

LM25115 Secondary Side Post Regulator Controller

Check for Samples: LM25115

FEATURES

- Self-synchronization to Main Channel Output
- Free-run Mode for Buck Regulation of DC Input
- Leading Edge Pulse Width Modulation
- Voltage-mode Control with Current Injection and Input Line Feed-forward
- Operates from AC or DC Input up to 42V
- Wide 4.5V to 30V Bias Supply Range
- Wide 0.75V to 13.5V Output Range.
- Top and Bottom Gate Drivers Sink 2.5A Peak
- Adaptive Gate Driver Dead-time Control
- Wide Bandwidth Error Amplifier (4MHz)
- Programmable Soft-start
- Thermal Shutdown Protection
- TSSOP-16 or Thermally Enhanced WSON-16 Packages

DESCRIPTION

The LM25115 controller contains all of the features necessary to implement multiple output power Secondary converters utilizing the Side Post Regulation (SSPR) technique. The SSPR technique develops a highly efficient and well regulated auxiliary output from the secondary side switching waveform of an isolated power converter. Regulation of the auxiliary output voltage is achieved by leading edge pulse width modulation (PWM) of the main channel duty cycle. Leading edge modulation is compatible with either current mode or voltage mode control of the main output. The LM25115 drives external high side and low side NMOS power switches configured as a synchronous buck regulator. A current sense amplifier provides overload protection and operates over a wide common mode input range. Additional features include a low dropout (LDO) bias regulator, error amplifier, precision reference, adaptive dead time control of the gate signals and thermal shutdown.

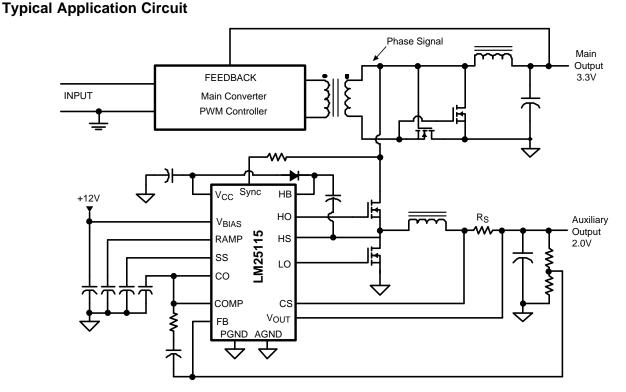


Figure 1. Simplified Multiple Output Power Converter Utilizing SSPR Technique

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Connection Diagram

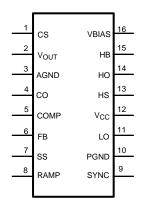


Figure 2. 16-Lead TSSOP, WSON See Package Numbers PW0016A and NHQ0016A

| Pin | Name | Description | Application Information | | | | | |
|-----|---|---|--|--|--|--|--|--|
| 1 | CS | Current Sense amplifier positive input | A low inductance current sense resistor is connected between CS and VOUT. Current limiting occurs when the differential voltage between CS and VOUT exceeds 45mV (typical). | | | | | |
| 2 | VOUT Current sense amplifier negative input | | Connected directly to the output voltage. The current sense amplifier operates over a voltage range from 0V to 13.5V at the VOUT pin. | | | | | |
| 3 | AGND | Analog ground | Connect directly to the power ground pin (PGND). | | | | | |
| 4 | CO | Current limit output | For normal current limit operation, connect the CO pin to the COMP pin. Leave this pin open to disable the current limit function. | | | | | |
| 5 | COMP | Compensation. Error amplifier output | COMP pin pull-up is provided by an internal 300uA current source. | | | | | |
| 6 | FB | Feedback. Error amplifier inverting input | Connected to the regulated output through the feedback resistor divider and compensation components. The non-inverting input of the error amplifier is internally connected to the SS pin. | | | | | |
| 7 | 7 SS Soft-start control | | An external capacitor and the equivalent impedance of an interr resistor divider connected to the bandgap voltage reference set soft-start time. The steady state operating voltage of the SS pin equal to 0.75V (typical). | | | | | |
| 8 | RAMP PWM Ramp signal | | An external capacitor connected to this pin sets the ramp slope for the voltage mode PWM. The RAMP capacitor is charged with a current that is proportional to current into the SYNC pin. The capacitor is discharged at the end of every cycle by an internal MOSFET. | | | | | |
| 9 | SYNC | Synchronization input | A low impedance current input pin. The current into this pin sets the RAMP capacitor charge current and the frequency of an internal oscillator that provides a clock for the free-run (DC input) mode . | | | | | |
| 10 | PGND | Power Ground | Connect directly to the analog ground pin (AGND). | | | | | |
| 11 | LO | Low side gate driver output | Connect to the gate of the low side synchronous MOSFET through a short, low inductance path. | | | | | |
| 12 | VCC | Output of bias regulator | Nominal 7V output from the internal LDO bias regulator. Locally decouple to PGND using a low ESR/ESL capacitor located as close to controller as possible. | | | | | |
| 13 | HS | High side MOSFET source connection | Connect to negative terminal of the bootstrap capacitor and the source terminal of the high side MOSFET. | | | | | |
| 14 | HO | High side gate driver output | Connect to the gate of high side MOSFET through a short, low inductance path. | | | | | |
| 15 | 5 HB High side gate driver bootstrap rail | | Connect to the cathode of the bootstrap diode and the positive terminal of the bootstrap capacitor. The bootstrap capacitor supplies current to charge the high side MOSFET gate and should be placed as close to controller as possible. | | | | | |

