

# LM22679/LM22679Q 42V, 5A SIMPLE SWITCHER® Step-Down Voltage Regulator with Features

Check for Samples: [LM22679/LM22679Q](#)

## FEATURES

- **Wide Input Voltage Range: 4.5V to 42V**
- **Internally Compensated Voltage Mode Control**
- **Stable with Low ESR Ceramic Capacitors**
- **100 mΩ N-Channel MOSFET**
- **Output Voltage Options:**
  - **ADJ (Outputs as Low as 1.285V)**
  - **5.0 (Output Fixed to 5V)**
- **±1.5% Feedback Reference Accuracy**
- **Switching Frequency of 500 kHz**
- **-40°C to 125°C Operating Junction Temperature Range**
- **Adjustable Soft-Start**
- **Adjustable Current Limit**
- **Integrated Boot-Strap Diode**
- **Fully WEBENCH® Enabled**
- **LM22679Q is AEC-Q100 qualified and manufactured on an Automotive Grade Flow**

## PACKAGE

- **PFM (Exposed Pad)**

## APPLICATIONS

- **Industrial Control**
- **Telecom and Datacom Systems**
- **Embedded Systems**
- **Conversions from Standard 24V, 12V and 5V Input Rails**

## DESCRIPTION

The LM22679 switching regulator provides all of the functions necessary to implement an efficient high voltage step-down (buck) regulator using a minimum of external components. This easy to use regulator incorporates a 42V N-channel MOSFET switch capable of providing up to 5A of load current. Excellent line and load regulation along with high efficiency (>90%) are featured. Voltage mode control offers short minimum on-time, allowing the widest ratio between input and output voltages. Internal loop compensation means that the user is free from the tedious task of calculating the loop compensation components. Fixed 5V output and adjustable output voltage options are available. A switching frequency of 500 kHz allows for small external components and good transient response. An adjustable soft-start feature is provided through the selection of a single external capacitor. In addition, the switch current limit can be programmed with a single external resistor, allowing solution optimization. The LM22679 also has built in thermal shutdown, and current limiting to protect against accidental overloads.

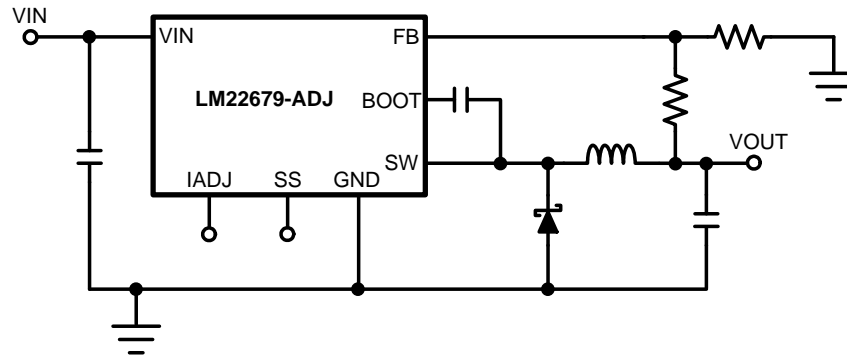
The LM22679 is a member of Texas Instruments' SIMPLE SWITCHER™ family. The SIMPLE SWITCHER™ concept provides for an easy to use complete design using a minimum number of external components and the TI WEBENCH® design tool. TI's WEBENCH® tool includes features such as external component calculation, electrical simulation, thermal simulation, and Build-It boards for easy design-in.



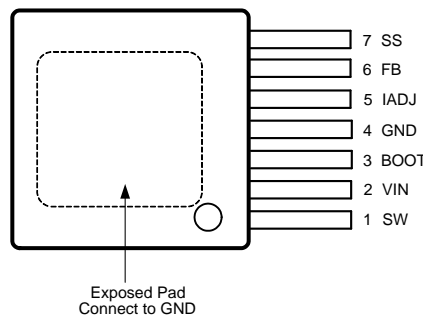
Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

All trademarks are the property of their respective owners.

### Simplified Application Schematic



### Connection Diagram



**Figure 1. Connection Diagram  
Package Number NDR0007A**

### PIN DESCRIPTIONS

Pin	Name	Description	Application Information
1	SW	Switch Output	Switching output of regulator.
2	VIN	Input Voltage	Supply input to regulator.
3	BOOT	Bootstrap input	Provides the gate voltage for the high side NFET
4	GND	Ground input to regulator; system common	System ground pin.
5	IADJ	Current limit adjust input pin	A resistor attached between this pin and GND can be used to set the current limit threshold. Pin can be left floating and internal setting will be default.
6	FB	Feedback Input	Feedback input to regulator.
7	SS	Soft-start pin	Used to increase soft-start time. See <a href="#">Soft-Start</a> .
EP	EP	Exposed Pad	Connect to ground. Provides thermal connection to PCB. See <a href="#">Application Information</a> .



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### Absolute Maximum Ratings<sup>(1)(2)</sup>

VIN to GND		43V
SS, IADJ Pin Voltage		-0.5V to 7V
SW to GND <sup>(3)</sup>		-5V to VIN
Boot Pin Voltage		V <sub>SW</sub> + 7V
FB Pin Voltage		-0.5V to 7V
Power Dissipation		Internally Limited
Junction Temperature <sup>(4)</sup>		150°C
ESD Rating <sup>(5)</sup>	Human Body Model	±2 kV
Storage Temperature Range		-65°C to +150°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the recommended Operating Ratings is not implied. The recommended Operating Ratings indicate conditions at which the device is functional and should not be operated beyond such conditions.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
- (3) The absolute maximum specification of the 'SW to GND' applies to DC voltage. An extended negative voltage limit of -10V applies to a pulse of up to 50 ns.
- (4) For soldering specifications, refer to the following document: [www.ti.com/lit/snoa549](http://www.ti.com/lit/snoa549)
- (5) ESD was applied using the human body model, a 100 pF capacitor discharged through a 1.5 kΩ resistor into each pin.

### Operating Ratings<sup>(1)</sup>

Supply Voltage (VIN)	4.5V to 42V
Junction Temperature Range	-40°C to +125°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the recommended Operating Ratings is not implied. The recommended Operating Ratings indicate conditions at which the device is functional and should not be operated beyond such conditions.

### Electrical Characteristics

Limits in standard type are for T<sub>J</sub> = 25°C only; limits in **boldface type** apply over the junction temperature (T<sub>J</sub>) range of -40°C to +125°C. Minimum and Maximum limits are guaranteed through test, design, or statistical correlation. Typical values represent the most likely parametric norm at T<sub>A</sub> = T<sub>J</sub> = 25°C, and are provided for reference purposes only. Unless otherwise specified: V<sub>IN</sub> = 12V.

