdown)
N/A	N/A	N/A	0 = TX1 interrupt will force the LED current to the programmed torch current level <b>(default)</b>	0 = $V_{IN}$ falling below the programmed VIN Monitor Threshold will force the LED current into the programmed torch current level <b>(default)</b>	0 = AET Mode Disabled <b>(default)</b>	0 = Voltage at LED/NTC falling below $V_{TRIP}$ will force the LED current to the programmed torch current level. <b>(default)</b>	0 = TX2 interrupt will force the LED current to the programmed torch current level <b>(default)</b>
			1 = TX1 interrupt will force the LED current into shutdown.	1 = $V_{IN}$ falling below the programmed VIN Monitor Threshold will force the LED current into shutdown.	1 = AET Mode Enabled	1 = Voltage at LED/NTC falling below $V_{TRIP}$ will force the LED current into shutdown.	1 = TX2 interrupt will force the LED current into shutdown.

## APPLICATIONS INFORMATION

### OUTPUT CAPACITOR SELECTION

The LM3560 is designed to operate with at least a 10  $\mu\text{F}$  ceramic output capacitor. When the boost converter is running the output capacitor supplies the load current during the boost converters on-time. When the NMOS switch turns off the inductor energy is discharged through the internal PMOS switch, supplying power to the load and restoring charge to the output capacitor. This causes a sag in the output voltage during the NFET on-time and a rise in the output voltage during the NFET off-time. The output capacitor is therefore chosen to limit the output ripple to an acceptable level depending on load current and input/output voltage differentials and also to ensure the converter remains stable.

For proper operation the output capacitor must be at least a 10  $\mu\text{F}$  ceramic. Larger capacitors such as a 22  $\mu\text{F}$  or multiple capacitors in parallel can be used if lower output voltage ripple is desired. To estimate the output voltage ripple considering the ripple due to capacitor discharge ( $\Delta V_Q$ ) and the ripple due to the capacitors ESR ( $\Delta V_{\text{ESR}}$ ) use the following equations:

For continuous conduction mode, the output voltage ripple due to the capacitor discharge is:

$$\Delta V_Q = \frac{I_{\text{LED}} \times (V_{\text{OUT}} - V_{\text{IN}})}{f_{\text{SW}} \times V_{\text{OUT}} \times C_{\text{OUT}}} \quad (1)$$

The output voltage ripple due to the output capacitors ESR is found by:

$$\Delta V_{\text{ESR}} = R_{\text{ESR}} \times \left( \frac{I_{\text{LED}} \times V_{\text{OUT}}}{V_{\text{IN}}} \right) + \Delta I_L$$

where

$$\Delta I_L = \frac{V_{\text{IN}} \times (V_{\text{OUT}} - V_{\text{IN}})}{2 \times f_{\text{SW}} \times L \times V_{\text{OUT}}} \quad (2)$$

In ceramic capacitors the ESR is very low so a close approximation is to assume that 80% of the output voltage ripple is due to capacitor discharge and 20% from ESR. [Table 20](#) lists different manufacturers for various output capacitors and their case sizes suitable for use with the LM3560.

### INPUT CAPACITOR SELECTION

Choosing the correct size and type of input capacitor helps minimize the input voltage ripple caused by the switching of the LM3560's boost converter, and reduces noise on the boost converters input terminal that can feed through and disrupt internal analog signals. In the Typical Application Circuit a 10  $\mu\text{F}$  ceramic input capacitor works well. It is important to place the input capacitor as close as possible to the LM3560's input (IN) terminals. This reduces the series resistance and inductance that can inject noise into the device due to the input switching currents. [Table 20](#) lists various input capacitors that are recommended for use with the LM3560.

**Table 20. Recommended Input/Output Capacitors (X5R Dielectric)**

Manufacturer	Part Number	Value	Case Size	Voltage Rating
TDK Corporation	C1608JB0J106M	10 $\mu\text{F}$	0603 (1.6mmx0.8mmx0.8mm)	6.3V
TDK Corporation	C2012JB1A106M	10 $\mu\text{F}$	0805 (2mmx1.25mmx1.25mm)	10V
Murata	GRM21BR61A106KE19	10 $\mu\text{F}$	0805 (2mmx1.25mmx1.25mm)	10V