PIN DESCRIPTIONS

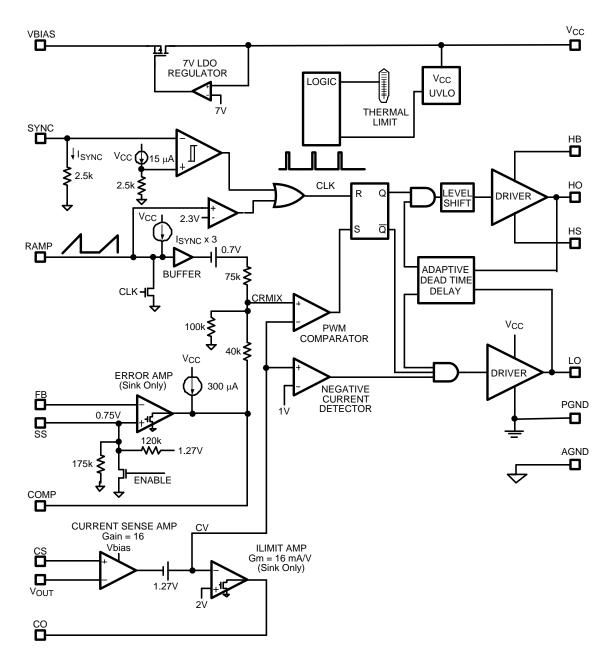


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PIN DESCRIPTIONS (continued)

| Pin | Name | Description | Application Information |
|-----|--|--|---|
| 16 | VBIAS | Supply Bias Input | Input to the LDO bias regulator and current sense amplifier that powers internal blocks. Input range of VBIAS is 4.5V to 30V. |
| - | Exposed Pad (WSON Package Only) | Exposed Pad, underside of WSON package | Internally bonded to the die substrate. Connect to system ground for low thermal impedance. |

Block Diagram



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾⁽²⁾

| VBIAS to GND | -0.3V to 32V |
|----------------------------------|-----------------|
| VCC to GND | -0.3V to 9V |
| HS to GND | -1V to 45V |
| VOUT, CS to GND | – 0.3V to 15V |
| All other inputs to GND | -0.3V to 7.0V |
| Storage Temperature Range | –55°C to +150°C |
| Junction Temperature | +150°C |
| ESD Rating HBM ⁽³⁾ | 2 kV |

(1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply ensured performance limits. For ensured performance limits and associated test conditions, see the Electrical Characteristics tables.

(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

(3) The human body model is a 100 pF capacitor discharged through a $1.5k\Omega$ resistor into each pin.

OPERATING RATINGS

| VBIAS supply voltage | 5V to 30V |
|--------------------------------|-----------------|
| VCC supply voltage | 5V to 7.5V |
| HS voltage | 0V to 42V |
| HB voltage | VCC + HS |
| Operating Junction Temperature | –40°C to +125°C |

TYPICAL OPERATING CONDITIONS

| Parameter | Min | Тур | Max | Units |
|---|-------|-----|------|-------|
| Supply Voltage, VBIAS | 4.5 | | 30 | V |
| Supply Voltage, VCC | 4.5 | | 7 | V |
| Supply voltage bypass, CVBIAS | 0.1 | 1 | | μF |
| Reference bypass capacitor, CVCC | 0.1 | 1 | 10 | μF |
| HB-HS bootstrap capacitor | 0.047 | | | μF |
| SYNC Current Range (VCC = 4.5V) | 50 | | 150 | μA |
| RAMP Saw Tooth Amplitude | 1 | | 1.75 | V |
| VOUT regulation voltage (VBIAS min = 3V + VOUT) | 0.75 | | 13.5 | V |

ELECTRICAL CHARACTERISTICS

Unless otherwise specified, $T_J = -40^{\circ}$ C to +125°C, VBIAS = 12V, No Load on LO or HO.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|------------|-----------------------------------|---|------|------|------|-------|
| VBIAS SUPP | LY | | | | | |
| Ibias | VBIAS Supply Current | F _{SYNC} = 200kHz | | | 4 | mA |
| VCC LOW DF | ROPOUT BIAS REGULATOR | | | | | |
| VccReg | VCC Regulation | VCC open circuit. Outputs not switching | 6.65 | 7 | 7.15 | V |
| | VCC Current Limit | (⁽¹⁾) | | 40 | | mA |
| | VCC Under-voltage Lockout Voltage | Positive going VCC | 4 | | 4.5 | V |
| | VCC Under-voltage Hysteresis | | 0.2 | 0.25 | 0.3 | V |

(1) Device thermal limitations may limit usable range.



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ELECTRICAL CHARACTERISTICS (continued)