Symbol	Parameter	Conditions	Min <sup>(1)</sup>	Typ <sup>(2)</sup>	Max <sup>(1)</sup>	Units
<b>LM22679-5.0</b>						
V <sub>FB</sub>	Feedback Voltage	V <sub>IN</sub> = 8V to 42V	4.925/ <b>4.9</b>	5.0	5.075/ <b>5.1</b>	V
<b>LM22679-ADJ</b>						
V <sub>FB</sub>	Feedback Voltage	V <sub>IN</sub> = 4.7V to 42V	1.266/ <b>1.259</b>	1.285	1.304/ <b>1.311</b>	V
<b>All Output Voltage Versions</b>						
I <sub>Q</sub>	Quiescent Current	V <sub>FB</sub> = 5V		3.4	<b>6</b>	mA
V <sub>ADJ</sub>	Current Limit Adjust Voltage		<b>0.65</b>	0.8	<b>0.9</b>	V
I <sub>CL</sub>	Current Limit		6.0/ <b>5.75</b>	7.1	8.4/ <b>8.75</b>	A
I <sub>L</sub>	Output Leakage Current	V <sub>IN</sub> = 42V, SS Pin = 0V, V <sub>SW</sub> = 0V		32	60	μA
		V <sub>SW</sub> = -1V		31	75	μA
R <sub>DS(ON)</sub>	Switch On-Resistance			0.10	0.14/ <b>0.2</b>	Ω
f <sub>O</sub>	Oscillator Frequency		<b>400</b>	500	<b>600</b>	kHz
T <sub>OFFMIN</sub>	Minimum Off-time		<b>100</b>	200	<b>300</b>	ns
T <sub>ONMIN</sub>	Minimum On-time			100		ns
I <sub>BIAS</sub>	Feedback Bias Current	V <sub>FB</sub> = 1.3V (ADJ Version Only)		230		nA
I <sub>SS</sub>	Soft-start Current		<b>30</b>	50	<b>70</b>	μA

- (1) Min and Max limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlation using Statistical Quality Control (SQC) methods. Limits are used to calculate TI's Average Outgoing Quality Level (AOQL).
- (2) Typical values represent most likely parametric norms at the conditions specified and are not guaranteed.

### Electrical Characteristics (continued)

Limits in standard type are for  $T_J = 25^\circ\text{C}$  only; limits in **boldface type** apply over the junction temperature ( $T_J$ ) range of  $-40^\circ\text{C}$  to  $+125^\circ\text{C}$ . Minimum and Maximum limits are guaranteed through test, design, or statistical correlation. Typical values represent the most likely parametric norm at  $T_A = T_J = 25^\circ\text{C}$ , and are provided for reference purposes only. Unless otherwise specified:  $V_{IN} = 12\text{V}$ .

Symbol	Parameter	Conditions	Min <sup>(1)</sup>	Typ <sup>(2)</sup>	Max <sup>(1)</sup>	Units
$T_{SD}$	Thermal Shutdown Threshold			150		$^\circ\text{C}$
$\theta_{JA}$	Thermal Resistance	Junction to ambient thermal resistance <sup>(3)</sup>		22		$^\circ\text{C}/\text{W}$

- (3) The value of  $\theta_{JA}$  for the PFM (TJ) package of  $22^\circ\text{C}/\text{W}$  is valid if package is mounted to 1 square inch of copper. The  $\theta_{JA}$  value can range from 20 to  $30^\circ\text{C}/\text{W}$  depending on the amount of PCB copper dedicated to heat transfer. See application note AN-1797 for more information.

### Typical Performance Characteristics

Unless otherwise specified the following conditions apply:  $V_{in} = 12V$ ,  $T_J = 25^\circ C$ .

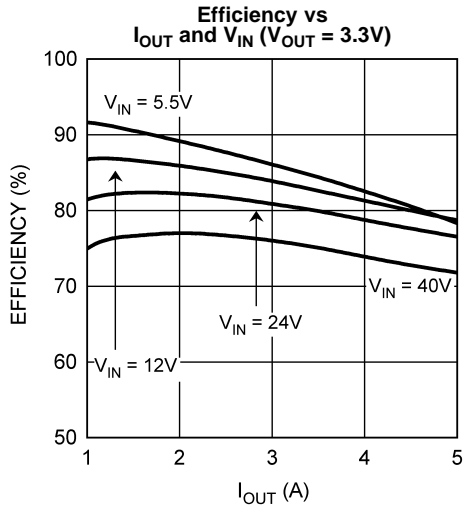


Figure 2.

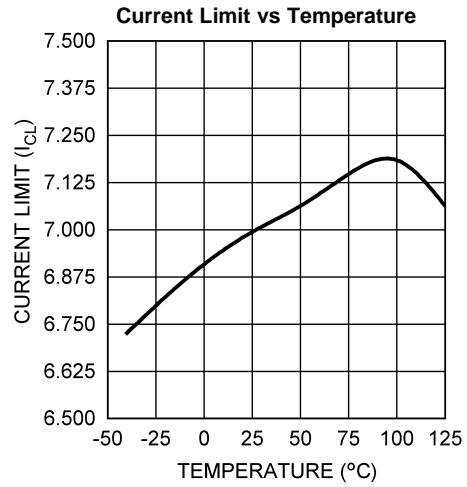


Figure 3.

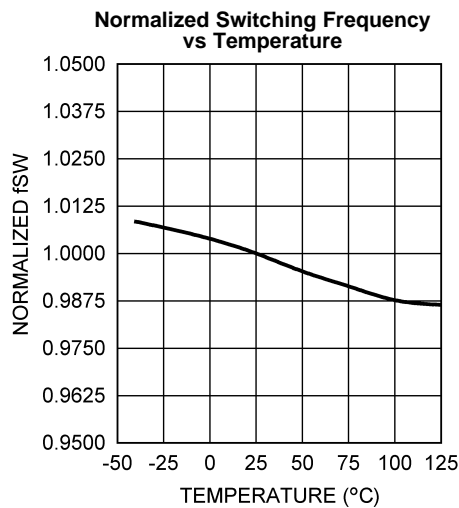


Figure 4.

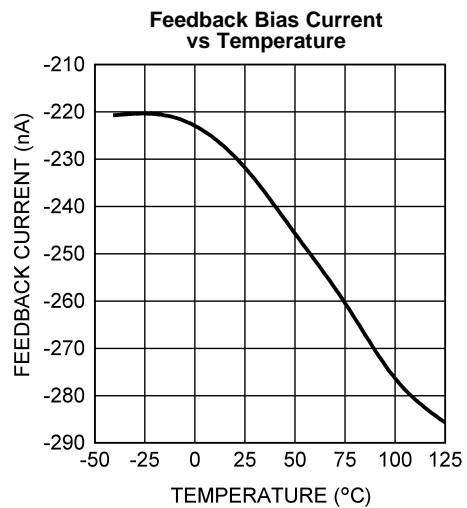


Figure 5.

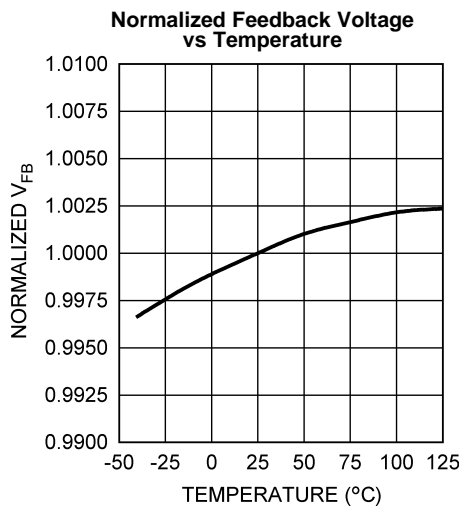


Figure 6.