### INDUCTOR SELECTION

The LM3560 is designed to use a 1  $\mu\text{H}$  or 2.2  $\mu\text{H}$  inductor. [Table 21](#) lists various inductors and their manufacturers that can work well with the LM3560. When the device is boosting ( $V_{\text{OUT}} > V_{\text{IN}}$ ) the inductor will typically be the largest area of efficiency loss in the circuit. Therefore, choosing an inductor with the lowest possible series resistance is important. Additionally, the saturation rating of the inductor should be greater than the maximum operating peak current of the LM3560. This prevents excess efficiency loss that can occur with inductors that operate in saturation. For proper inductor operation and circuit performance, ensure that the inductor saturation and the peak current limit setting of the LM3560 are greater than  $I_{\text{PEAK}}$  in the following calculation:

$$I_{PEAK} = \frac{I_{LOAD}}{\eta} \times \frac{V_{OUT}}{V_{IN}} + \Delta I_L \quad \text{where} \quad \Delta I_L = \frac{V_{IN} \times (V_{OUT} - V_{IN})}{2 \times f_{SW} \times L \times V_{OUT}} \quad (3)$$

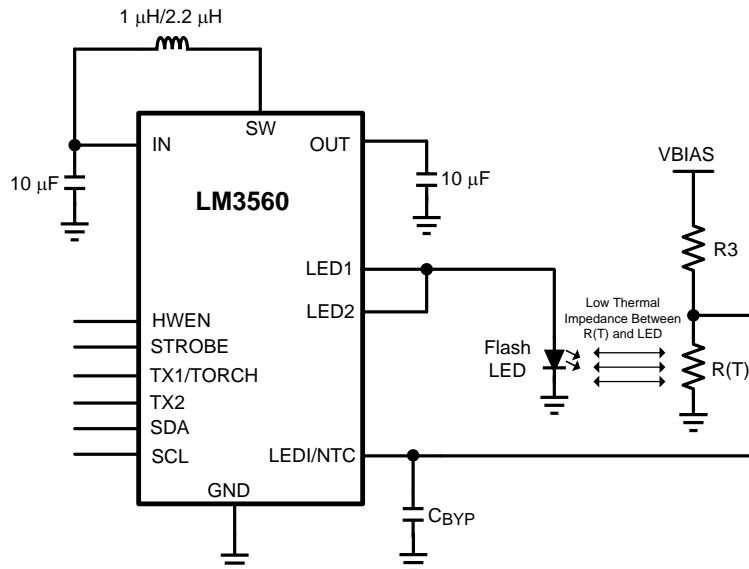
where  $f_{SW} = 2\text{MHz}$ , and efficiency can be found in the Typical Performance Characteristics plots.

**Table 21. Recommended Inductors**

Manufacturer	L	Part Number	Dimensions (LxWxH)	I <sub>SAT</sub>	R <sub>DC</sub>
TOKO	2.2 $\mu\text{H}$	FSD0312-H-2R02M	3 mmx3.2 mmx1.2 mm	2.3A	105 m $\Omega$
TOKO	1 $\mu\text{H}$	FSD0312-H-1R0M	3 mmx3.2 mmx1.2 mm	3.4A	43 m $\Omega$
TDK	1 $\mu\text{H}$	VLS252012T-1R0N	2 mmx2.5 mmx1.2 mm	2.45A	73 m $\Omega$
TDK	1 $\mu\text{H}$	VLS4012ET-1R0N	4 mm x 4 mm x 1.2 mm	2.8A	50 m $\Omega$

## NTC THERMISTOR SELECTION

Programming bit [4] of Configuration Register 1 with a '1' selects NTC mode and makes the LED1/NTC pin a comparator input for flash LED thermal sensing. Figure 45 shows the LM3560 using the NTC thermistor circuit. The thermal sensor resistor divider is composed of R3 and R(T), where R(T) is the Negative Temperature Coefficient Thermistor, V<sub>BIAS</sub> is the bias voltage for the resistive divider, and R3 is used to linearize the NTC's response around the NTC comparators trip point. C<sub>BYP</sub> is used to filter noise at the NTC input.



**Figure 45. Typical Application Circuit with Thermistor**

In designing the NTC circuit, we must choose values for V<sub>BIAS</sub>, R(T) and R3. To begin with, NTC thermistors have a non-linear relationship between temperature and resistance:

$$R(T) = R_{25^\circ\text{C}} \times e^{\left[ \beta \left( \frac{1}{T^\circ\text{C} + 273} - \frac{1}{298} \right) \right]} \quad (4)$$

where  $\beta$  is given in the thermistor datasheet and  $R_{25^\circ\text{C}}$  is the thermistor's value at  $+25^\circ\text{C}$ . R3 is chosen so that the temperature to resistance relationship becomes more linear and can be found by solving for R3 in the R(T) and R3 resistive divider:

$$R3 = \frac{R_{T(\text{TRIP})} (V_{\text{BIAS}} - V_{\text{TRIP}})}{V_{\text{TRIP}}} \quad (5)$$