Unless otherwise specified, $T_J = -40^{\circ}$ C to +125°C, VBIAS = 12V, No Load on LO or HO.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|------------------|---------------------------------|---|-------|------|-------|--------|
| SOFT-STAR | T | | | | | |
| | SS Source Impedance | | 43 | 60 | 77 | kΩ |
| | SS Discharge Impedance | | | 100 | | Ω |
| ERROR AMF | LIFIER and FEEDBACK REFERENCE | E | | | | |
| VREF | FB Reference Voltage | Measured at FB pin | 0.737 | 0.75 | 0.763 | V |
| | FB Input Bias Current | FB = 2V | | 0.2 | 0.5 | μA |
| | COMP Source Current | | | 300 | | μA |
| | Open Loop Voltage Gain | | | 60 | | dB |
| GBW | Gain Bandwidth Product | | | 4 | | MHz |
| Vio | Input Offset Voltage | | -7 | 0 | 7 | mV |
| | COMP Offset | Threshold for V_{HO} = high RAMP = CS = VOUT = 0V | | 2 | | V |
| | RAMP Offset | Threshold for V_{HO} = high COMP = 1.5V, CS = VOUT = 0V | | 1.1 | | V |
| CURRENT S | ENSE AMPLIFIER | · · · · · · · · · · · · · · · · · · · | | • | • | |
| | Current Sense Amplifier Gain | | | 16 | | V/V |
| | Output DC Offset | | | 1.27 | | V |
| | Amplifier Bandwidth | | | 500 | | kHz |
| CURRENT L | IMIT | | | l. | l. | 1 |
| | ILIMIT Amp Transconductance | | | 16 | | mA / V |
| | Overall Transconductance | | | 237 | | mA / V |
| | Positive Current Limit | $V_{CL} = V_{CS} - V_{VOUT}$ VOUT = 6V and CO/COMP = 1.5V | 37 | 45 | 53 | mV |
| | Positive Current Limit Foldback | $V_{CL} = V_{CS} - V_{VOUT}$ VOUT = 0V and CO/COMP = 1.5V | 31 | 38 | 45 | mV |
| VCLneg | Negative Current Limit | VOUT = 6V V _{CL} = V _{CS} - V _{VOUT} to cause LO to shutoff | | -17 | | mV |
| RAMP GENE | RATOR | | | | | I |
| | SYNC Input Impedance | | | 2.5 | | kΩ |
| | SYNC Threshold | End of cycle detection threshold | | 15 | | μA |
| | Free Run Mode Peak Threshold | RAMP peak voltage with dc current applied to SYNC. | | | 2.3 | V |
| | Current Mirror Gain | Ratio of RAMP charge current to SYNC input current. | 2.7 | | 3.3 | A/A |
| | Discharge Impedance | | | 100 | | Ω |
| LOW SIDE G | ATE DRIVER | | | | | |
| V _{OLL} | LO Low-state Output Voltage | I _{LO} = 100mA | | 0.2 | 0.5 | V |
| VOHL | LO High-state Output Voltage | I_{LO} = -100mA, V_{OHL} = V_{CC} - V_{LO} | | 0.4 | 0.8 | V |
| | LO Rise Time | $C_{LOAD} = 1000 pF$ | | 15 | | ns |
| | LO Fall Time | $C_{LOAD} = 1000 \text{pF}$ | | 12 | | ns |
| I _{OHL} | Peak LO Source Current | $V_{LO} = 0V$ | | 2 | | А |
| I _{OLL} | Peak LO Sink Current | $V_{LO} = 12V$ | | 2.5 | | А |

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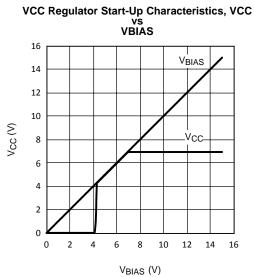
ELECTRICAL CHARACTERISTICS (continued)

Unless otherwise specified, $T_J = -40^{\circ}$ C to +125°C, VBIAS = 12V, No Load on LO or HO.

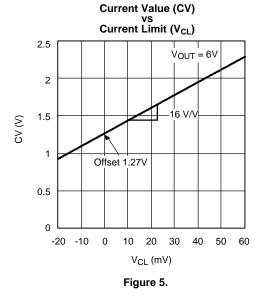
| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|------------------|------------------------------|--|-----|-----|-----|-------|
| HIGH SIDE G | ATE DRIVER | · · | | | | |
| V _{OLH} | HO Low-state Output Voltage | I _{HO} = 100mA | | 0.2 | 0.5 | V |
| V _{OHH} | HO High-state Output Voltage | I_{HO} = -100mA, V_{OHH} = V_{HB} – V_{HO} | | 0.4 | 0.8 | V |
| | HO Rise Time | $C_{LOAD} = 1000 pF$ | | 15 | | ns |
| | HO High Side Fall Time | $C_{LOAD} = 1000 pF$ | | 12 | | ns |
| I _{OHH} | Peak HO Source Current | $V_{HO} = 0V$ | | 2 | | А |
| I _{OLH} | Peak HO Sink Current | V _{HO} = 12V | | 2.5 | | А |
| SWITCHING | CHARACTERISITCS | | | | | |
| | LO Fall to HO Rise Delay | C _{LOAD} = 0 | | 70 | | ns |
| | HO Fall to LO Rise Delay | $C_{LOAD} = 0$ | | 50 | | ns |
| | SYNC Fall to HO Fall Delay | $C_{LOAD} = 0$ | | 120 | | ns |
| | SYNC Rise to LO Fall Delay | $C_{LOAD} = 0$ | | 50 | | ns |
| THERMAL S | HUTDOWN | | | | | |
| T _{SD} | Thermal Shutdown Temp. | | 150 | 165 | | °C |
| | Thermal Shutdown Hysteresis | | | 25 | | °C |
| THERMAL R | ESISTANCE | | | | | |
| θ_{JA} | Junction to Ambient | PW Package | | 125 | | °C/W |
| θ_{JA} | Junction to Ambient | NHQ Package | | 32 | | °C/W |