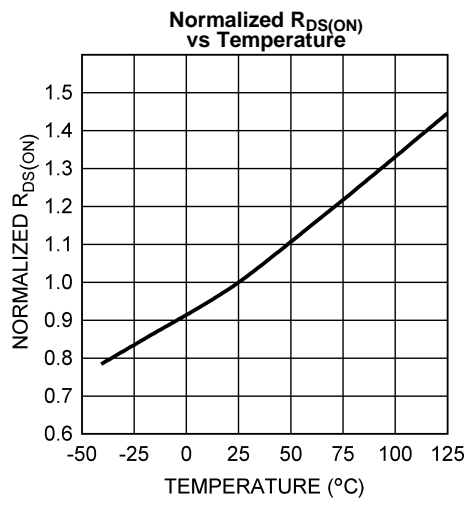


Figure 7.

**Typical Performance Characteristics (continued)**

Unless otherwise specified the following conditions apply:  $V_{in} = 12V$ ,  $T_J = 25^{\circ}C$ .

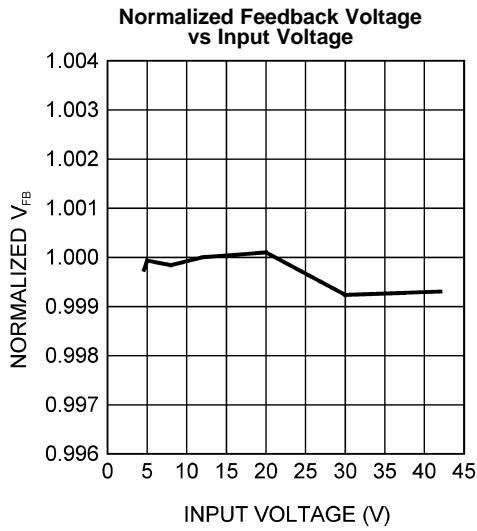


Figure 8.

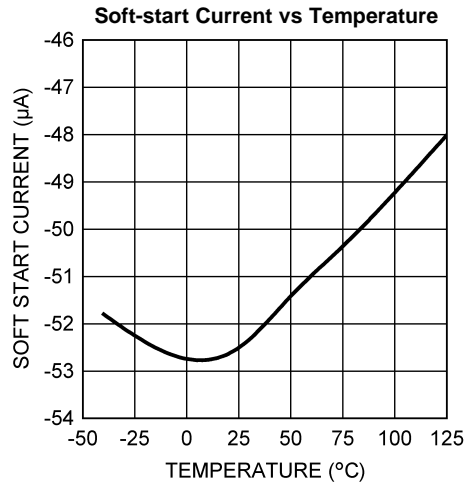


Figure 9.

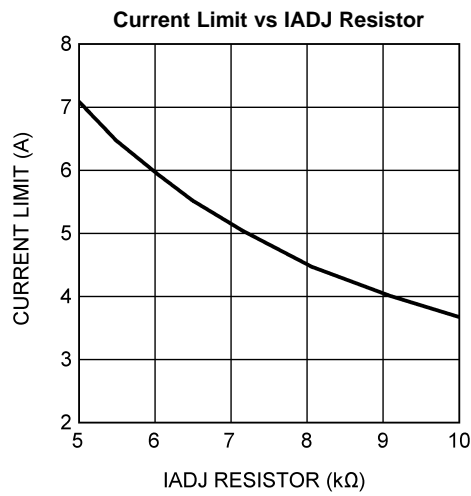


Figure 10.

Simplified Block Diagram

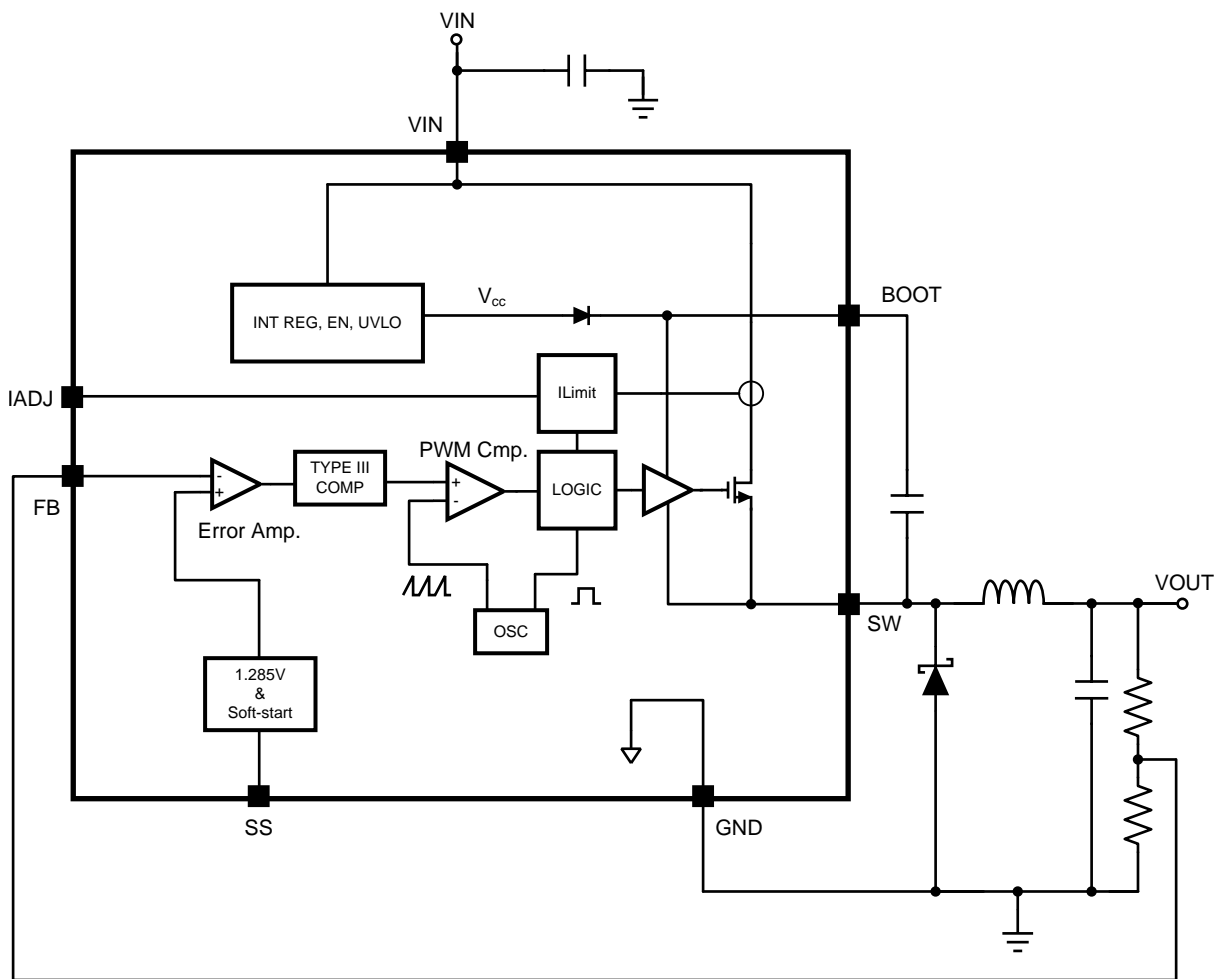


Figure 11. Simplified Block Diagram

## Detailed Operating Description

The LM22679 incorporates a voltage mode constant frequency PWM architecture. In addition, input voltage feed-forward is used to stabilize the loop gain against variations in input voltage. This allows the loop compensation to be optimized for transient performance. The power MOSFET, in conjunction with the diode, produce a rectangular waveform at the switch pin, that swings from about zero volts to VIN. The inductor and output capacitor average this waveform to become the regulator output voltage. By adjusting the duty cycle of this waveform, the output voltage can be controlled. The error amplifier compares the output voltage with the internal reference and adjusts the duty cycle to regulate the output at the desired value.