where  $R(T)_{\text{TRIP}}$  is the thermistor's value at the temperature trip point and  $V_{\text{TRIP}} = 1\text{V}$  (typical). As an example, with  $V_{\text{BIAS}} = 2.5\text{V}$  and a thermistor whose nominal value at  $+25^\circ\text{C}$  is 100 k $\Omega$  and a  $\beta = 4500\text{K}$ , the trip point is chosen to be  $+93^\circ\text{C}$ . The value of R(T) at  $93^\circ\text{C}$  is:



$$R(T) = 100\text{k}\Omega \times e^{\beta \left( \frac{1}{93+273} - \frac{1}{298} \right)} = 6.047\text{k}\Omega$$

$$R3 \text{ is then: } \frac{6.047\text{k}\Omega \times (2.5\text{V} - 1\text{V})}{1\text{V}} = 9.071\text{k}\Omega$$

(6)

Figure 46 shows the linearity of the thermistor resistive divider of the previous example.

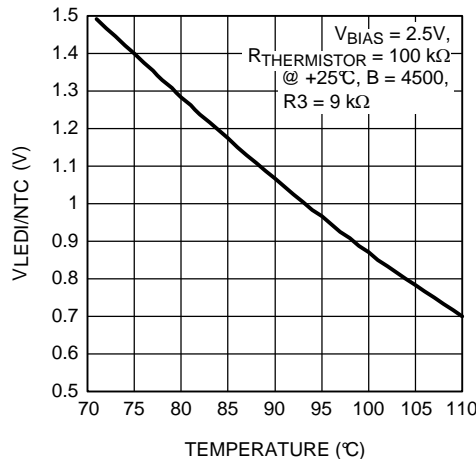


Figure 46. Thermistor Resistive Divider Response vs Temperature

## Layout Recommendations

The high switching frequency and large switching currents of the LM3560 make the choice of layout important. The following steps should be used as a reference to ensure the device is stable and maintains proper LED current regulation across its intended operating voltage and current range.

1. Place  $C_{IN}$  on the top layer (same layer as the LM3560) and as close to the device as possible. The input capacitor conducts the driver currents during the low side MOSFET turn-on and turn-off and can see current spikes over 1A in amplitude. Connecting the input capacitor through short wide traces to both the IN and GND terminals will reduce the inductive voltage spikes that occur during switching and which can corrupt the  $V_{IN}$  line.
2. Place  $C_{OUT}$  on the top layer (same layer as the LM3560) and as close as possible to the OUT and GND terminal. The returns for both  $C_{IN}$  and  $C_{OUT}$  should come together at one point, and as close to the GND pin as possible. Connecting  $C_{OUT}$  through short wide traces will reduce the series inductance on the OUT and GND terminals that can corrupt the  $V_{OUT}$  and GND line and cause excessive noise in the device and surrounding circuitry.
3. Connect the inductor on the top layer close to the SW pin. There should be a low-impedance connection from the inductor to SW due to the large DC inductor current, and at the same time the area occupied by the SW node should be small so as to reduce the capacitive coupling of the high  $dV/dt$  present at SW that can couple into nearby traces.
4. Avoid routing logic traces near the SW node so as to avoid any capacitively coupled voltages from SW onto any high-impedance logic lines such as TX1/TORCH/GPIO1, TX2/INT/GPIO2, HWEN, LED1/NTC (NTC mode), SDA, and SCL. A good approach is to insert an inner layer GND plane underneath the SW node and between any nearby routed traces. This creates a shield from the electric field generated at SW.
5. Terminate the Flash LED cathodes directly to the GND pin of the LM3560. If possible, route the LED returns with a dedicated path so as to keep the high amplitude LED currents out of the GND plane. For Flash LEDs that are routed relatively far away from the LM3560, a good approach is to sandwich the forward and return current paths over the top of each other on two layers. This will help in reducing the inductance of the LED current paths.
6. The NTC Thermistor is intended to have its return path connected to the LEDs cathode. This allows the thermistor resistive divider voltage ( $V_{NTC}$ ) to trip the comparators threshold as  $V_{NTC}$  is falling. Additionally, the thermistor-to-LED cathode junction should be connected as close as possible in order to reduce the thermal

impedance between the LED and the thermistor. The drawback is that the thermistor's return will see the switching currents from the LM3560's boost converter. Because of this, it is necessary to have a filter capacitor at the NTC pin which terminates close to the GND of the LM3560 (see  $C_{BYP}$  in [Figure 45](#)).