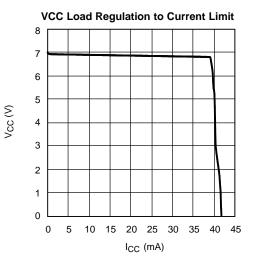


TYPICAL PERFORMANCE CHARACTERISTICS



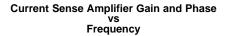


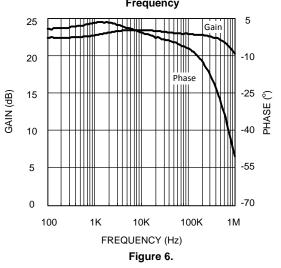




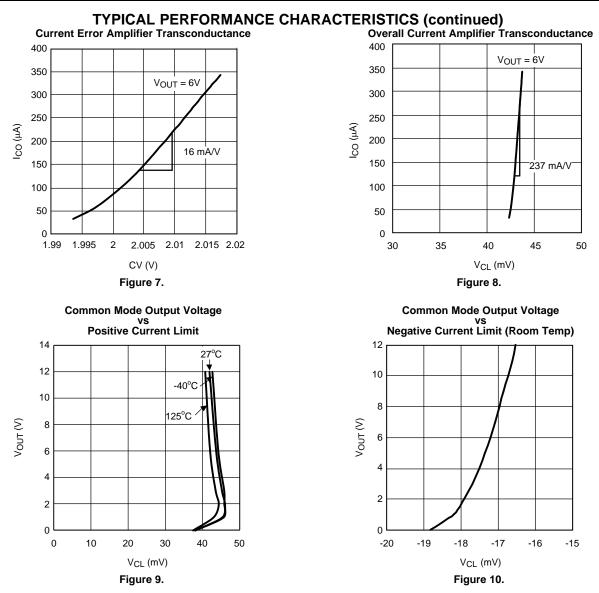
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DETAILED OPERATING DESCRIPTION

The LM25115 controller contains all of the features necessary to implement multiple output power converters utilizing the Secondary Side Post Regulation (SSPR) technique. The SSPR technique develops a highly efficient and well regulated auxiliary output from the secondary side switching waveform of an isolated power converter. Regulation of the auxiliary output voltage is achieved by leading edge pulse width modulation (PWM) of the main channel duty cycle. Leading edge modulation is compatible with either current mode or voltage mode control of the main output. The LM25115 drives external high side and low side NMOS power switches configured as a synchronous buck regulator. A current sense amplifier provides overload protection and operates over a wide common mode input range from 0V to 13.5V. Additional features include a low dropout (LDO) bias regulator, error amplifier, precision reference, adaptive dead time control of the gate driver signals and thermal shutdown. A programmable oscillator provides a PWM clock signal when the LM25115 is powered by a dc input (free-run mode) instead of the phase signal of the main channel converter (SSPR mode).

Low Drop-out Bias Regulator (VCC)

The LM25115 contains an internal LDO regulator that operates over an input supply range from 4.5V to 30V. The output of the regulator at the VCC pin is nominally regulated at 7V and is internally current limited to 40mA. VCC is the main supply to the internal logic, PWM controller, and gate driver circuits. When power is applied to the VBIAS pin, the regulator is enabled and sources current into an external capacitor connected to the VCC pin. The recommended output capacitor range for the VCC regulator is 0.1uF to 100uF. When the voltage at the VCC pin reaches the VCC under-voltage lockout threshold of 4.25V, the controller is enabled. The controller is disabled if VCC falls below 4.0V (250mV hysteresis). In applications where an appropriate regulated dc bias supply is available, the LM25115 controller can be powered directly through the VCC pin instead of the VBIAS pin. In this configuration, it is recommended that the VCC and the VBIAS pins be connected together such that the external bias voltage is applied to both pins. The allowable VCC range when biased from an external supply is 4.5V to 7V.

Synchronization (SYNC) and Feed-forward (RAMP)

The pulsing "phase signal" from the main converter synchronizes the PWM ramp and gate drive outputs of the LM25115. The phase signal is the square wave output from the transformer secondary winding before rectification (Figure 1). A resistor connected from the phase signal to the low impedance SYNC pin produces a square wave current (I_{SYNC}) as shown in Figure 11. A current comparator at the SYNC input monitors I_{SYNC} relative to an internal 15µA reference. When I_{SYNC} exceeds 15µA, the internal clock signal (CLK) is reset and the capacitor connected to the RAMP begins to charge. The current source that charges the RAMP capacitor is equal to 3 times the I_{SYNC} current. The falling edge of the phase signal sets the CLK signal and discharges the RAMP capacitor until the next rising edge of the phase signal. The RAMP capacitor is discharged to ground by a low impedance (100 Ω) n-channel MOSFET. The input impedance at SYNC pin is 2.5k Ω which is normally much less than the external SYNC pin resistance.

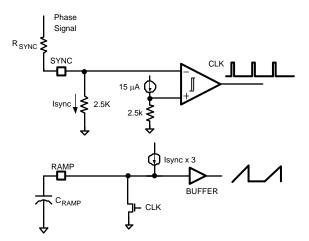


Figure 11. Line Feed-forward Diagram



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The RAMP and SYNC functions illustrated in Figure 11 provide line voltage feed-forward to improve the regulation of the auxiliary output when the input voltage of the main converter changes. Varying the input voltage to the main converter produces proportional variations in amplitude of the phase signal. The main channel PWM controller adjusts the pulse width of the phase signal to maintain constant volt*seconds and a regulated main output as shown in Figure 12. The variation of the phase signal amplitude and duration are reflected in the slope and duty cycle of the RAMP signal of the LM25115 ($I_{SYNC} \alpha$ phase signal amplitude). As a result, the duty cycle of the LM25115 is automatically adjusted to regulate the auxiliary output voltage with virtually no change in the PWM threshold voltage. Transient line regulation is improved because the PWM duty cycle of the auxiliary converter is immediately corrected, independent of the delays of the voltage regulation loop.