The internal loop compensation of the -ADJ option is optimized for outputs of 5V and below. If an output voltage of 5V or greater is required, the -5.0 option can be used with an external voltage divider. The minimum output voltage is equal to the reference voltage; 1.285V (typ.).

The functional block diagram of the LM22679 is shown in [Figure 11](#).

### UVLO

The LM22679 also incorporates an input under voltage lock-out (UVLO) feature. This prevents the regulator from turning on when the input voltage is not great enough to properly bias the internal circuitry. The rising threshold is 4.3V (typ.) while the falling threshold is 3.9V (typ.).

### Duty-Cycle Limits

Ideally the regulator would control the duty cycle over the full range of zero to one. However due to inherent delays in the circuitry, there are limits on both the maximum and minimum duty cycles that can be reliably controlled. This in turn places limits on the maximum and minimum input and output voltages that can be converted by the LM22679. A minimum on-time is imposed by the regulator in order to correctly measure the switch current during a current limit event. A minimum off-time is imposed in order to re-charge the bootstrap capacitor. The following equation can be used to determine the approximate maximum input voltage for a given output voltage:

$$V_{in|_{max}} \approx \frac{V_{out} + 0.4}{T_{on} \cdot F_{sw} \cdot 1.8} \quad (1)$$

Where  $F_{sw}$  is the switching frequency and  $T_{ON}$  is the minimum on-time; both found in the [Electrical Characteristics](#) table. Nominal values should be used. The worst case is lowest output voltage. If this input voltage is exceeded, the regulator will skip cycles, effectively lowering the switching frequency. The consequences of this are higher output voltage ripple and a degradation of the output voltage accuracy.

The second limitation is the maximum duty cycle before the output voltage will "dropout" of regulation. The following equation can be used to approximate the minimum input voltage before dropout occurs:

$$V_{in|_{min}} \approx \frac{V_{out} + 0.4 + I_{out} \cdot R_L}{1 - T_{off} \cdot F_{sw} \cdot 1.8} + I_{out} \cdot R_{dson} \quad (2)$$

The values of  $T_{OFF}$  and  $R_{DS(ON)}$  are found in the [Electrical Characteristics](#) table. The worst case here is largest load. In this equation,  $R_L$  is the D.C. inductor resistance. Of course, the lowest input voltage to the regulator must not be less than 4.5V (typ.).

### Current Limit

The LM22679 has current limiting to prevent the switch current from exceeding safe values during an accidental overload on the output. This peak current limit is found in the [Electrical Characteristics](#) table under the heading of  $I_{CL}$ . The maximum load current that can be provided, before current limit is reached, is determined from the following equation:

$$I_{out|_{max}} \approx I_{CL} - \frac{(V_{in} - V_{out})}{2 \cdot L \cdot F_{sw}} \cdot \frac{V_{out}}{V_{in}} \quad (3)$$

Where L is the value of the power inductor.



When the LM22679 enters current limit, the output voltage will drop and the peak inductor current will be fixed at  $I_{CL}$  at the end of each cycle. The switching frequency will remain constant while the duty cycle drops. The load current will not remain constant, but will depend on the severity of the overload and the output voltage.

For very severe overloads ("short-circuit"), the regulator changes to a low frequency current foldback mode of operation. The frequency foldback is about 1/5 of the nominal switching frequency. This will occur when the current limit trips before the minimum on-time has elapsed. This mode of operation is used to prevent inductor current "run-away", and is associated with very low output voltages when in overload. The following equation can be used to determine what level of output voltage will cause the part to change to low frequency current foldback:

$$V_x \leq V_{in} \cdot F_{sw} \cdot T_{on} \cdot 1.8 \quad (4)$$

Where  $F_{sw}$  is the normal switching frequency and  $V_{in}$  is the maximum for the application. If the overload drives the output voltage to less than or equal to  $V_x$ , the part will enter current foldback mode. If a given application can drive the output voltage to  $\leq V_x$ , during an overload, then a second criterion must be checked. The next equation gives the maximum input voltage, when in this mode, before damage occurs:

$$V_{in} \leq \frac{V_{sc} + 0.4}{T_{on} \cdot F_{sw}} \cdot 0.36 \quad (5)$$

Where  $V_{sc}$  is the value of output voltage during the overload and  $F_{sw}$  is the normal switching frequency. **If the input voltage should exceed this value, while in foldback mode, the regulator and/or the diode may be damaged.** It is important to note that the voltages in these equations are measured at the inductor. Normal trace and wiring resistance will cause the voltage at the inductor to be higher than that at a remote load. Therefore, even if the load is shorted with zero volts across its terminals, the inductor will still see a finite voltage. It is this value that should be used for  $V_x$  and  $V_{sc}$  in the calculations. In order to return from foldback mode, the load must be reduced to a value much lower than that required to initiate foldback. This load "hysteresis" is a normal aspect of any type of current limit foldback associated with voltage regulators.

The safe operating area, when in short circuit mode, is shown in Figure 12. Operating points below and to the right of the curve represent safe operation.

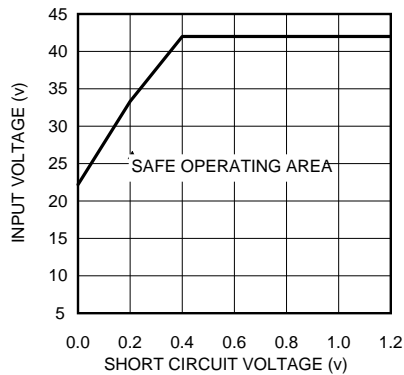
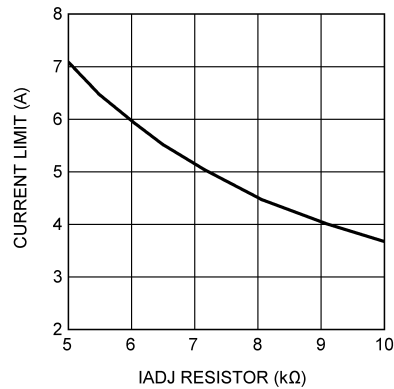


Figure 12. SOA

## Current Limit Adjustment

A key feature of the LM22679 is the ability to adjust the peak switch current limit. This can be useful when the full current capability of the regulator is not required for a given application. A smaller current limit may allow the use of power components with lower current ratings, thus saving space and reducing cost. A single resistor between the IADJ pin and ground controls the current limit in accordance with Figure 13. The current limit mode is set during start-up of the regulator. When  $V_{IN}$  is applied, a weak pull-up is connected to the IADJ pin and, after approximately 100  $\mu$ s, the voltage on the pin is checked against a threshold of about 0.8V. With the IADJ pin open, the voltage floats above this threshold, and the current limit is set to the default value of 7.1A (typ). With a resistor present, an internal reference holds the pin voltage at 0.8V; the resulting current sets the current limit. The accuracy of the adjusted current limit will be slightly worse than that of the default value; +35%/ -25% is to be expected. Resistor values should not exceed the limits shown in Figure 13.