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## REVISION HISTORY

Changes from Original (May 2013) to Revision A	Page
• Changed layout of National Data Sheet to TI format .....	<a href="#">42</a>

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**PRODUCT PREVIEW**

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Op Temp (°C)	Top-Side Markings (4)	Samples
LM3560TLX/NOPB	ACTIVE	DSBGA	YZR	16	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM		3560	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

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## TAPE AND REEL INFORMATION



### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM3560TLX/NOPB	DSBGA	YZR	16	3000	178.0	8.4	2.08	2.08	0.76	4.0	8.0	Q1

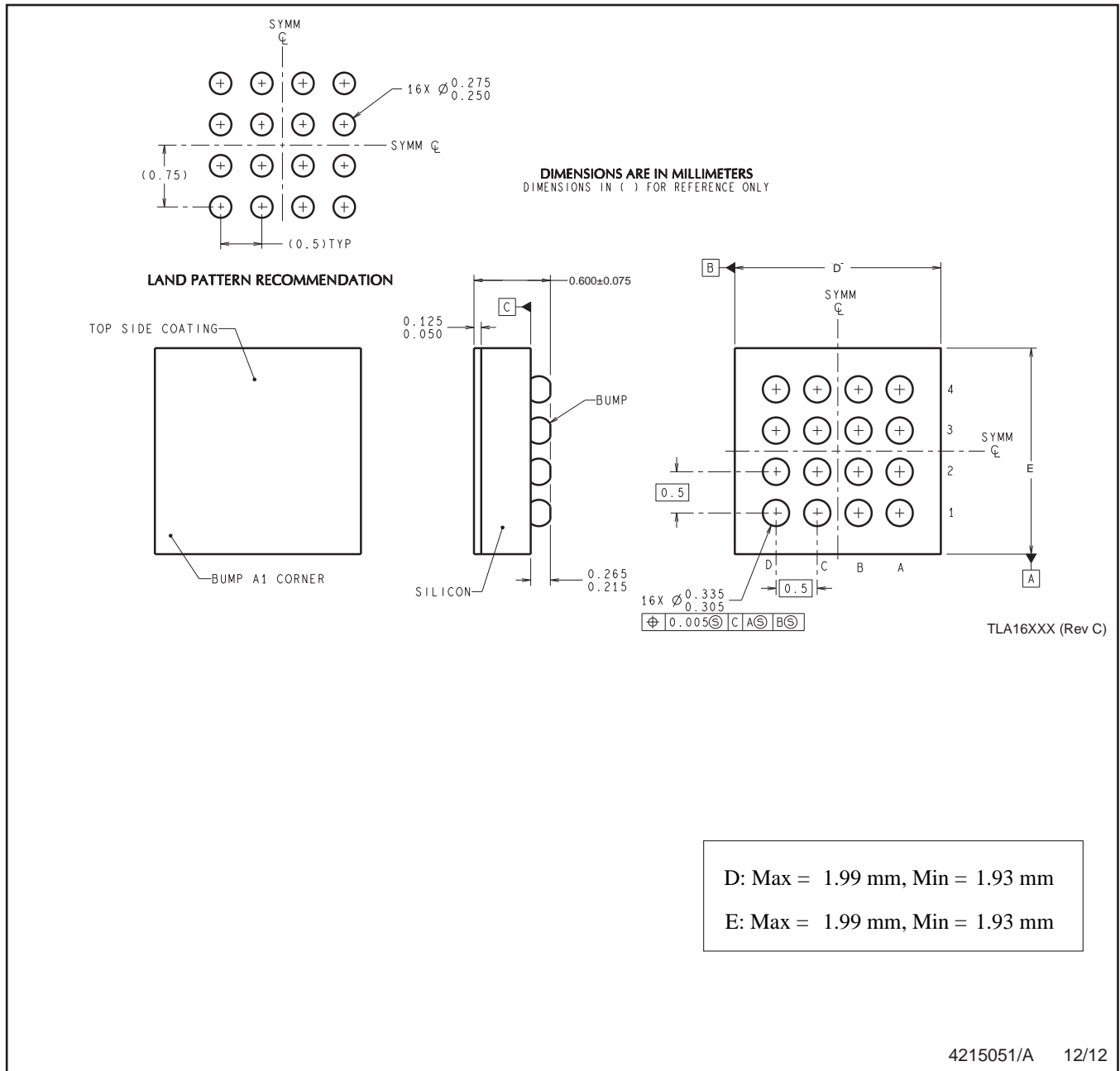
**TAPE AND REEL BOX DIMENSIONS**



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM3560TLX/NOPB	DSBGA	YZR	16	3000	210.0	185.0	35.0

YZR0016



4215051/A 12/12

NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.  
B. This drawing is subject to change without notice.

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