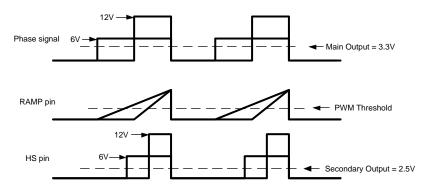


Figure 12. Line Feed-forward Waveforms

The recommended SYNC input current range is 50µA to 150µA. The SYNC pin resistor (R_{SYNC}) should be selected to set the SYNC current (I_{SYNC}) to 150µA with the maximum phase signal amplitude, $V_{PHASE(max)}$. This will ensure that I_{SYNC} stays within the recommended range over a 3:1 change in phase signal amplitude. The SYNC pin resistor is therefore:

 $R_{SYNC} = (V_{PHASE(max)} / 150\mu A) - 2.5k\Omega$

Once I_{SYNC} has been established by selecting R_{SYNC} , the RAMP signal amplitude may be programmed by selecting the proper RAMP pin capacitor value. The recommended peak amplitude of the RAMP waveform is 1V to 1.75V. The C_{RAMP} capacitor is chosen to provide the desired RAMP amplitude with the nominal phase signal voltage and pulse width.

 $C_{RAMP} = (3 \times I_{SYNC} \times T_{ON}) / V_{RAMP}$

where

- C_{RAMP} = RAMP pin capacitance
- I_{SYNC} = SYNC pin current current
- T_{ON} = corresponding phase signal pulse width
- V_{RAMP} = desired RAMP amplitude (1V to 1.75V)

For example,

Main channel output = 3.3V. Phase signal maximum amplitude = 12V. Phase signal frequency = 250kHz

- Set $I_{SYNC} = 150\mu A$ with phase signal at maximum amplitude (12V):
- $-I_{SYNC} = 150\mu A = V_{PHASE(max)} / (R_{SYNC} + 2.5 \text{ k}\Omega) = 12 \text{V} / (R_{SYNC} + 2.5 \text{ k}\Omega)$
- $-R_{SYNC} = 12V/150\mu A 2.5k\Omega = 77.5k\Omega$
- T_{ON} = Main channel duty cycle / Phase frequency = (3.3V/12V) / 250kHz = 1.1µs
- Assume desired V_{RAMP} = 1.5V
- C_{RAMP} = (3 x I_{SYNC} x T_{ON}) / V_{RAMP} = (3 x 150μA x 1.1μs) / 1.5V
- C_{RAMP} = 330pF



Error Amplifier and Soft-Start (FB, CO, & COMP, SS)

An internal wide bandwidth error amplifier is provided within the LM25115 for voltage feedback to the PWM controller. The amplifier's inverting input is connected to the FB pin. The output of the auxiliary converter is regulated by connecting a voltage setting resistor divider between the output and the FB pin. Loop compensation networks are connected between the FB pin and the error amplifier output (COMP). The amplifier's non-inverting input is internally connected to the SS pin. The SS pin is biased at 0.75V by a resistor divider connected to the internal 1.27V bandgap reference. When the VCC voltage is below the UVLO threshold, the SS pin is discharged to ground. When VCC rises and exceeds the positive going UVLO threshold (4.25V), the SS pin is released and allowed to rise. If an external capacitor is connected to the SS pin, it will be charged by the internal resistor divider to gradually increase the non-inverting input of the error amplifier to 0.75V. The equivalent impedance of the SS resistor divider is nominally $60k\Omega$ which determines the charging time constant of the SS capacitor. During start-up, the output of the LM25115 converter will follow the exponential equation:

 $VOUT(t) = VOUT(final) \times (1 - exp(-t/R_{SS} \times C_{SS}))$

where

- Rss = internal resistance of SS pin ($60k\Omega$)
- Css = external Soft-Start capacitor
- VOUT(final) = regulator output set point

The initial $\Delta v / \Delta t$ of the output voltage is VOUT(final) / Rss x Css and VOUT will be within 1% of the final regulation level after 4.6 time constants or when t = 4.6 x Rss x Css.

Pull-up current for the error amplifier output is provided by an internal 300µA current source. The PWM threshold signal at the COMP pin can be controlled by either the open drain error amplifier or the open drain current amplifier connected through the CO pin to COMP. Since the internal error amplifier is configured as an open drain output it can be disabled by connecting FB to ground. The current sense amplifier and current limiting function will be described in a later section.

Leading Edge Pulse Width Modulation

Unlike conventional voltage mode controllers, the LM25115 implements leading edge pulse width modulation. A current source equal to 3 times the I_{SYNC} current is used to charge the capacitor connected to the RAMP pin as shown in Figure 13. The ramp signal and the output of the error amplifier (COMP) are combined through a resistor network to produce a voltage ramp with variable dc offset (CRMIX in Figure 13). The high side MOSFET which drives the HS pin is held in the off state at the beginning of the phase signal. When the voltage of CRMIX exceeds the internal threshold voltage CV, the PWM comparator turns on the high side MOSFET. The HS pin rises and the MOSFET delivers current from the main converter phase signal to the output of the auxiliary regulator. The PWM cycle ends when the phase signal falls and power is no longer supplied to the drain of the high side MOSFET.

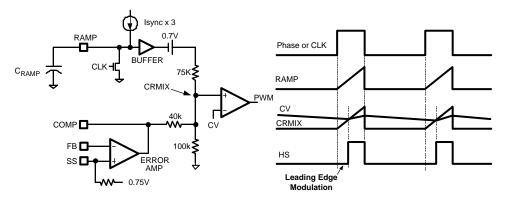


Figure 13. Synchronization and Leading Edge Modulation



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Leading edge modulation of the auxiliary PWM controller is required if the main converter is implemented with peak current mode control. If trailing edge modulation were used, the additional load on the transformer secondary from the auxiliary channel would be drawn only during the first portion of the phase signal pulse. Referring to Figure 14, the turn off the high side MOSFET of the auxiliary regulator would create a non-monotonic negative step in the transformer current. This negative current step would produce instability in a peak current mode controller. With leading edge modulation, the additional load presented by the auxiliary regulator on the transformer secondary will be present during the latter portion of the phase signal. This positive step in the phase signal current can be accommodated by a peak current mode controller without instability.