**Figure 13. Current Limit vs IADJ Resistor**

### Soft-Start

The soft-start feature allows the regulator to gradually reach steady-state operation, thus reducing start-up stresses. The internal soft-start feature brings the output voltage up in about 500  $\mu$ s. This time can be extended by using an external capacitor connected to the SS pin. Values in the range of 100 nF to 1  $\mu$ F are recommended. The approximate soft-start time can be estimated from the following equation:

$$T_{SS} \approx 26 \times 10^3 \cdot C_{SS} \quad (6)$$

Soft-start is reset any time the part is shut down or a thermal overload event occurs.

### Boot-Strap Supply

The LM22679 incorporates a floating high-side gate driver to control the power MOSFET. The supply for this driver is the external boot-strap capacitor connected between the BOOT pin and SW. A good quality 10 nF ceramic capacitor must be connected to these pins with short, wide PCB traces. One reason the regulator imposes a minimum off-time is to ensure that this capacitor recharges every switching cycle. A minimum load of about 5 mA is required to fully recharge the boot-strap capacitor in the minimum off-time. Some of this load can be provided by the output voltage divider, if used.

### Thermal Protection

Internal thermal shutdown circuitry protects the LM22679 should the maximum junction temperature be exceeded. This protection is activated at about 150°C, with the result that the regulator will shutdown until the temperature drops below about 135°C.

### Internal Compensation

The LM22679 has internal loop compensation designed to provide a stable regulator over a wide range of external power stage components. The internal compensation of the -ADJ option is optimized for output voltages below 5V. If an output voltage of 5V or greater is needed, the -5.0 option with an external resistor divider can be used.

Ensuring stability of a design with a specific power stage (inductor and output capacitor) can be tricky. The LM22679 stability can be verified using the WEBENCH® Designer online circuit simulation tool at [www.ti.com](http://www.ti.com). A quick start spreadsheet can also be downloaded from the online product folder.

The complete transfer function for the regulator loop is found by combining the compensation and power stage transfer functions. The LM22679 has internal type III loop compensation, as detailed in Internal Loop Compensation section. This is the approximate "straight line" function from the FB pin to the input of the PWM modulator. The power stage transfer function consists of a D.C. gain and a second order pole created by the inductor and output capacitor(s). Due to the input voltage feedforward employed in the LM22679, the power stage D.C. gain is fixed at 20dB. The second order pole is characterized by its resonant frequency and its quality factor (Q). For a first pass design, the product of inductance and output capacitance should conform to the following equation:

$$L \cdot C_{out} \approx 1.1 \times 10^{-9} \tag{7}$$

Alternatively, this pole should be placed between 1.5kHz and 15kHz and is given by the equation shown below:

$$F_o = \frac{1}{2\pi \sqrt{L \cdot C_{out}}} \tag{8}$$

The Q factor depends on the parasitic resistance of the power stage components and is not typically in the control of the designer. Of course, loop compensation is only one consideration when selecting power stage components; see [Application Information](#) for more details.

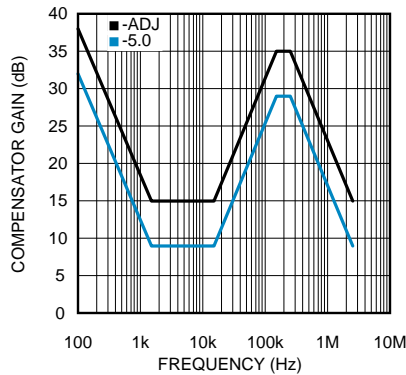


Figure 14. Compensator Gain

In general, hand calculations or simulations can only aid in selecting good power stage components. Good design practice dictates that load and line transient testing should be done to verify the stability of the application. Also, Bode plot measurements should be made to determine stability margins. Application note AN-1889 shows how to perform a loop transfer function measurement with only an oscilloscope and function generator.

## APPLICATION INFORMATION

### TYPICAL BUCK REGULATOR APPLICATION

Figure 15 shows an example of converting an input voltage range of 5.5V to 42V, to an output of 3.3V at 5A. See AN-1891 for more information.

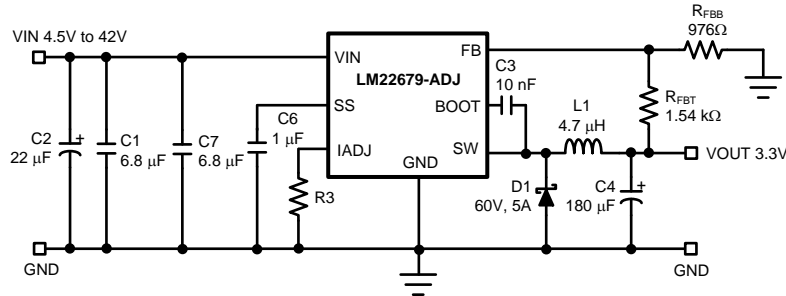


Figure 15. Typical Buck Regulator Application

### EXTERNAL COMPONENTS

The following guidelines should be used when designing a step-down (buck) converter with the LM22679.

#### INDUCTOR

The inductor value is determined based on the load current, ripple current, and the minimum and maximum input voltages. To keep the application in continuous conduction mode (CCM), the maximum ripple current,  $I_{RIPPLE}$ , should be less than twice the minimum load current.

The general rule of keeping the inductor current peak-to-peak ripple around 30% of the nominal output current is a good compromise between excessive output voltage ripple and excessive component size and cost. Using this value of ripple current, the value of inductor,  $L$ , is calculated using the following formula:

$$L = \frac{(V_{in} - V_{out}) \cdot V_{out}}{0.3 \cdot I_{out} \cdot F_{sw} \cdot V_{in}} \quad (9)$$

where  $F_{sw}$  is the switching frequency and  $V_{in}$  should be taken at its maximum value, for the given application. The above formula provides a guide to select the value of the inductor  $L$ ; the nearest standard value will then be used in the circuit.

Once the inductor is selected, the actual ripple current can be found from the equation shown below:

$$\Delta I = \frac{(V_{in} - V_{out}) \cdot V_{out}}{L \cdot F_{sw} \cdot V_{in}} \quad (10)$$

Increasing the inductance will generally slow down the transient response but reduce the output voltage ripple. Reducing the inductance will generally improve the transient response but increase the output voltage ripple.

The inductor must be rated for the peak current,  $I_{PK}$ , in a given application, to prevent saturation. During normal loading conditions, the peak current is equal to the load current plus 1/2 of the inductor ripple current.

During an overload condition, as well as during certain load transients, the controller may trip current limit. In this case the peak inductor current is given by  $I_{CL}$ , found in the [Electrical Characteristics](#) table. Good design practice requires that the inductor rating be adequate for this overload condition. **If the inductor is not rated for the maximum expected current, it can saturate resulting in damage to the LM22679 and/or the power diode.** This consideration highlights the value of the current limit adjust feature of the LM22679.

## INPUT CAPACITOR

The input capacitor selection is based on both input voltage ripple and RMS current. Good quality input capacitors are necessary to limit the ripple voltage at the VIN pin while supplying most of the regulator current during switch on-time. Low ESR ceramic capacitors are preferred. Larger values of input capacitance are desirable to reduce voltage ripple and noise on the input supply. This noise may find its way into other circuitry, sharing the same input supply, unless adequate bypassing is provided. A very approximate formula for determining the input voltage ripple is shown below:

$$V_{ri} \approx \frac{I_{out}}{4 \cdot F_{sw} \cdot C_{in}} \quad (11)$$

Where  $V_{ri}$  is the peak-to-peak ripple voltage at the switching frequency. Another concern is the RMS current passing through this capacitor. The following equation gives an approximation to this current:

$$I_{rms} \approx \frac{I_{out}}{2} \quad (12)$$

The capacitor must be rated for at least this level of RMS current at the switching frequency.

All ceramic capacitors have large voltage coefficients, in addition to normal tolerances and temperature coefficients. To help mitigate these effects, multiple capacitors can be used in parallel to bring the minimum capacitance up to the desired value. This may also help with RMS current constraints by sharing the current among several capacitors. Many times it is desirable to use an electrolytic capacitor on the input, in parallel with the ceramics. The moderate ESR of this capacitor can help to damp any ringing on the input supply caused by long power leads. This method can also help to reduce voltage spikes that may exceed the maximum input voltage rating of the LM22679.

It is good practice to include a high frequency bypass capacitor as close as possible to the LM22679. This small case size, low ESR, ceramic capacitor should be connected directly to the VIN and GND pins with the shortest possible PCB traces. Values in the range of 0.47  $\mu$ F to 1  $\mu$ F are appropriate. This capacitor helps to provide a low impedance supply to sensitive internal circuitry. It also helps to suppress any fast noise spikes on the input supply that may lead to increased EMI.

## OUTPUT CAPACITOR

The output capacitor is responsible for filtering the output voltage and supplying load current during transients. Capacitor selection depends on application conditions as well as ripple and transient requirements. Best performance is achieved with a parallel combination of ceramic capacitors and a low ESR SP™ or POSCAP™ types. Very low ESR capacitors such as ceramics reduce the output ripple and noise spikes, while higher value electrolytics or polymers provide large bulk capacitance to supply transients. Assuming very low ESR, the following equation gives an approximation to the output voltage ripple:

$$V_{ro} \approx \frac{(V_{in} - V_{out}) \cdot V_{out}}{8 \cdot V_{in}} \cdot \frac{1}{F_{sw}^2 \cdot L \cdot C_{out}} \quad (13)$$

Typically, a total value of 100  $\mu$ F, or greater, is recommended for output capacitance.

In applications with  $V_{out}$  less than 3.3V, it is critical that low ESR output capacitors are selected. This will limit potential output voltage overshoots as the input voltage falls below the device normal operating range.

## BOOT-STRAP CAPACITOR

The bootstrap capacitor between the BOOT pin and the SW pin supplies the gate current to turn on the N-channel MOSFET. The recommended value of this capacitor is 10 nF and should be a good quality, low ESR ceramic capacitor. In some cases it may be desirable to slow down the turn-on of the internal power MOSFET, in order to reduce EMI. This can be done by placing a small resistor in series with the  $C_{boot}$  capacitor. Resistors in the range of 10 $\Omega$  to 50 $\Omega$  can be used. This technique should only be used when absolutely necessary, since it will increase switching losses and thereby reduce efficiency.

## OUTPUT VOLTAGE DIVIDER SELECTION

For output voltages between about 1.285V and 5V, the -ADJ option should be used, with an appropriate voltage divider as shown in [Figure 16](#). The following equation can be used to calculate the resistor values of this divider:

$$R_{F_{BT}} = \left[ \frac{V_{out}}{1.285} - 1 \right] \cdot R_{F_{BB}} \quad (14)$$

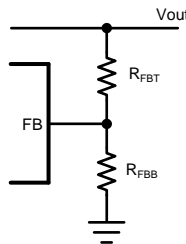
A good value for  $R_{F_{BB}}$  is 1k  $\Omega$ . This will help to provide some of the minimum load current requirement and reduce susceptibility to noise pick-up. The top of  $R_{F_{BT}}$  should be connected directly to the output capacitor or to the load for remote sensing. If the divider is connected to the load, a local high-frequency bypass should be provided at that location.

For output voltages of 5V, the -5.0 option should be used. In this case no external divider is needed and the FB pin is connected to the output. The approximate values of the internal voltage divider are as follows: 7.38k $\Omega$  from the FB pin to the input of the error amplifier and 2.55k $\Omega$  from there to ground.

Both the -ADJ and -5.0 options can be used for output voltages greater than 5V, by using the correct output divider. As mentioned in the [Internal Compensation](#) section, the -5.0 option is optimized for output voltages of 5V. However, for output voltages greater than 5V, this option may provide better loop bandwidth than the -ADJ option, in some applications. If the -5.0 option is to be used at output voltages greater than 5V, the following equation should be used to determine the resistor values in the output divider:

$$R_{F_{BT}} = \frac{R_{F_{BB}} \cdot (V_{out} - 5)}{5 + R_{F_{BB}} \cdot 5 \times 10^{-4}} \quad (15)$$

Again a value of  $R_{F_{BB}}$  of about 1k  $\Omega$  is a good first choice.



**Figure 16. Resistive Feedback Divider**

A maximum value of 10 k $\Omega$  is recommended for the sum of  $R_{F_{BB}}$  and  $R_{F_{BT}}$  to maintain good output voltage accuracy for the -ADJ option. A maximum of 2 k $\Omega$  is recommended for the -5.0 option. For the -5.0 option, the total internal divider resistance is typically 9.93 k $\Omega$ .

In all cases the output voltage divider should be placed as close as possible to the FB pin of the LM22679; since this is a high impedance input and is susceptible to noise pick-up.

## POWER DIODE

A Schottky type power diode is required for all LM22679 applications. Ultra-fast diodes are not recommended and may result in damage to the IC due to reverse recovery current transients. The near ideal reverse recovery characteristics and low forward voltage drop of Schottky diodes are particularly important for high input voltage and low output voltage applications common to the LM22679. The reverse breakdown rating of the diode should be selected for the maximum  $V_{IN}$ , plus some safety margin. A good rule of thumb is to select a diode with a reverse voltage rating of 1.3 times the maximum input voltage.

Select a diode with an average current rating at least equal to the maximum load current that will be seen in the application.

## Circuit Board Layout

Board layout is critical for the proper operation of switching power supplies. First, the ground plane area must be sufficient for thermal dissipation purposes. Second, appropriate guidelines must be followed to reduce the effects of switching noise. Switch mode converters are very fast switching devices. In such cases, the rapid increase of input current combined with the parasitic trace inductance generates unwanted  $L \, di/dt$  noise spikes. The magnitude of this noise tends to increase as the output current increases. This noise may turn into electromagnetic interference (EMI) and can also cause problems in device performance. Therefore, care must be taken in layout to minimize the effect of this switching noise.

The most important layout rule is to keep the AC current loops as small as possible. Figure 17 shows the current flow in a buck converter. The top schematic shows a dotted line which represents the current flow during the FET switch on-state. The middle schematic shows the current flow during the FET switch off-state.

The bottom schematic shows the currents referred to as AC currents. These AC currents are the most critical since they are changing in a very short time period. The dotted lines of the bottom schematic are the traces to keep as short and wide as possible. This will also yield a small loop area reducing the loop inductance. To avoid functional problems due to layout, review the PCB layout example. Best results are achieved if the placement of the LM22679, the bypass capacitor, the Schottky diode,  $R_{FBB}$ ,  $R_{FBT}$ , and the inductor are placed as shown in the example. Note that, in the layout shown,  $R1 = R_{FBB}$  and  $R2 = R_{FBT}$ . It is also recommended to use 2oz copper boards or heavier to help thermal dissipation and to reduce the parasitic inductances of board traces. See application note AN-1229 for more information.