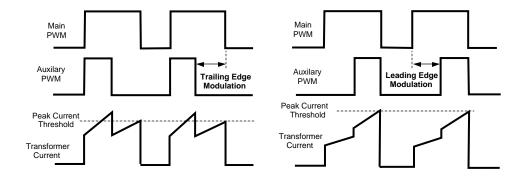


Figure 14. Leading versus Trailing Edge Modulation

Voltage Mode Control with Current Injection

The LM25115 controller uniquely combines elements and benefits of current mode control in a voltage mode PWM controller. The current sense amplifier shown in Figure 15 monitors the inductor current as it flows through a sense resistor connected between CS and VOUT. The voltage gain of the sense amplifier is nominally equal to 16. The current sense output signal is shifted by 1.27V to produce the internal CV reference signal. The CV signal is applied to the negative input of the PWM comparator and compared to CRMIX as illustrated in Figure 13. Thus the PWM threshold of the voltage mode controller (CV) varies with the instantaneous inductor current. Insure that the Vbias voltage is at least 3V above the regulated output voltage (VOUT).

Injecting a signal proportional to the instantaneous inductor current into a voltage mode controller improves the control loop stability and bandwidth. This current injection eliminates the lead R-C lead network in the feedback path that is normally required with voltage mode control (see Figure 16). Eliminating the lead network not only simplifies the compensation, but also reduces sensitivity to output noise that could pass through the lead network to the error amplifier.

The design of the voltage feedback path through the error amp begins with the selection of R1 and R2 in Figure 16 to set the regulated output voltage. The steady state output voltage after soft-start is determined by the following equation:

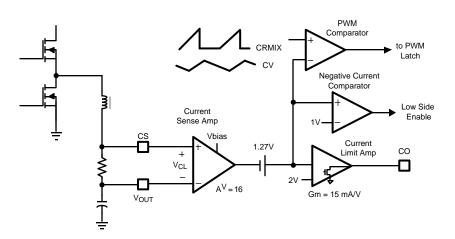
$VOUT(final) = 0.75V \times (1+R1/R2)$

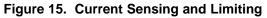
The parallel impedance of the R1, R2 resistor divider should be approximately $2k\Omega$ (between $0.5k\Omega$ and $5k\Omega$). Lower resistance values may not be properly driven by the error amplifier output and higher feedback resistances can introduce noise sensitivity. The next step in the design process is selection of R3, which sets the ac gain of the error amplifier. The ac gain is given by the following equation and should be set to a value less than 30.

GAIN(ac) = R3/(R1|| R2) < 30

The capacitor C1 is connected in series with R3 to increase the dc gain of the voltage regulation loop and improve output voltage accuracy. The corner frequency set by R3 x C1 should be less than 1/10th of the cross-over frequency of the overall converter such that capacitor C1 does not add phase lag at the crossover frequency. Capacitor C2 is added to reduce the noise in the voltage control loop. The value of C2 should be less than 500pF and C2 may not be necessary with very careful PC board layout.

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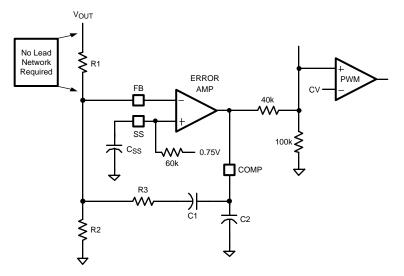


Figure 16. Voltage Sensing and Feedback

Current Limiting (CS, CO and VOUT)

Current limiting is implemented through the current sense amplifier as illustrated in Figure 15. The current sense amplifier monitors the inductor current that flows through a sense resistor connected between CS and VOUT. The voltage gain of the current sense amplifier is nominally equal to 16. The output of current sense amplifier is level shifted by 1.27V to produce the internal CV reference signal. The CV signal drives a current limit amplifier with nominal transconductance of 16mA/V. The current limit amplifier has an open drain (sink only) output stage and its output pin, CO is typically connected to the COMP pin. During normal operation, the voltage error amplifier controls the COMP pin voltage which adjusts the PWM duty cycle by varying the internal CRMIX level (Figure 13). However, when the current sense input voltage V_{CL} exceeds 45mV, the current limit amplifier pulls down on COMP through the CO pin. Pulling COMP low reduces the CRMIX signal below the CV signal level. When CRMIX does not exceed the CV signal, the PWM comparator inhibits output pulses until the CRMIX signal increases to a normal operating level.

A current limit fold-back feature is provided by the LM25115 to reduce the peak output current delivered to a shorted load. When the common mode input voltage to the current sense amplifier (CS and VOUT pins) falls below 2V, the current limit threshold is reduced from the normal level. At common mode voltages > 2V, the current limit threshold is nominally 45mV. When VOUT is reduced to 0V the current limit threshold drops to 36mV to reduce stress on the inductor and power MOSFETs.

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Negative Current Limit

When inductor current flows from the regulator output through the low side MOSFET, the input to the current sense comparator becomes negative. The intent of the negative current comparator is to protect the low-side MOSFET from excessive currents. Negative current can lead to large negative voltage spikes on the output at turn off which can damage circuitry powered by the output. The negative current comparator threshold is sufficiently negative to allow inductor current to reverse at no load or light load conditions. It is not intended to support discontinuous conduction mode with diode emulation by the low-side MOSFET. The negative current comparator illustrated in Figure 15 monitors the CV signal and compares this signal to a fixed 1V threshold. This corresponds to a negative V_{CL} voltage between CS and VOUT of -17mV. The negative current limit comparator turns off the low-side MOSFET for the remainder of the cycle when the V_{CL} input falls below this threshold.