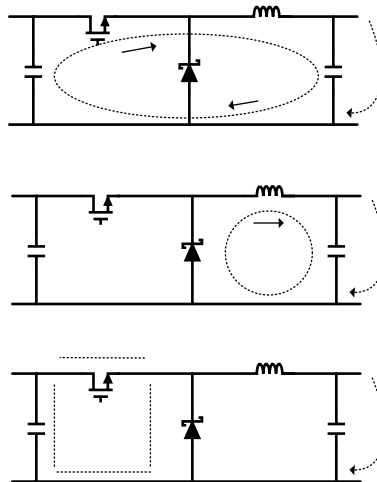


Figure 17. Current Flow in a Buck Application

## Thermal Considerations

The components with the highest power dissipation are the power diode and the power MOSFET internal to the LM22679 regulator. The easiest method to determine the power dissipation within the LM22679 is to measure the total conversion losses then subtract the power losses in the diode and inductor. The total conversion loss is the difference between the input power and the output power. An approximation for the power diode loss is:

$$P_D = I_{out} \cdot V_D \cdot \left[ 1 - \frac{V_{out}}{V_{in}} \right] \quad (16)$$

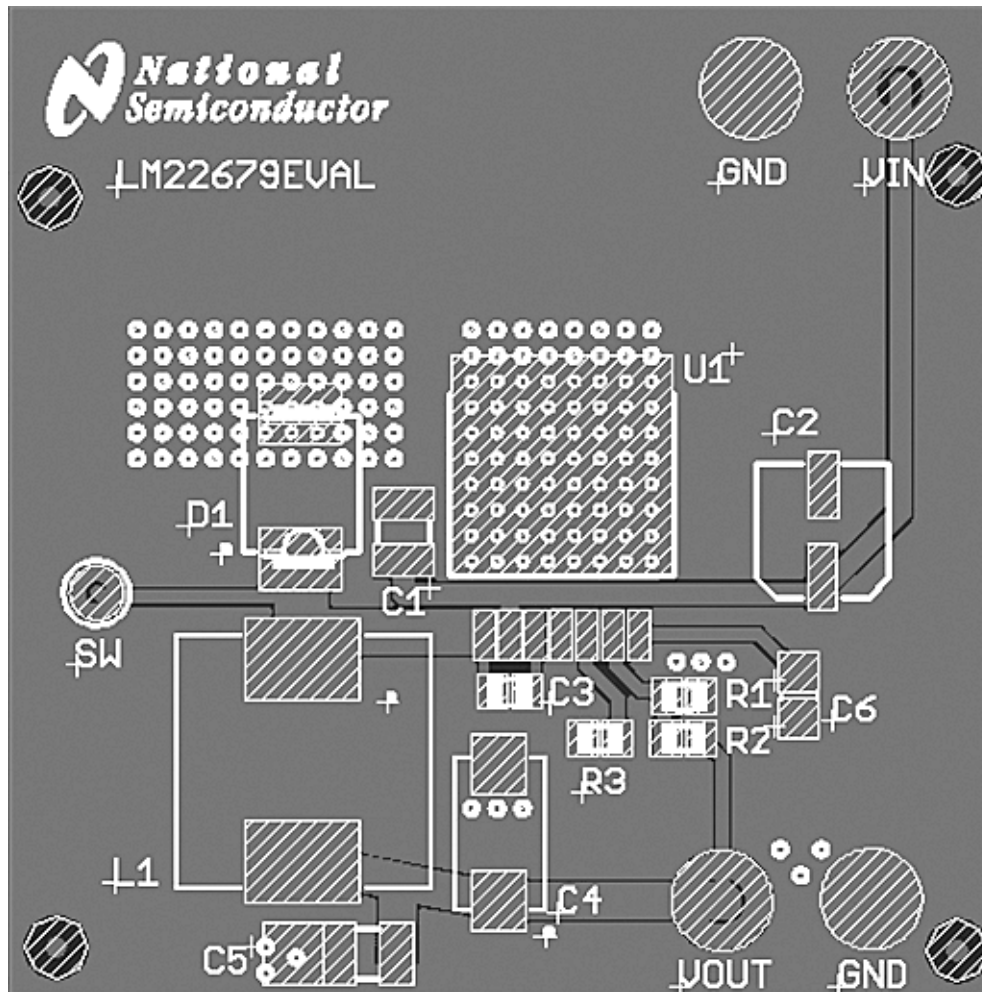
Where  $V_D$  is the diode voltage drop. An approximation for the inductor power is:

$$P_L = I_{out}^2 \cdot R_L \cdot 1.1 \quad (17)$$

where  $R_L$  is the DC resistance of the inductor and the 1.1 factor is an approximation for the AC losses.

The regulator has an exposed thermal pad to aid power dissipation. Adding multiple vias under the device to the ground plane will greatly reduce the regulator junction temperature. Selecting a diode with an exposed pad will also aid the power dissipation of the diode. The most significant variables that affect the power dissipation of the regulator are output current, input voltage and operating frequency. The power dissipated while operating near the maximum output current and maximum input voltage can be appreciable. The junction-to-ambient thermal resistance of the LM22679 will vary with the application. The most significant variables are the area of copper in the PC board, the number of vias under the IC exposed pad and the amount of forced air cooling provided. A large continuous ground plane on the top or bottom PCB layer will provide the most effective heat dissipation. The integrity of the solder connection from the IC exposed pad to the PC board is critical. Excessive voids will greatly diminish the thermal dissipation capacity. The junction-to-ambient thermal resistance of the LM22679 PFM package is specified in the [Electrical Characteristics](#) table. See application note AN-2020 for more information.

### PCB Layout Example





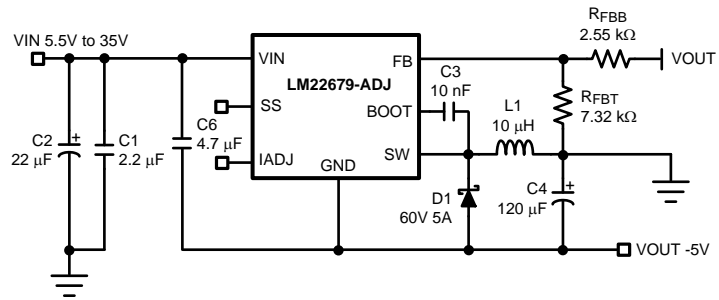


Figure 18. Inverting Regulator Application

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LM22679QTJ-5.0/NOPB	ACTIVE	TO-263	NDR	7	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM		LM22679 QTJ-5.0	<a href="#">Samples</a>
LM22679QTJ-ADJ/NOPB	ACTIVE	TO-263	NDR	7	1000	TBD	Call TI	Call TI		LM22679 QTJ-ADJ	<a href="#">Samples</a>
LM22679QTJE-5.0/NOPB	ACTIVE	TO-263	NDR	7	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM		LM22679 QTJ-5.0	<a href="#">Samples</a>
LM22679QTJE-ADJ/NOPB	ACTIVE	TO-263	NDR	7	250	TBD	Call TI	Call TI		LM22679 QTJ-ADJ	<a href="#">Samples</a>
LM22679TJ-5.0/NOPB	ACTIVE	TO-263	NDR	7	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM22679 TJ-5.0	<a href="#">Samples</a>
LM22679TJ-ADJ/NOPB	ACTIVE	TO-263	NDR	7	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM22679 TJ-ADJ	<a href="#">Samples</a>
LM22679TJE-5.0/NOPB	ACTIVE	TO-263	NDR	7	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM22679 TJ-5.0	<a href="#">Samples</a>
LM22679TJE-ADJ/NOPB	ACTIVE	TO-263	NDR	7	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM22679 TJ-ADJ	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

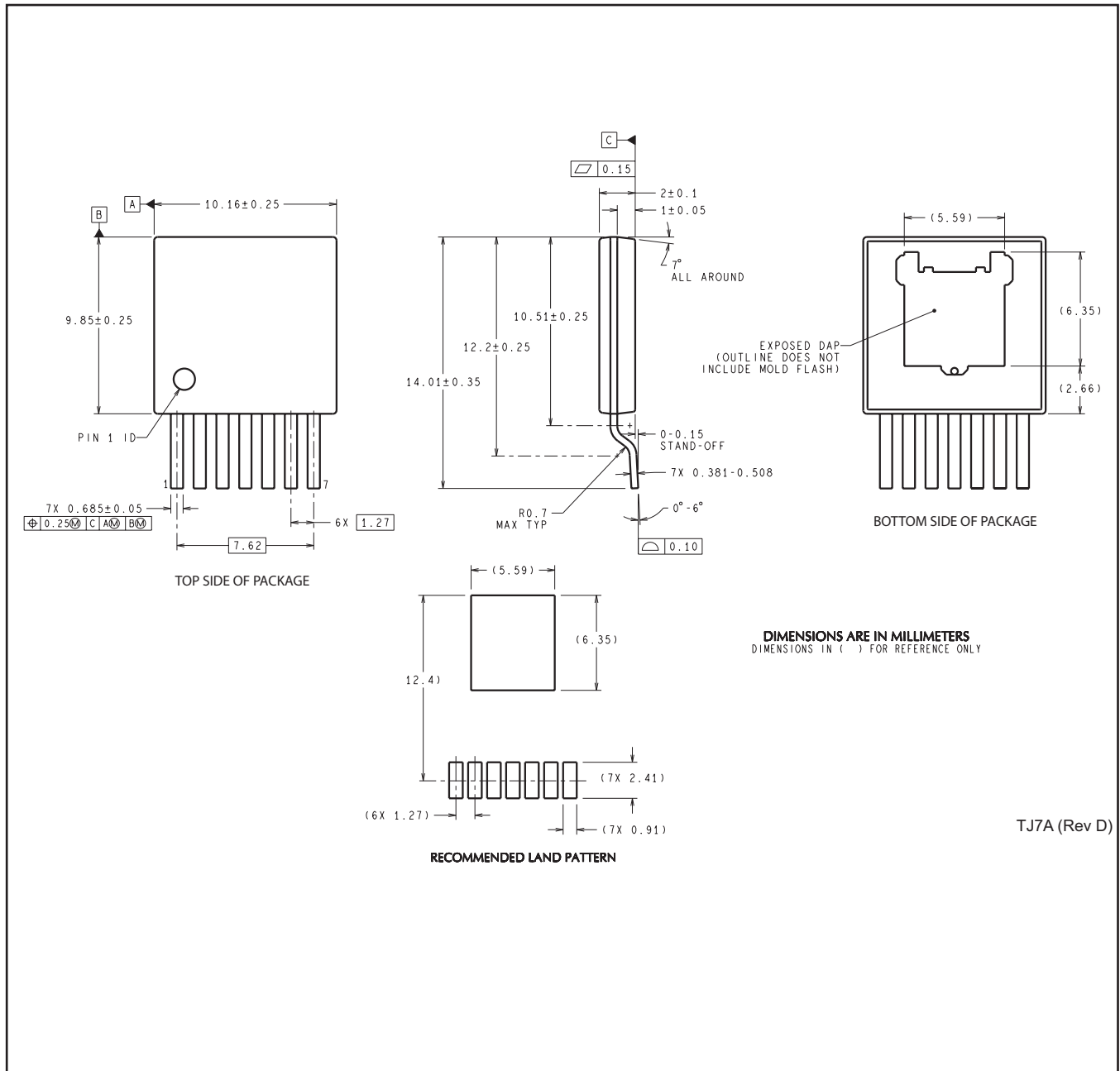
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM22679QTJ-5.0/NOPB	TO-263	NDR	7	1000	330.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2
LM22679QTJE-5.0/NOPB	TO-263	NDR	7	250	178.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2
LM22679TJ-5.0/NOPB	TO-263	NDR	7	1000	330.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2
LM22679TJ-ADJ/NOPB	TO-263	NDR	7	1000	330.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2
LM22679TJE-5.0/NOPB	TO-263	NDR	7	250	178.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2
LM22679TJE-ADJ/NOPB	TO-263	NDR	7	250	178.0	24.4	10.6	15.4	2.45	12.0	24.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM22679QTJ-5.0/NOPB	TO-263	NDR	7	1000	367.0	367.0	35.0
LM22679QTJE-5.0/NOPB	TO-263	NDR	7	250	210.0	185.0	35.0
LM22679TJ-5.0/NOPB	TO-263	NDR	7	1000	367.0	367.0	35.0
LM22679TJ-ADJ/NOPB	TO-263	NDR	7	1000	367.0	367.0	35.0
LM22679TJE-5.0/NOPB	TO-263	NDR	7	250	210.0	185.0	35.0
LM22679TJE-ADJ/NOPB	TO-263	NDR	7	250	210.0	185.0	35.0

NDR0007A



TJ7A (Rev D)

## IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

### Products

Audio	<a href="http://www.ti.com/audio">www.ti.com/audio</a>
Amplifiers	<a href="http://amplifier.ti.com">amplifier.ti.com</a>
Data Converters	<a href="http://dataconverter.ti.com">dataconverter.ti.com</a>
DLP® Products	<a href="http://www.dlp.com">www.dlp.com</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>
Clocks and Timers	<a href="http://www.ti.com/clocks">www.ti.com/clocks</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>
RFID	<a href="http://www.ti-rfid.com">www.ti-rfid.com</a>
OMAP Applications Processors	<a href="http://www.ti.com/omap">www.ti.com/omap</a>
Wireless Connectivity	<a href="http://www.ti.com/wirelessconnectivity">www.ti.com/wirelessconnectivity</a>

### Applications

Automotive and Transportation	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
Communications and Telecom	<a href="http://www.ti.com/communications">www.ti.com/communications</a>
Computers and Peripherals	<a href="http://www.ti.com/computers">www.ti.com/computers</a>
Consumer Electronics	<a href="http://www.ti.com/consumer-apps">www.ti.com/consumer-apps</a>
Energy and Lighting	<a href="http://www.ti.com/energy">www.ti.com/energy</a>
Industrial	<a href="http://www.ti.com/industrial">www.ti.com/industrial</a>
Medical	<a href="http://www.ti.com/medical">www.ti.com/medical</a>
Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
Space, Avionics and Defense	<a href="http://www.ti.com/space-avionics-defense">www.ti.com/space-avionics-defense</a>
Video and Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>

### TI E2E Community

[e2e.ti.com](http://e2e.ti.com)