Gate Drivers Outputs (HO & LO)

The LM25115 provides two gate driver outputs, the floating high-side gate driver HO and the synchronous rectifier low-side driver LO. The low-side driver is powered directly by the VCC regulator. The high-side gate driver is powered from a bootstrap capacitor connected between HB and HS. An external diode connected between VCC and HB charges the bootstrap capacitor when the HS is low. When the high-side MOSFET is turned on, HB rises with HS to a peak voltage equal to VCC + $V_{HS} - V_D$ where V_D is the forward drop of the external bootstrap diode. Both output drivers have adaptive dead-time control to avoid shoot through currents. The adaptive dead-time control circuit monitors the state of each driver to ensure that the opposing MOSFET is turned off before the other is turned on. The HB and VCC capacitors should be placed close to the pins of the LM25115 to minimize voltage transients due to parasitic inductances and the high peak output currents of the drivers. The recommended range of the HB capacitor is 0.047µF to 0.22µF.

Both drivers are controlled by the PWM logic signal from the PWM latch. When the phase signal is low, the outputs are held in the reset state with the low-side MOSFET on and the high-side MOSFET off. When the phase signal switches to the high state, the PWM latch reset signal is de-asserted. The high-side MOSFET remains off until the PWM latch is set by the PWM comparator (CRMIX > CV as shown in Figure 13). When the PWM latch is set, the LO driver turns off the low-side MOSFET and the HO driver turns on the high-side MOSFET. The high-side pulse is terminated when the phase signal falls and the SYNC input comparator resets the PWM latch.

Free-Run Mode

The LM25115 can be operated as a conventional synchronous buck controller with a dc input supply instead of the square wave phase signal. In the dc or free-run mode, the LM25115 PWM controller synchronizes to an internal clock signal instead of the phase signal pulses. The clock frequency in the free-run mode is programmed by the SYNC pin resistor and RAMP pin capacitor. Connecting a resistor between a dc bias supply and the SYNC pin produces a current I_{SYNC} which controls the charging current of the RAMP pin capacitor . The RAMP capacitor is charged until its voltage reaches the free-run mode peak threshold of 2.25V. The RAMP capacitor is then discharged for 300ns before beginning a new PWM cycle. The 300ns reset time of the RAMP pin sets the minimum off time of the PWM controller in the free-run mode. The internal clock frequency in the free-run mode is set by the synchronization current, ramp capacitor, free-run peak threshold, and 300ns deadtime.

$$F_{CLK} \cong 1 / ((C_{RAMP} \times 2.25V) / (I_{SYNC} \times 3) + 300ns)$$

Note that the VCC supply can be used as the dc bias to produce I_{SYNC}. Note that the input voltage feedforward is no longer functional in this operating mode, so the loop gain will vary as a function of Vin. The LM25115 controls the buck power stage with leading edge pulse width modulaton to hold off the high-side driver until the necessary volt*seconds is established for regulation. Other features described for the secondary side post regulator apply in the free run mode operation. They include voltage mode control with current injection, positive and negative current limit, programmable soft-start, adaptive delays for outputs, and thermal protection.

Thermal Protection

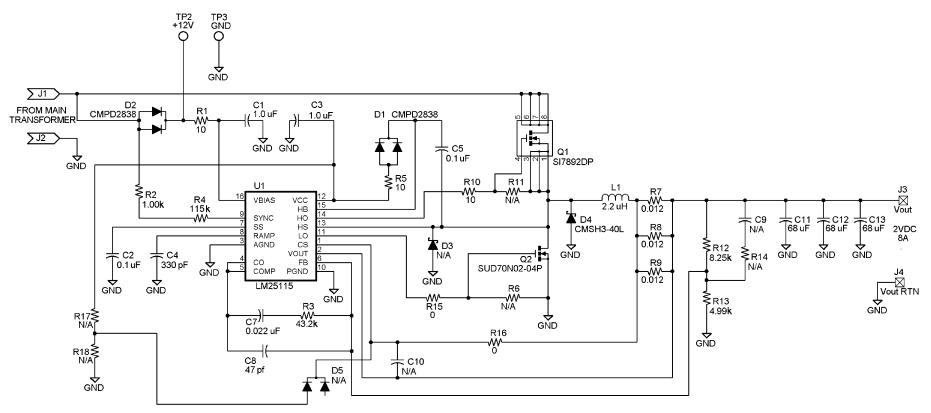
Internal thermal shutdown circuitry is provided to protect the integrated circuit in the event the maximum junction temperature limit is exceeded. When activated, typically at 165 degrees Celsius, the controller is forced into a low power standby state with the output drivers and the bias regulator disabled. The device will restart when the junction temperature falls below the thermal shutdown hysteresis, which is typically 25 degrees. The thermal protection feature is provided to prevent catastrophic failures from accidental device overheating.



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LM25115

Application Circuit



(Inputs from LM5025 Forward Active Clamp Converter, 36V to 78V)

Figure 17. LM25115 Secondary Side Post Regulator

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REVISION HISTORY

| Cł | nanges from Original (March 2013) to Revision A F | Page |
|----|--|------|
| • | Changed layout of National Data Sheet to TI format | . 14 |

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11-Apr-2013

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | | Lead/Ball Finish | | Op Temp (°C) | Top-Side Markings | Samples |
|------------------|---------------|--------------|--------------------|------|----------------|----------------------------|------------------|--------------------|--------------|---------------------|---------|
| LM25115MT | ACTIVE | TSSOP | PW | 16 | 92 | (2) TBD | Call TI | (3) Call TI | -40 to 125 | (4) L25115 MT | Samples |
| LM25115MT/NOPB | ACTIVE | TSSOP | PW | 16 | 92 | Green (RoHS & no Sb/Br) | CU SN | Level-1-260C-UNLIM | -40 to 125 | L25115 MT | Samples |
| LM25115MTX | ACTIVE | TSSOP | PW | 16 | 2500 | TBD | Call TI | Call TI | -40 to 125 | L25115 MT | Samples |
| LM25115MTX/NOPB | ACTIVE | TSSOP | PW | 16 | 2500 | Green (RoHS & no Sb/Br) | CU SN | Level-1-260C-UNLIM | -40 to 125 | L25115 MT | Samples |
| LM25115SD | ACTIVE | WSON | NHQ | 16 | 1000 | TBD | Call TI | Call TI | -40 to 125 | L25115 | Samples |
| LM25115SD/NOPB | ACTIVE | WSON | NHQ | 16 | 1000 | Green (RoHS & no Sb/Br) | CU SN | Level-1-260C-UNLIM | -40 to 125 | L25115 | Samples |
| LM25115SDX | ACTIVE | WSON | NHQ | 16 | 4500 | TBD | Call TI | Call TI | -40 to 125 | L25115 | Samples |
| LM25115SDX/NOPB | ACTIVE | WSON | NHQ | 16 | 4500 | Green (RoHS & no Sb/Br) | CU SN | Level-1-260C-UNLIM | -40 to 125 | L25115 | Samples |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.



PACKAGE OPTION ADDENDUM

11-Apr-2013

⁽⁴⁾ Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

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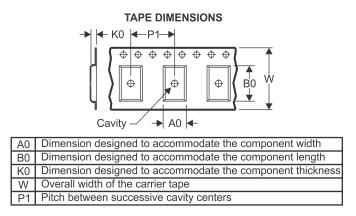
PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



| *All dimensions are nominal | | | | | | | | | | | | |
|-----------------------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| Device | Package Type | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
| LM25115MTX | TSSOP | PW | 16 | 2500 | 330.0 | 12.4 | 6.95 | 8.3 | 1.6 | 8.0 | 12.0 | Q1 |
| LM25115MTX/NOPB | TSSOP | PW | 16 | 2500 | 330.0 | 12.4 | 6.95 | 8.3 | 1.6 | 8.0 | 12.0 | Q1 |
| LM25115SD | WSON | NHQ | 16 | 1000 | 178.0 | 12.4 | 5.3 | 5.3 | 1.3 | 8.0 | 12.0 | Q1 |
| LM25115SD/NOPB | WSON | NHQ | 16 | 1000 | 178.0 | 12.4 | 5.3 | 5.3 | 1.3 | 8.0 | 12.0 | Q1 |
| LM25115SDX | WSON | NHQ | 16 | 4500 | 330.0 | 12.4 | 5.3 | 5.3 | 1.3 | 8.0 | 12.0 | Q1 |
| LM25115SDX/NOPB | WSON | NHQ | 16 | 4500 | 330.0 | 12.4 | 5.3 | 5.3 | 1.3 | 8.0 | 12.0 | Q1 |

TEXAS INSTRUMENTS

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PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|-----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| LM25115MTX | TSSOP | PW | 16 | 2500 | 349.0 | 337.0 | 45.0 |
| LM25115MTX/NOPB | TSSOP | PW | 16 | 2500 | 349.0 | 337.0 | 45.0 |
| LM25115SD | WSON | NHQ | 16 | 1000 | 210.0 | 185.0 | 35.0 |
| LM25115SD/NOPB | WSON | NHQ | 16 | 1000 | 210.0 | 185.0 | 35.0 |
| LM25115SDX | WSON | NHQ | 16 | 4500 | 367.0 | 367.0 | 35.0 |
| LM25115SDX/NOPB | WSON | NHQ | 16 | 4500 | 367.0 | 367.0 | 35.0 |

PW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



NOTES:

A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. β . This drawing is subject to change without notice.

Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.

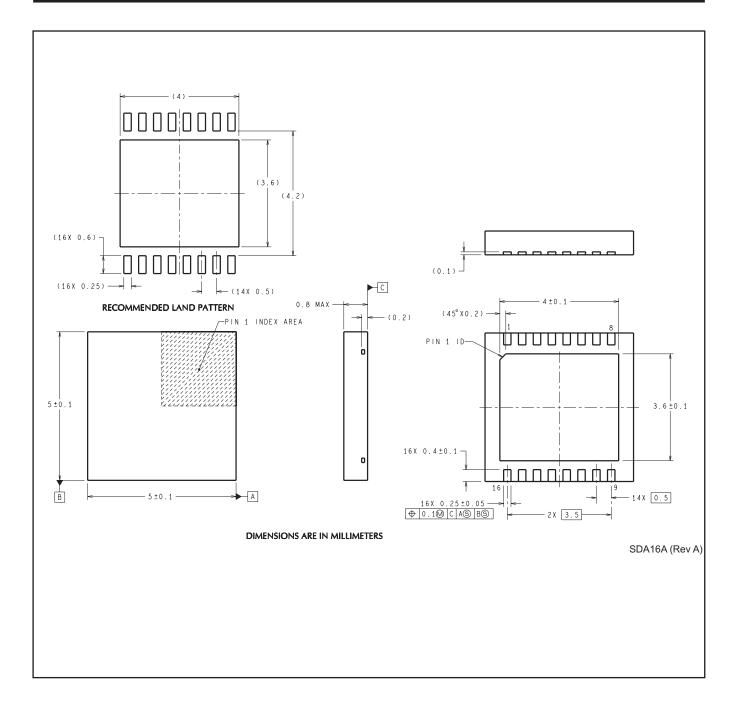
Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.

E. Falls within JEDEC MO-153



MECHANICAL DATA

NHQ0016A





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